

Unravelling long-term behaviour in historic geophysical data sets

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(2012-08-02)

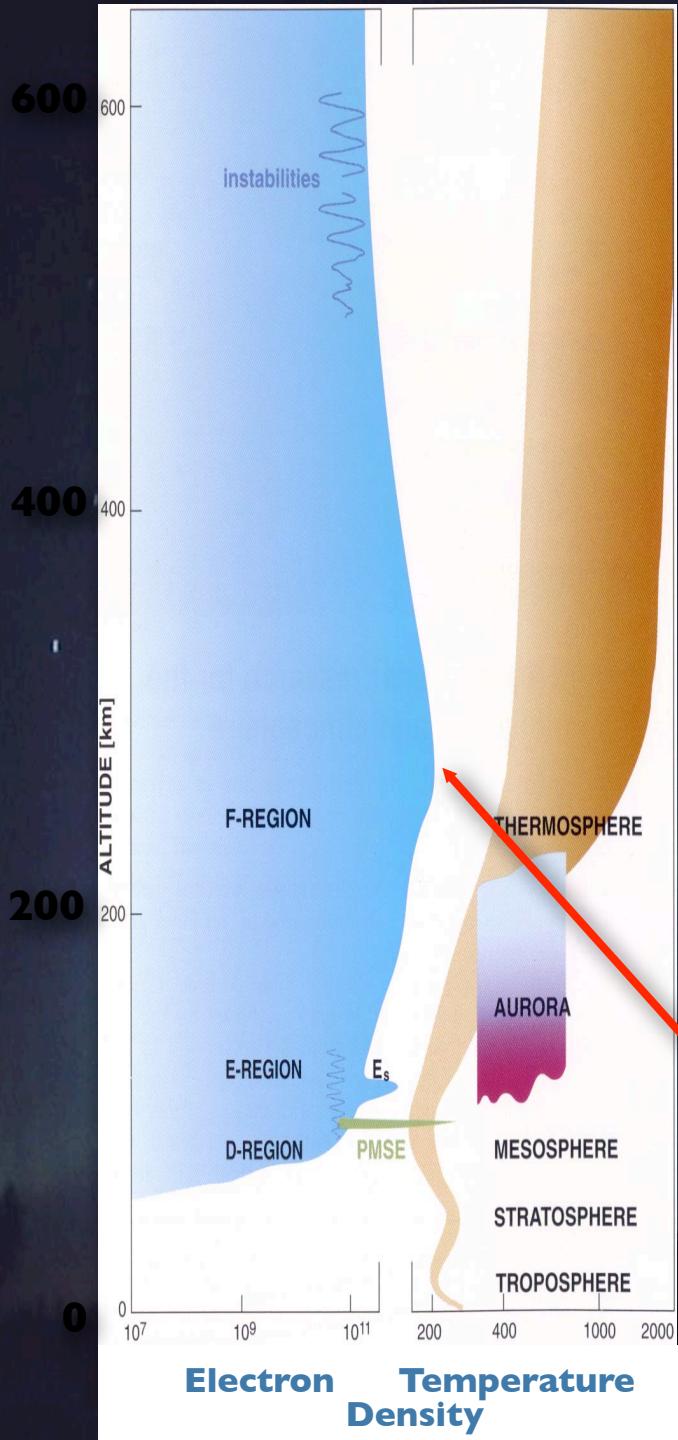
Sodankylä Geophysical Observatory

- First observations during the International Polar Year 1882/83.
- Established 1913.
- Finland independent from Russia in 1917.
- Part of University of Oulu since 1997.
- Oldest scientific research institute in Northern Finland.



Where we are...





Greenhouse Cooling

Doubling of $[CO_2]$ and $[CH_4]$

cools

Mesosphere by **10 K** and
Thermosphere by **50 K**.

Atmosphere shrinks.

Layer of maximum electron density *lowers* by 15-20 km.

Greenhouse high up?

- Model results, assuming doubling of CO₂ and CH₄:
- Stratopause cools by 8 K, stratosphere by 15 K.
(Brasseur & Hitchman, 1988)
- Mesosphere and thermosphere cool by 10 K and 50 K, respectively.
(Roble & Dickinson, 1989)
- F2-layer peak (hmF2) lowers by 15-20 km.
(Rishbeth, 1990)
- Riometer absorption decreases.
(Serafimov & Serafimova, 1992)
- Stratopause cools by 14 K, mesosphere by 8 K, thermosphere by 50 K.
(Akmaev & Fomichev, 1998)

Ionomonde

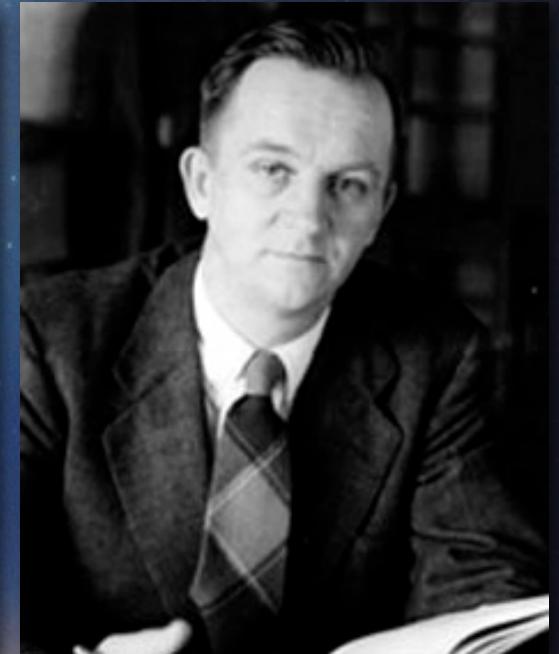
G Breit and M A Tuve,
A radio method of
estimating the height of
the conducting layer,
Nature, 116, p. 357, 1925.

Gregory Breit



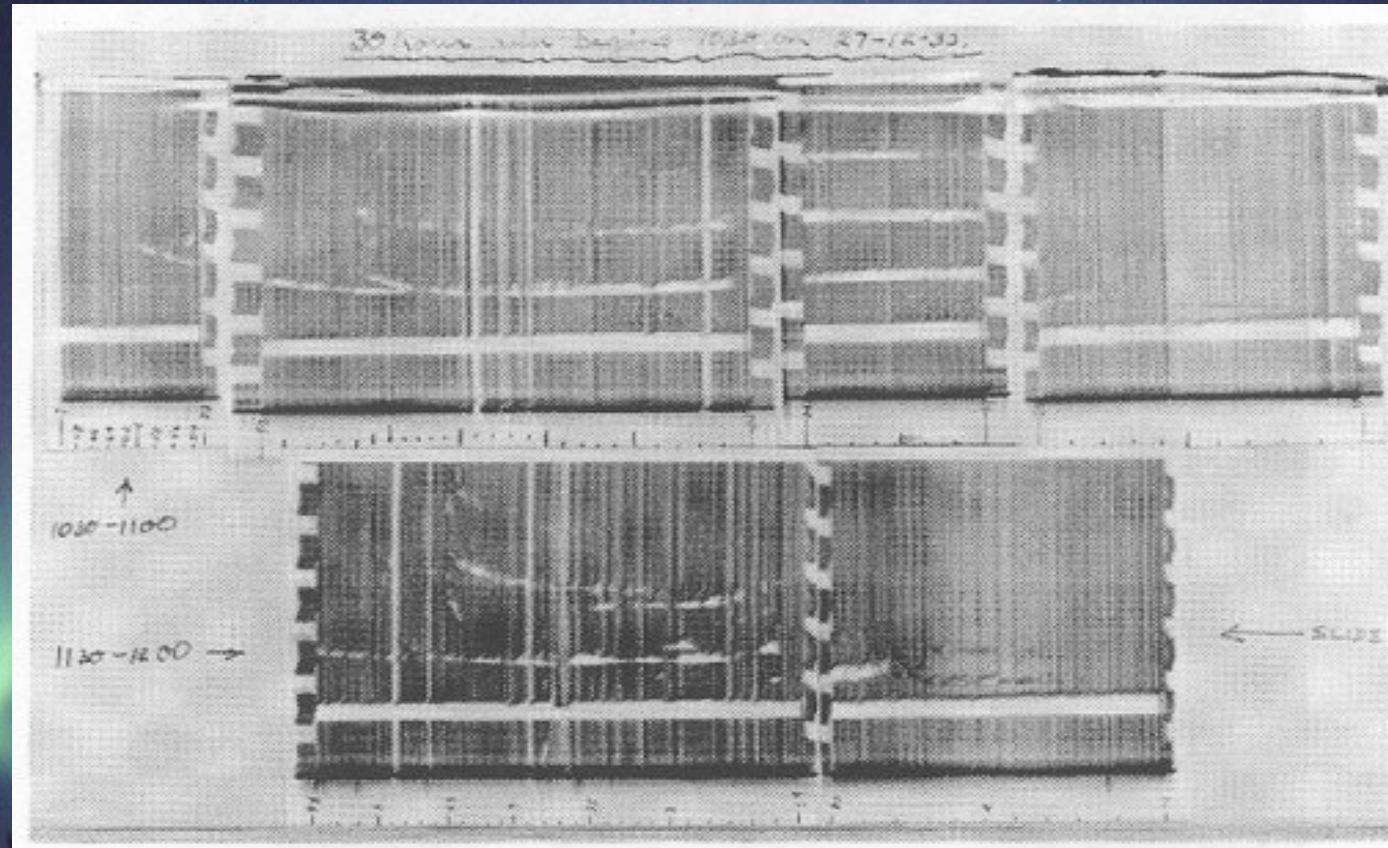
(14 July 1899 - 11 September 1981)

Merle Tuve



(27 June 1901 - 20 May 1982)

Early Slough ionogram



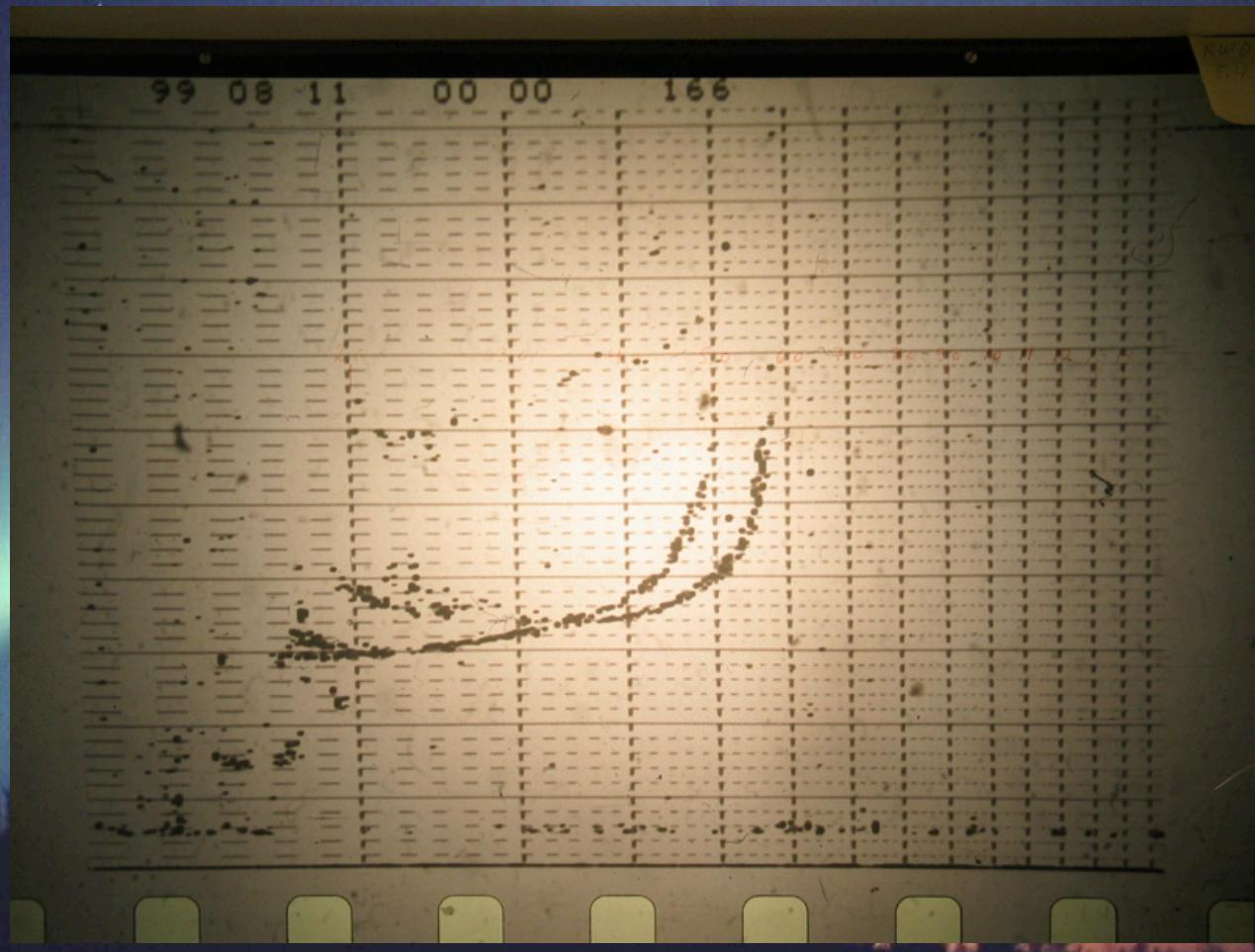
Radio Research Station Slough, Buckinghamshire
27th December 1933, 10:30-11:00 UTC and 11:30-12:00 UTC.

Sodankylä ionosonde

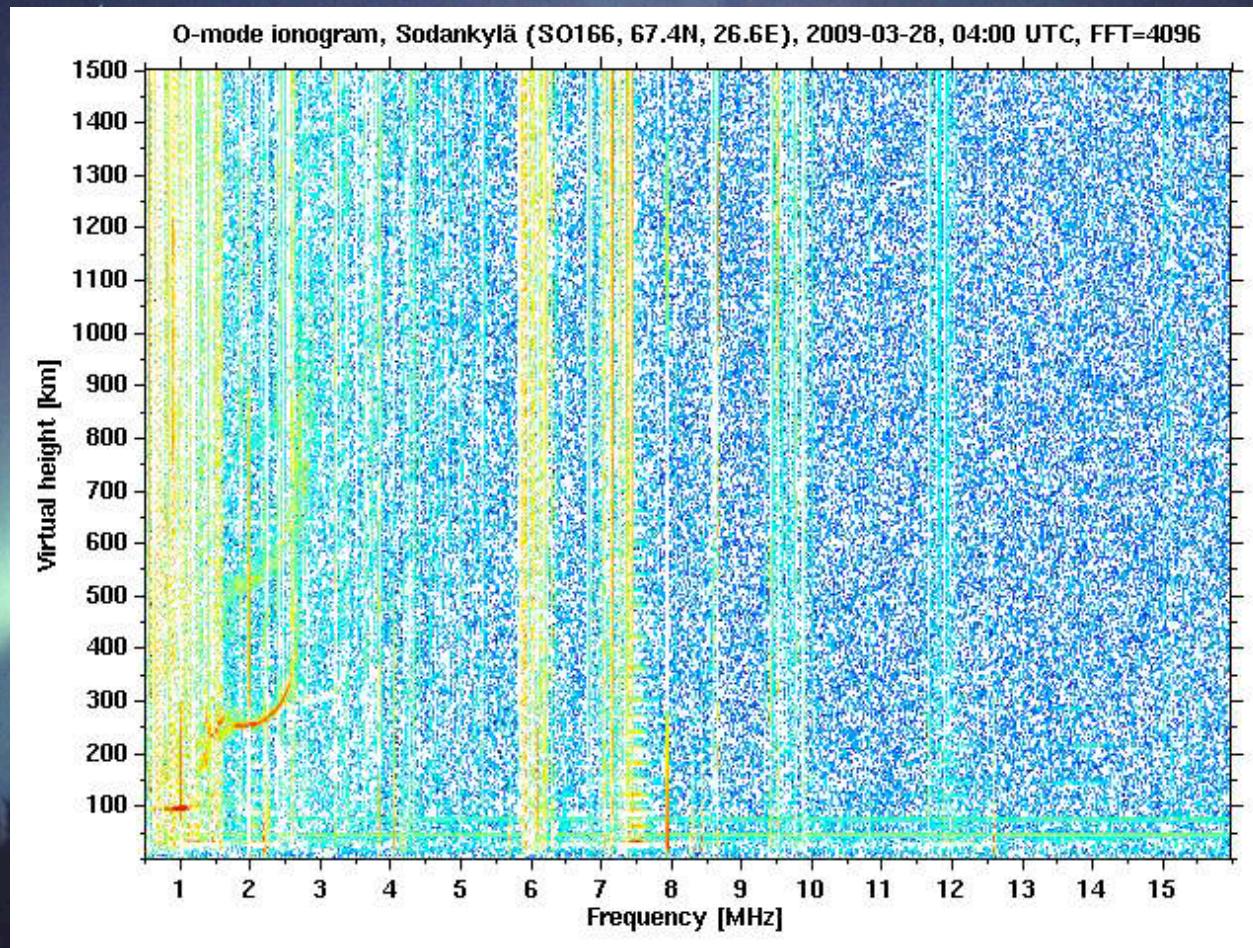
- Sodankylä ionosonde measurements began 1st August 1957.
- Until Nov 2005: 1 sounding per 30 min.
- Until Mar 2007: 1 sounding per 10 min.
- IPY (Apr '07-Mar '08): 1 sounding per minute.
- April 2008: we forgot to turn off IPY mode.
- Millionth ionogram: before May 2007.
- High data quality:
first 800.000+ ionograms were analysed by
the very same person!



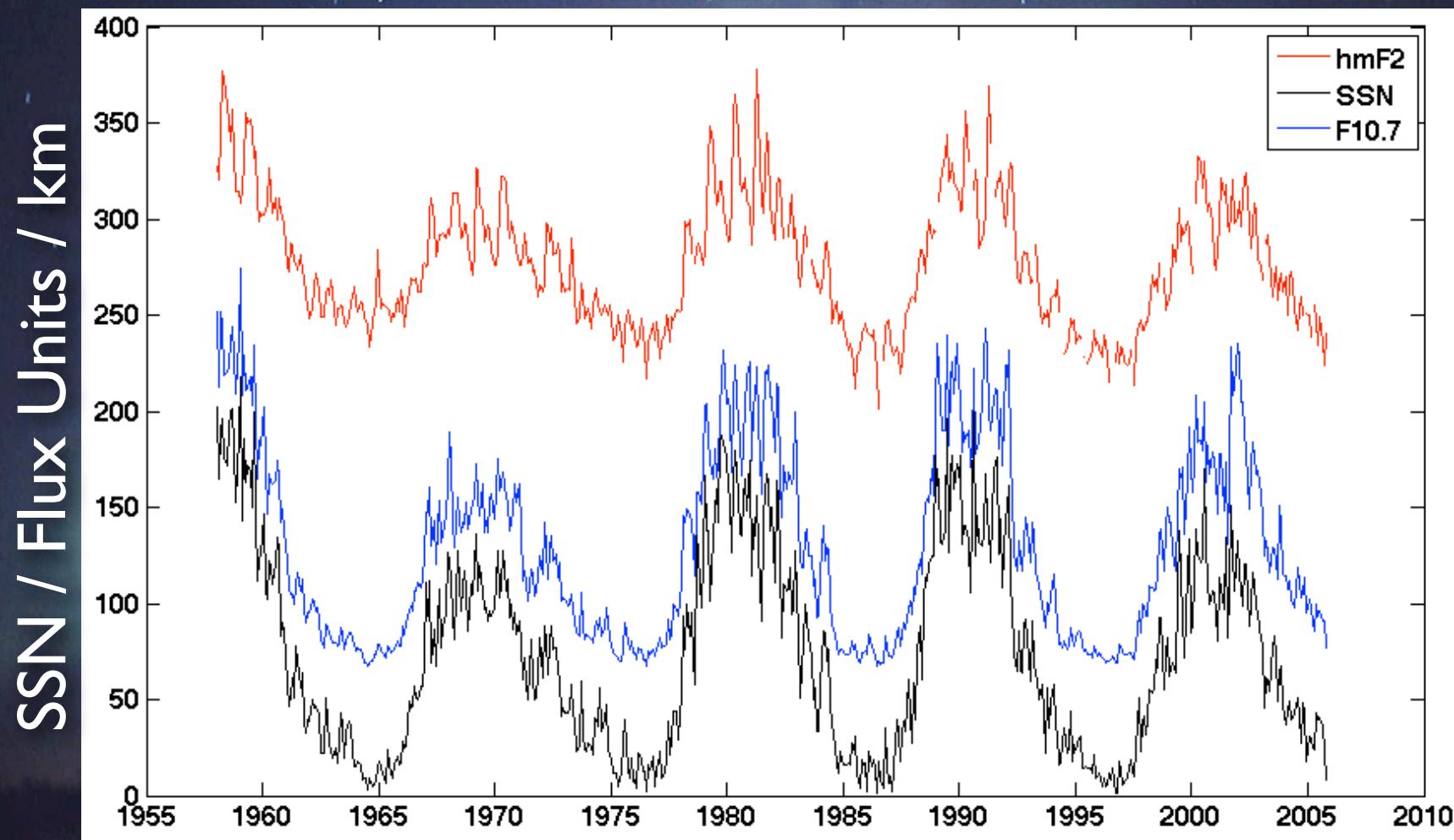
Sodankylä ionosonde



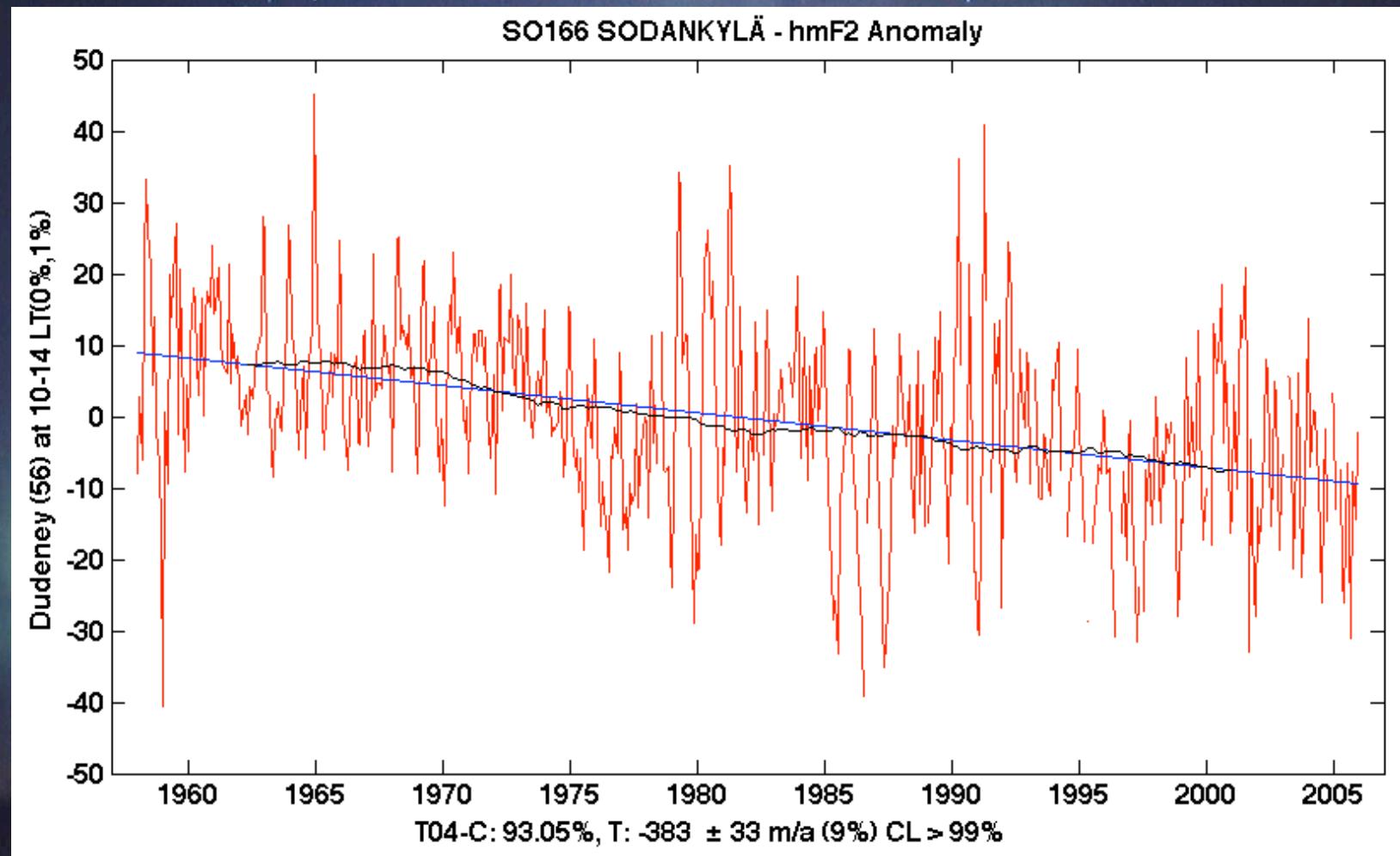
Sodankylä ionosonde



hmF2 & Solar Activity

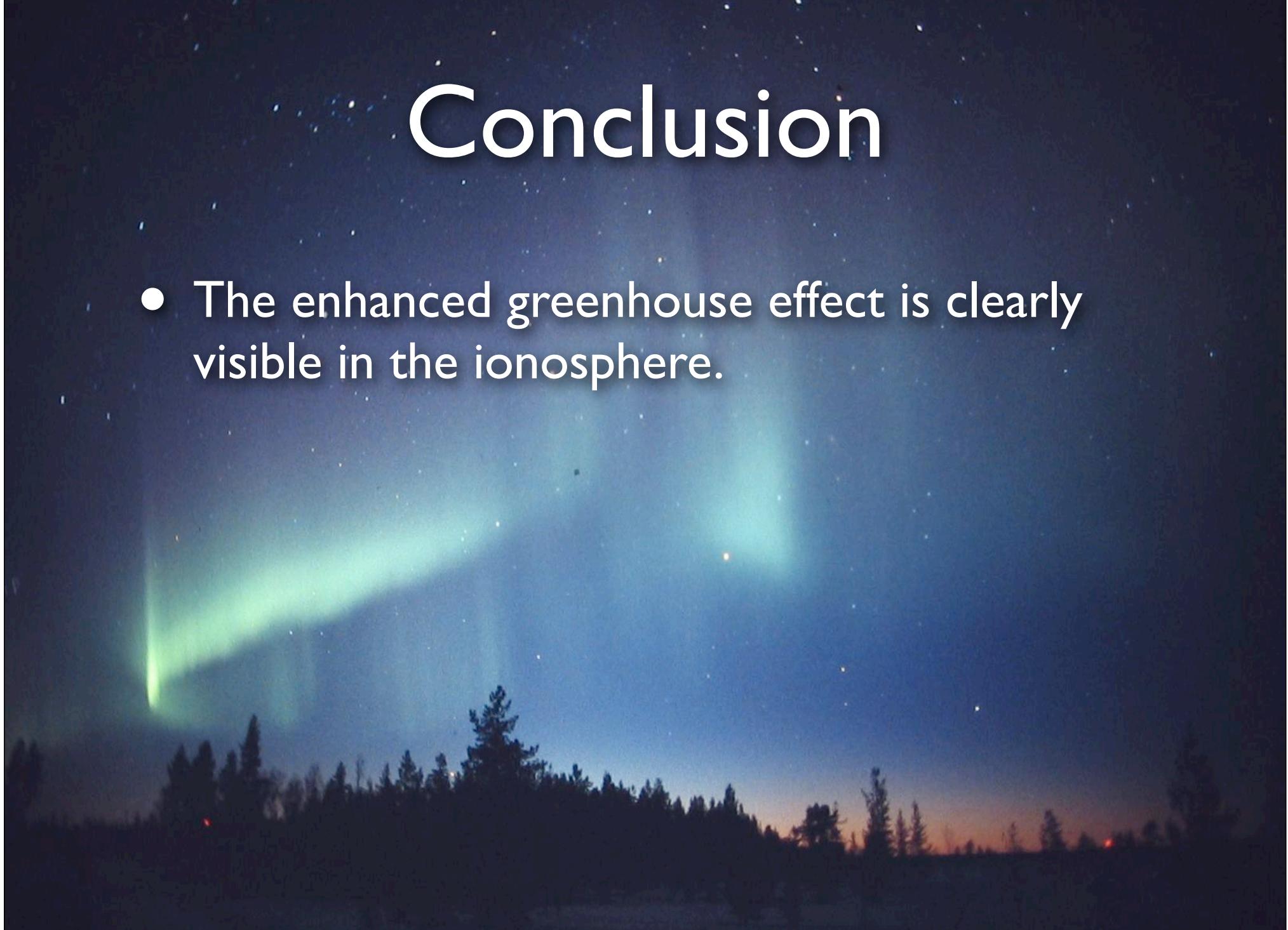


Sodankylä hmF2 Trend

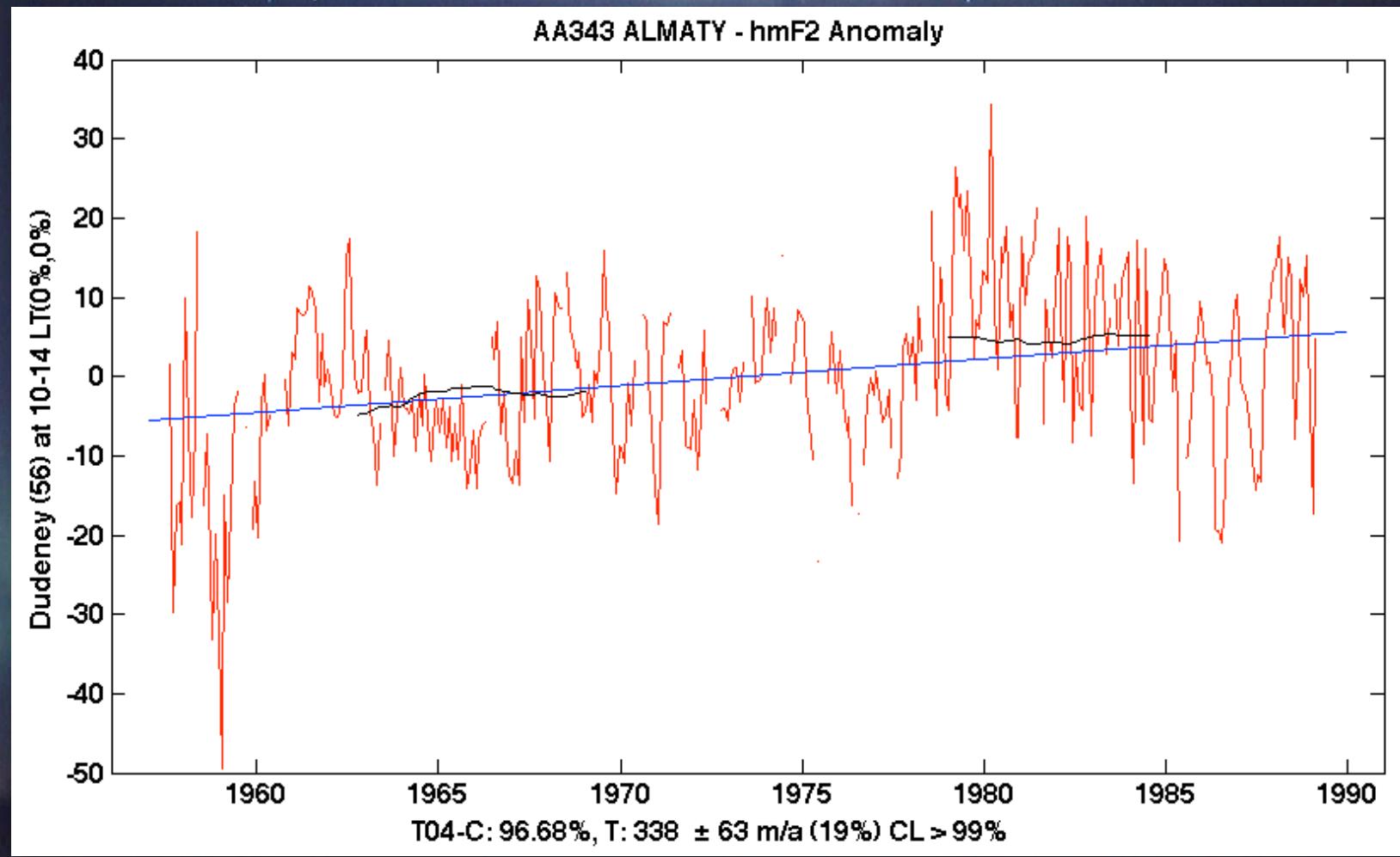


Conclusion

- The enhanced greenhouse effect is clearly visible in the ionosphere.



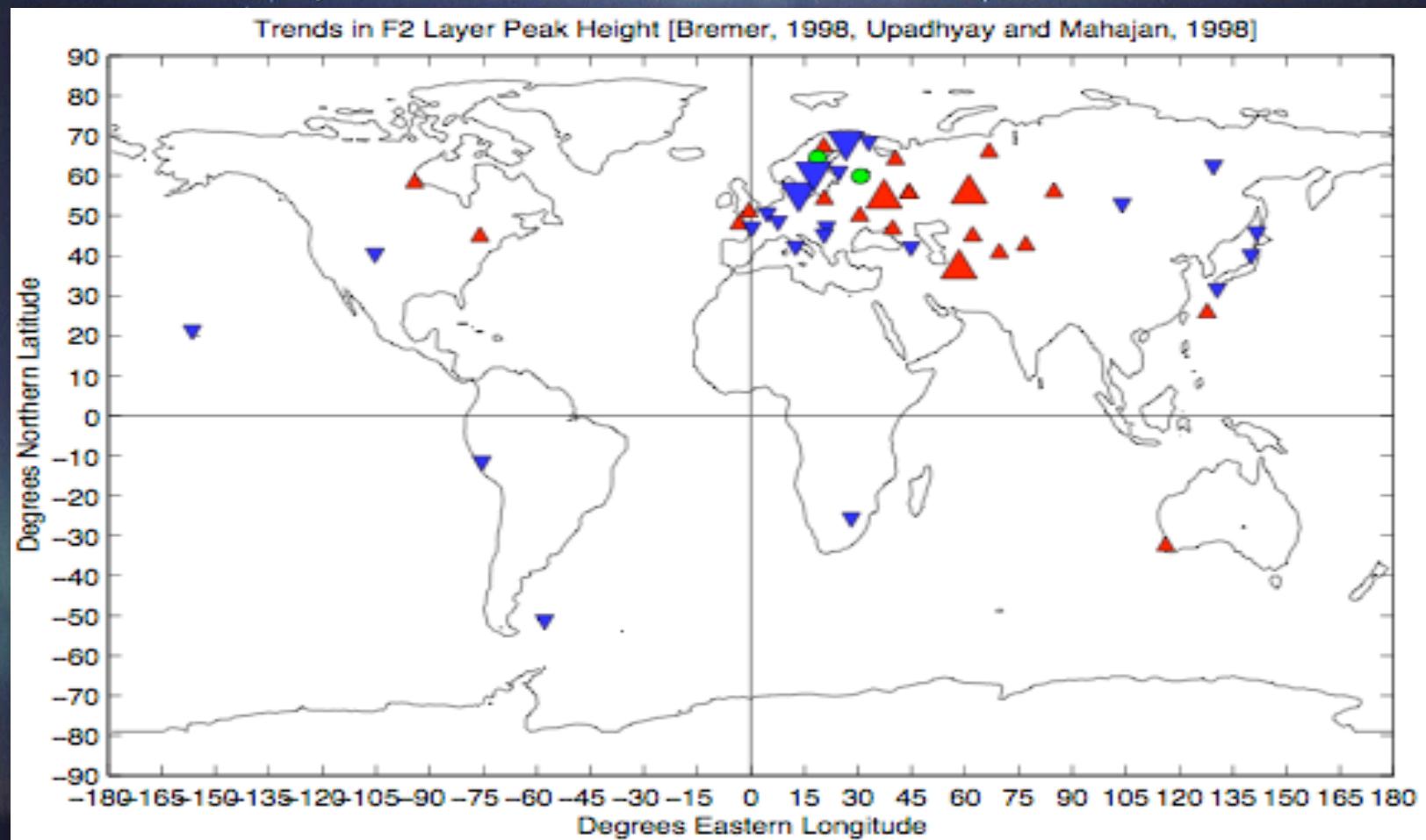
Almaty hmF2



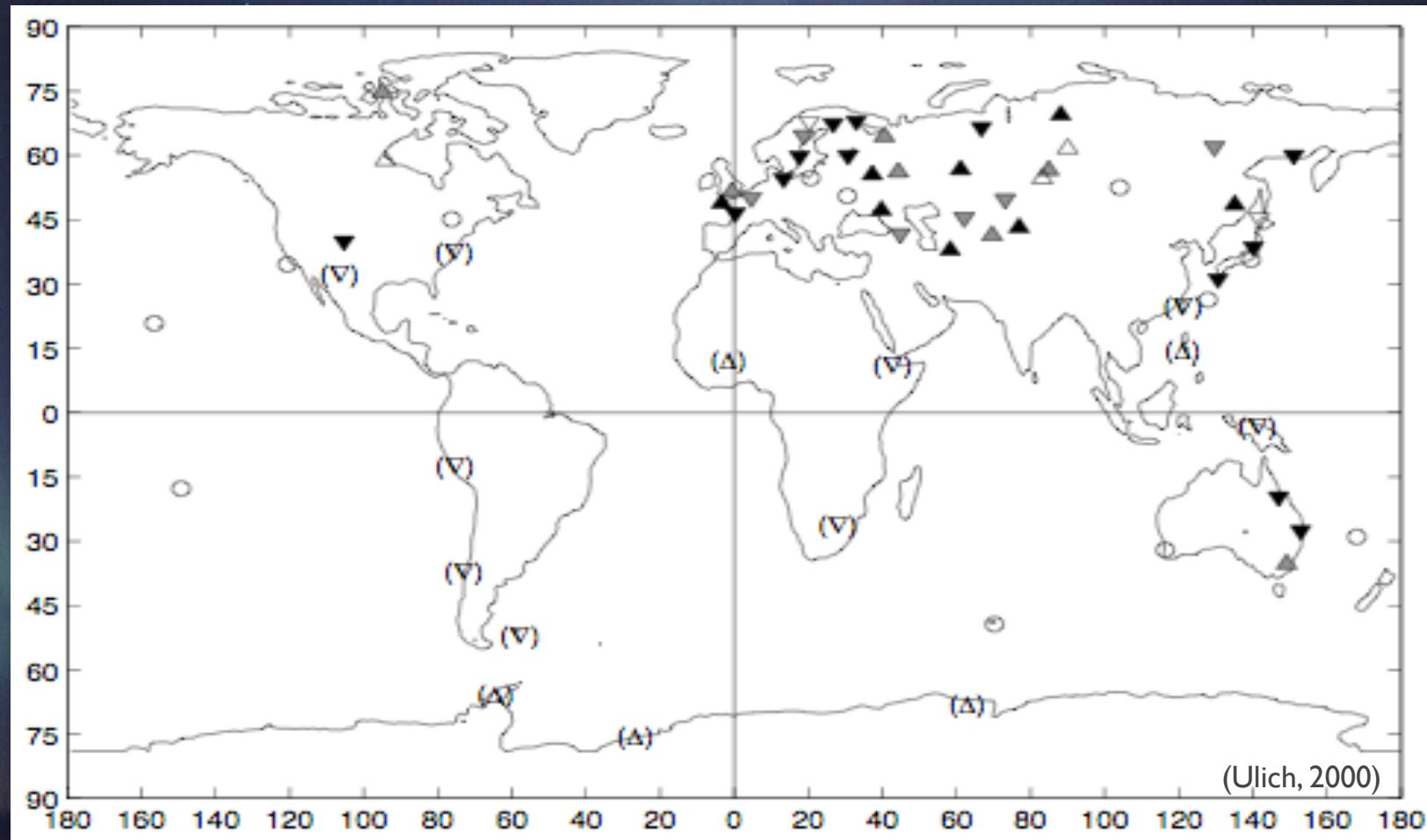
Conclusion

- Obviously, my data set is better than yours.
- The enhanced greenhouse effect is clearly visible in the ionosphere.

hmF2 Trends



Global hmF2 Trends



Conclusion

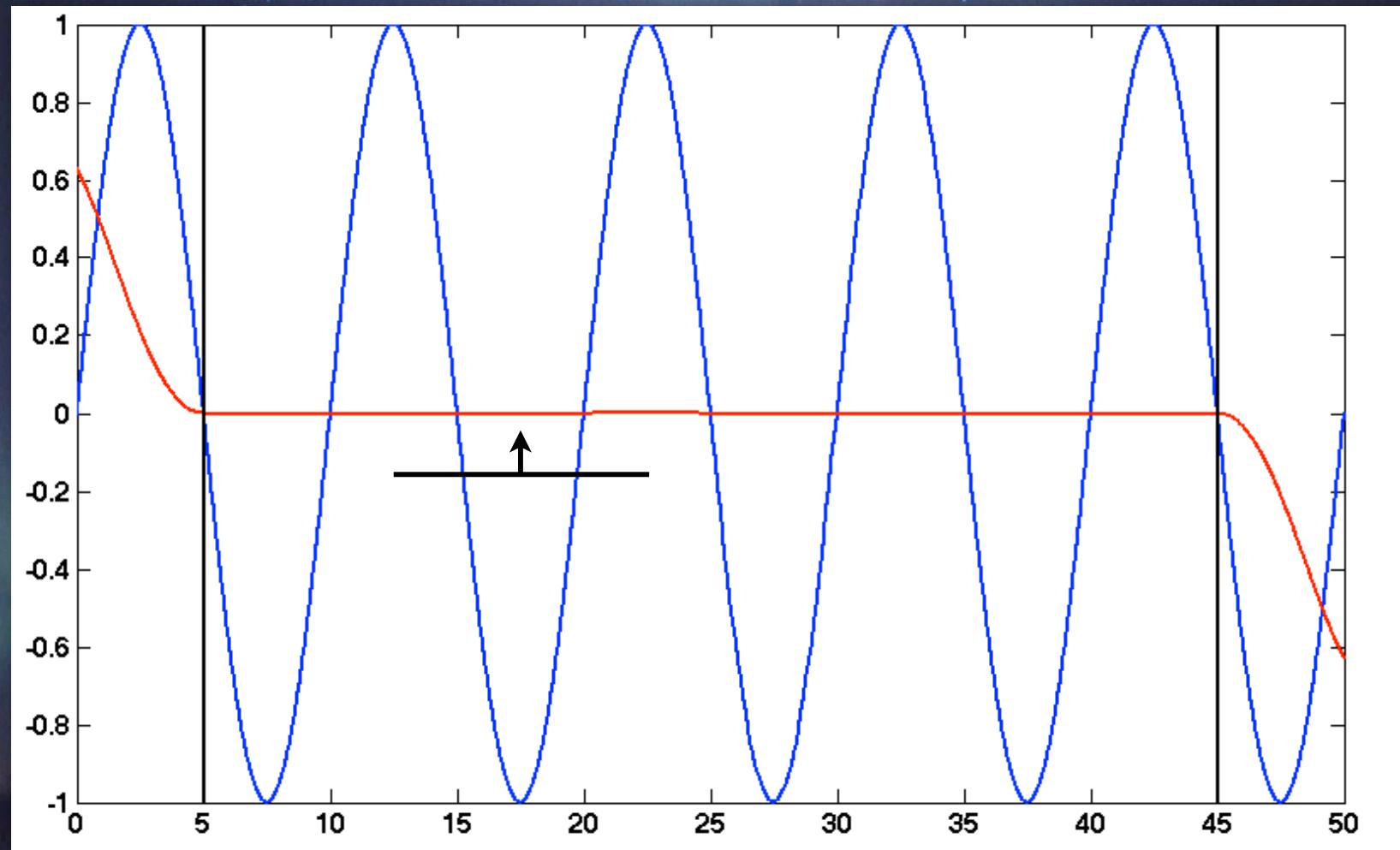
- What the ... ???



Problems

- Data resolution (h, 3-h, day, month(?), ...)
- Low-pass filtering or polynomial fitting...

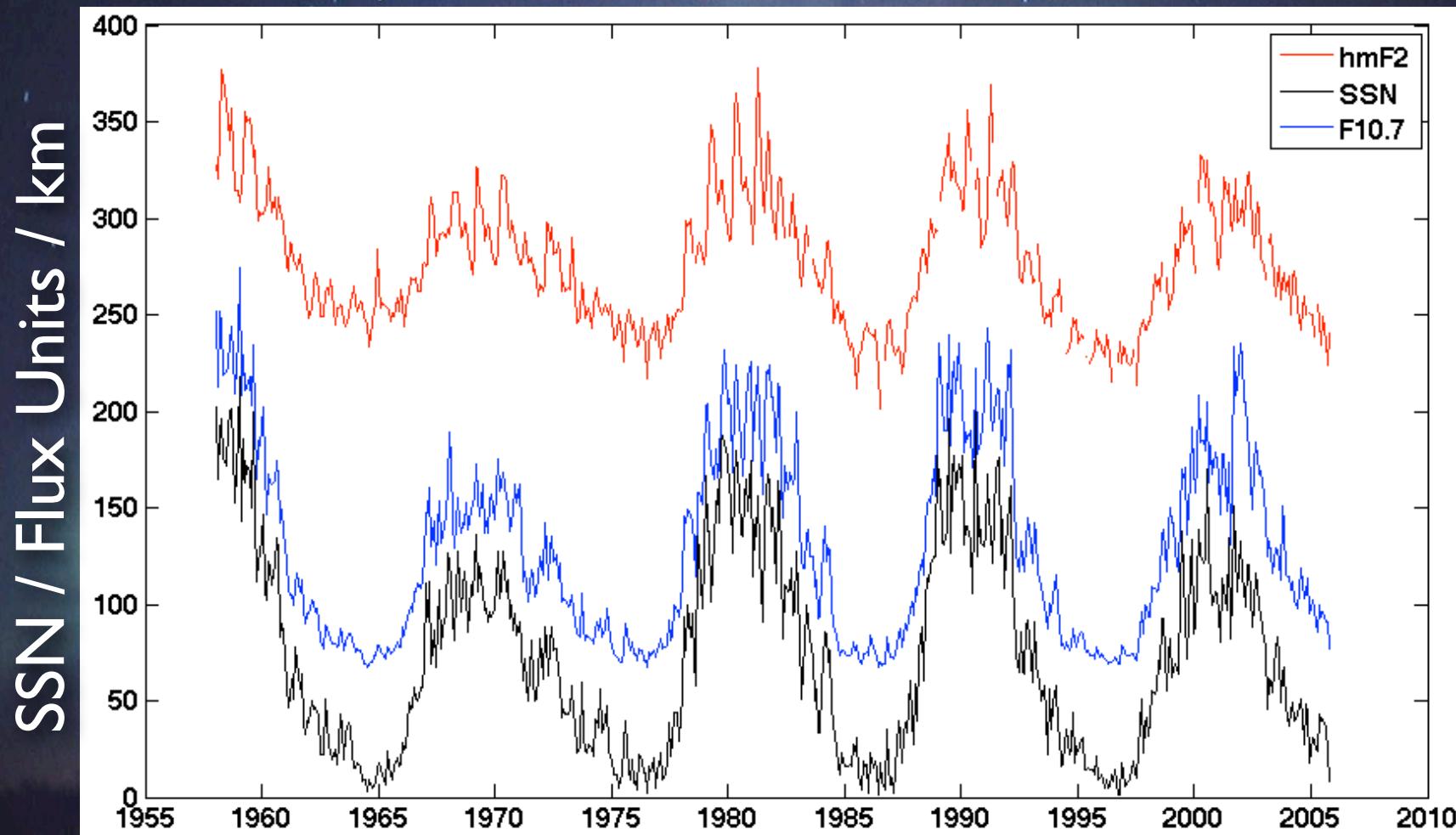
Running Mean Filter



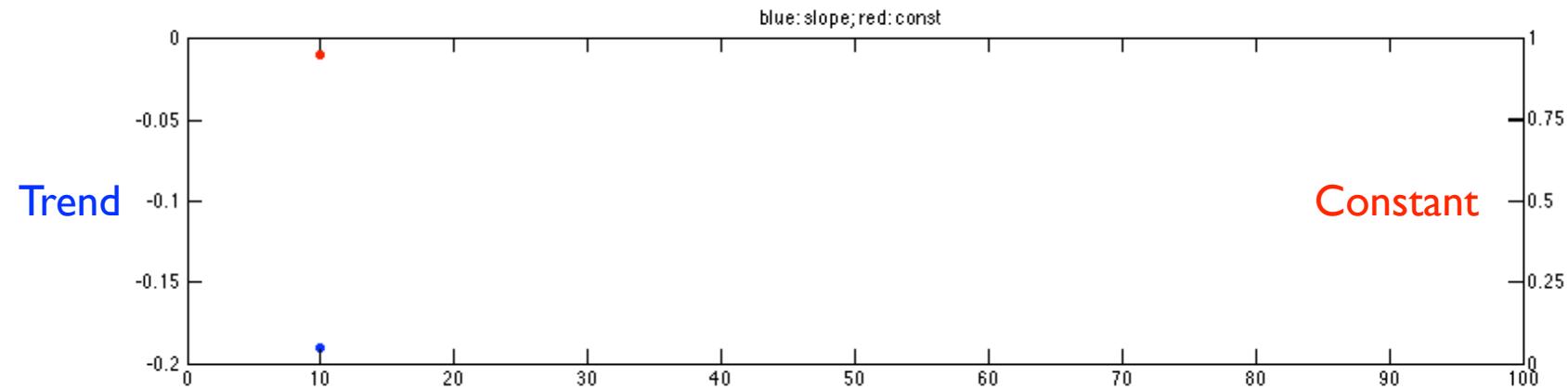
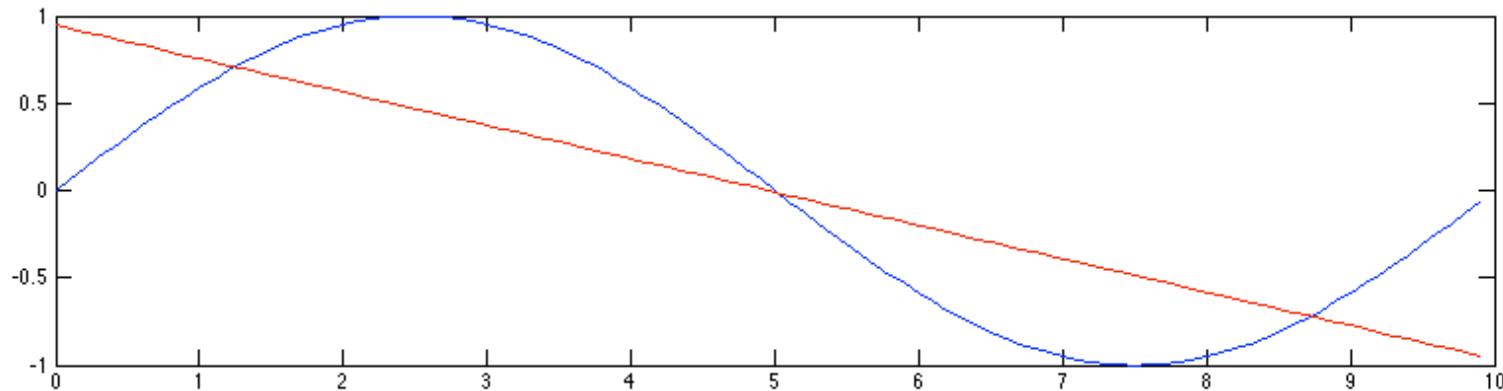
Problems

- Data resolution (h, 3-h, day, month(?), ...)
- Low-pass filtering or polynomial fitting...
- Removal of underlying (cyclic) variability:
 - Choice of proxy (sinusoid, SSN, Group SSN, F10.7 (adj./obs.), Ly- α , Mg II, E10.7, ...)
 - Resolution of proxy: compatibility with data

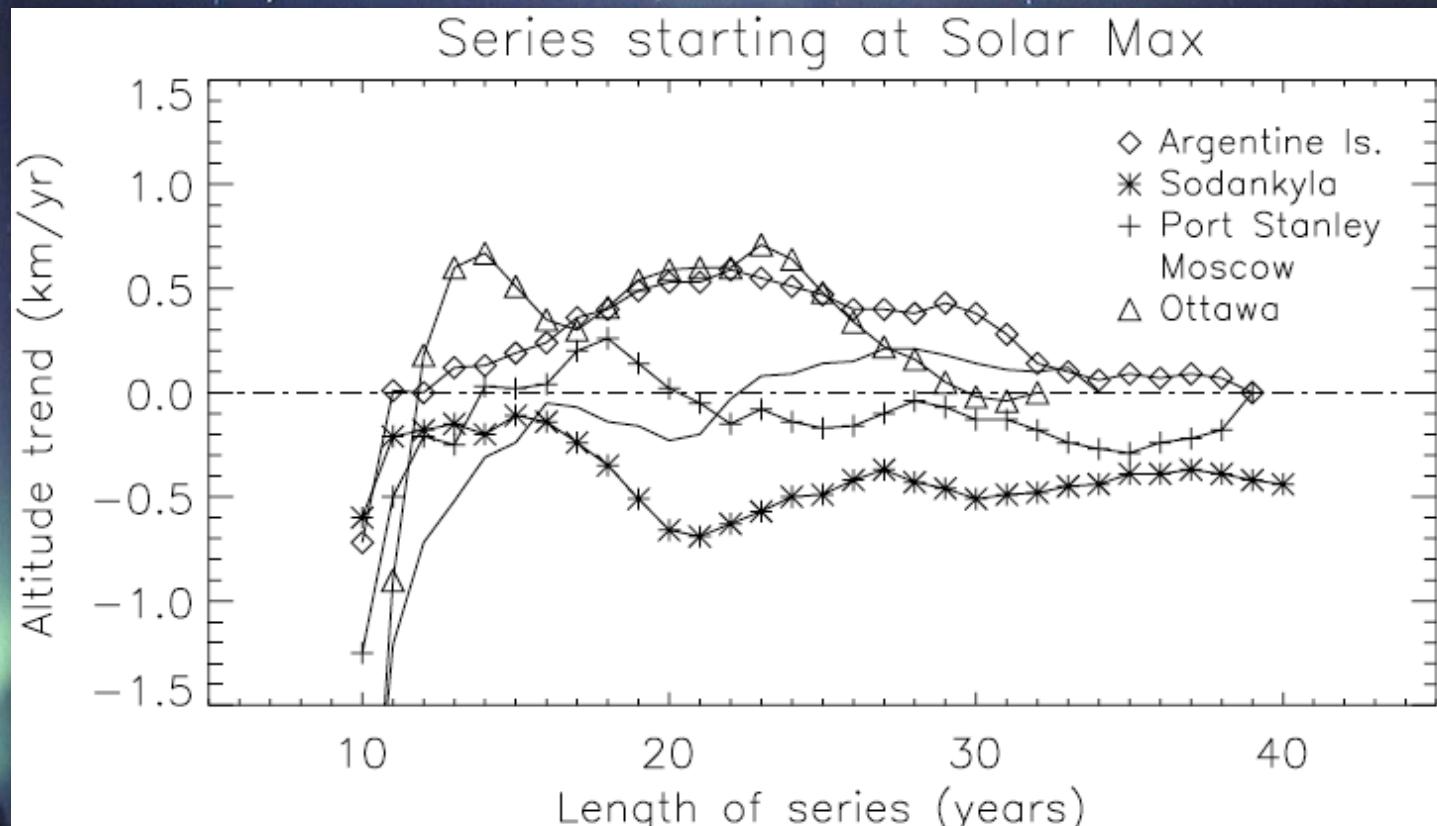
hmF2 & Solar Activity



Ringing



Ringing



The ringing idea was first introduced by Jarvis et al., 2002. The plots shown here are from a follow-up paper by Clilverd et al., 2003.

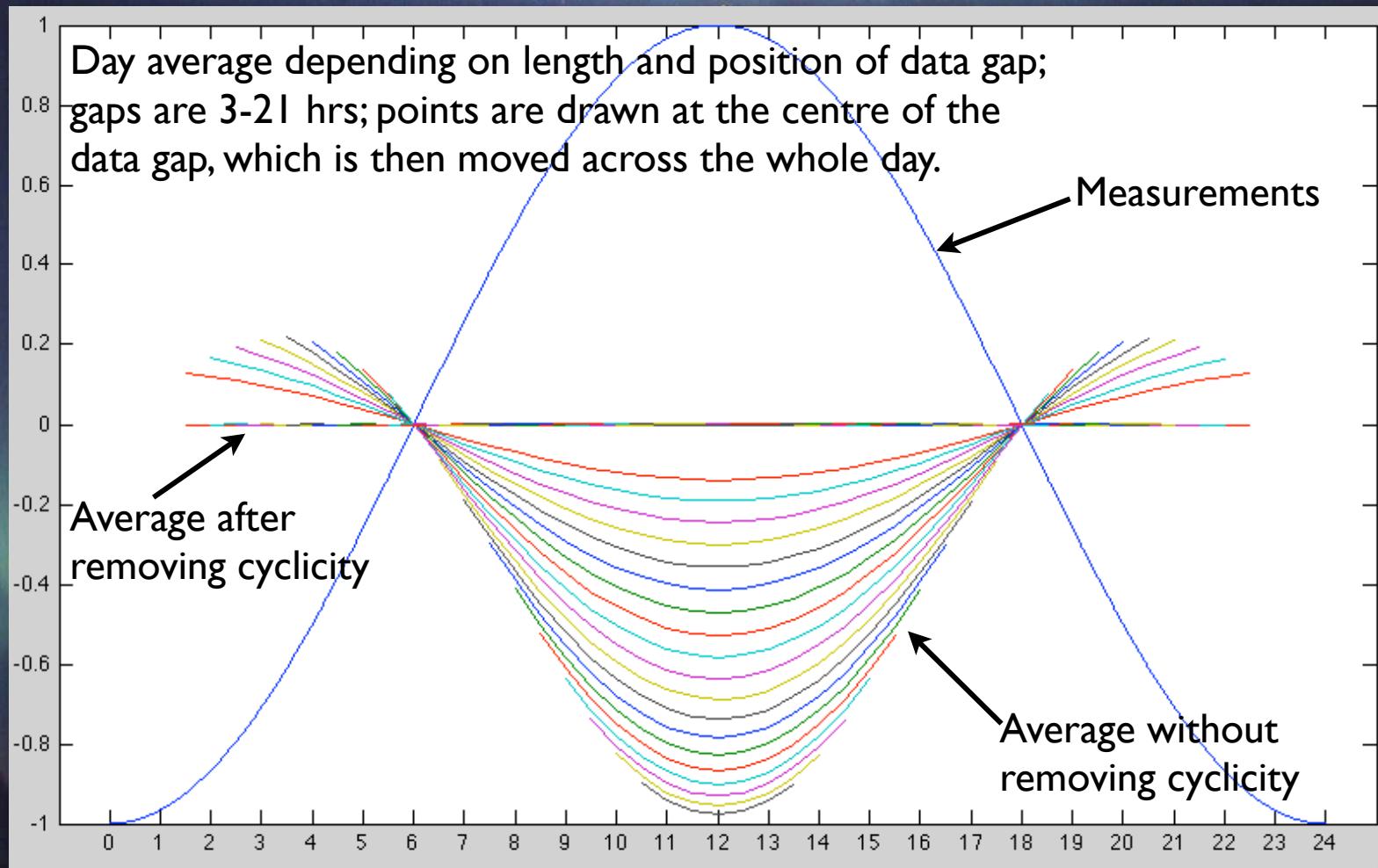
Problems

- Data resolution (h, 3-h, day, month(?), ...)
- Low-pass filtering or polynomial fitting...
- Removal of underlying (cyclic) variability: ...
- Data gaps

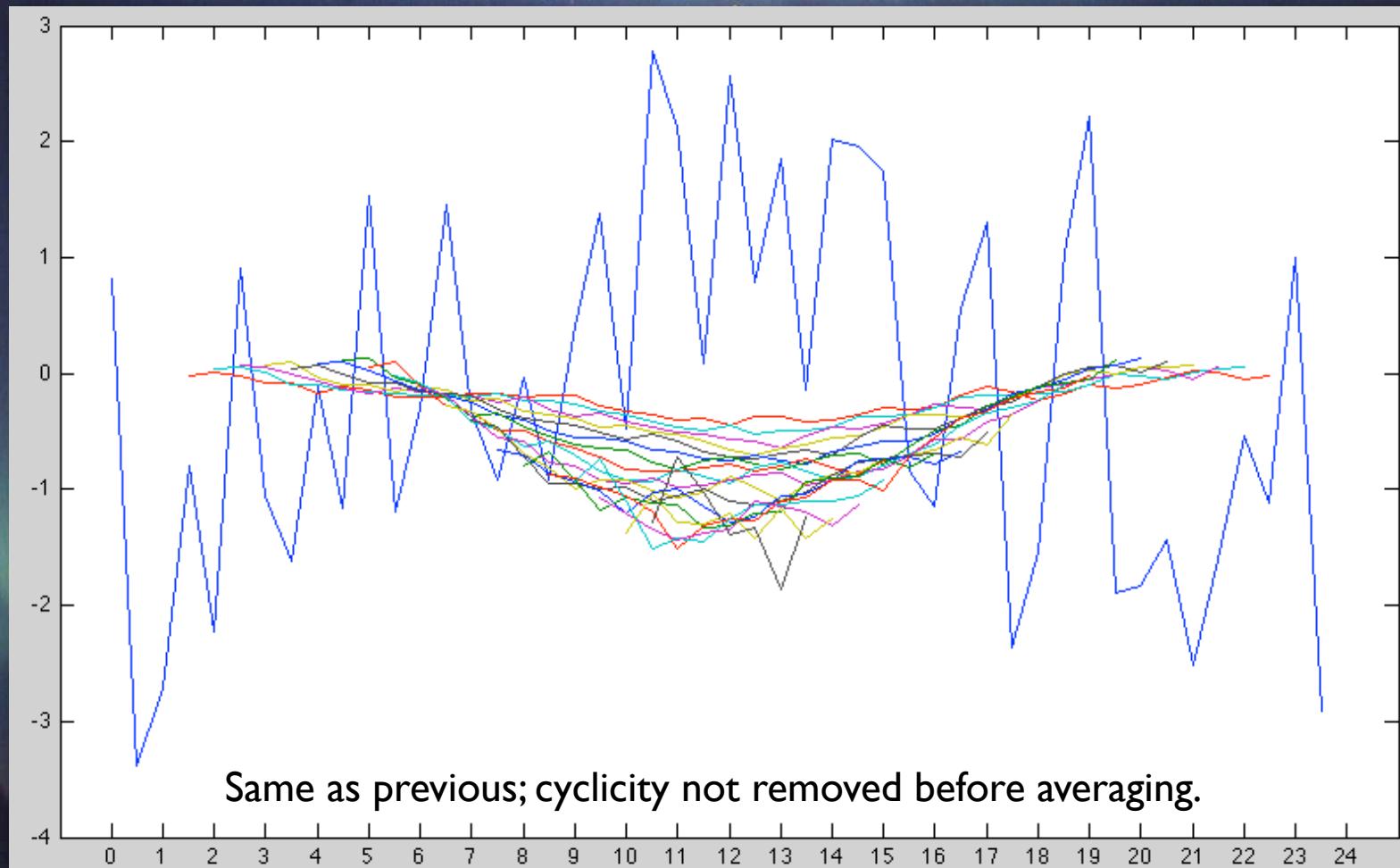
Example: Data Gaps



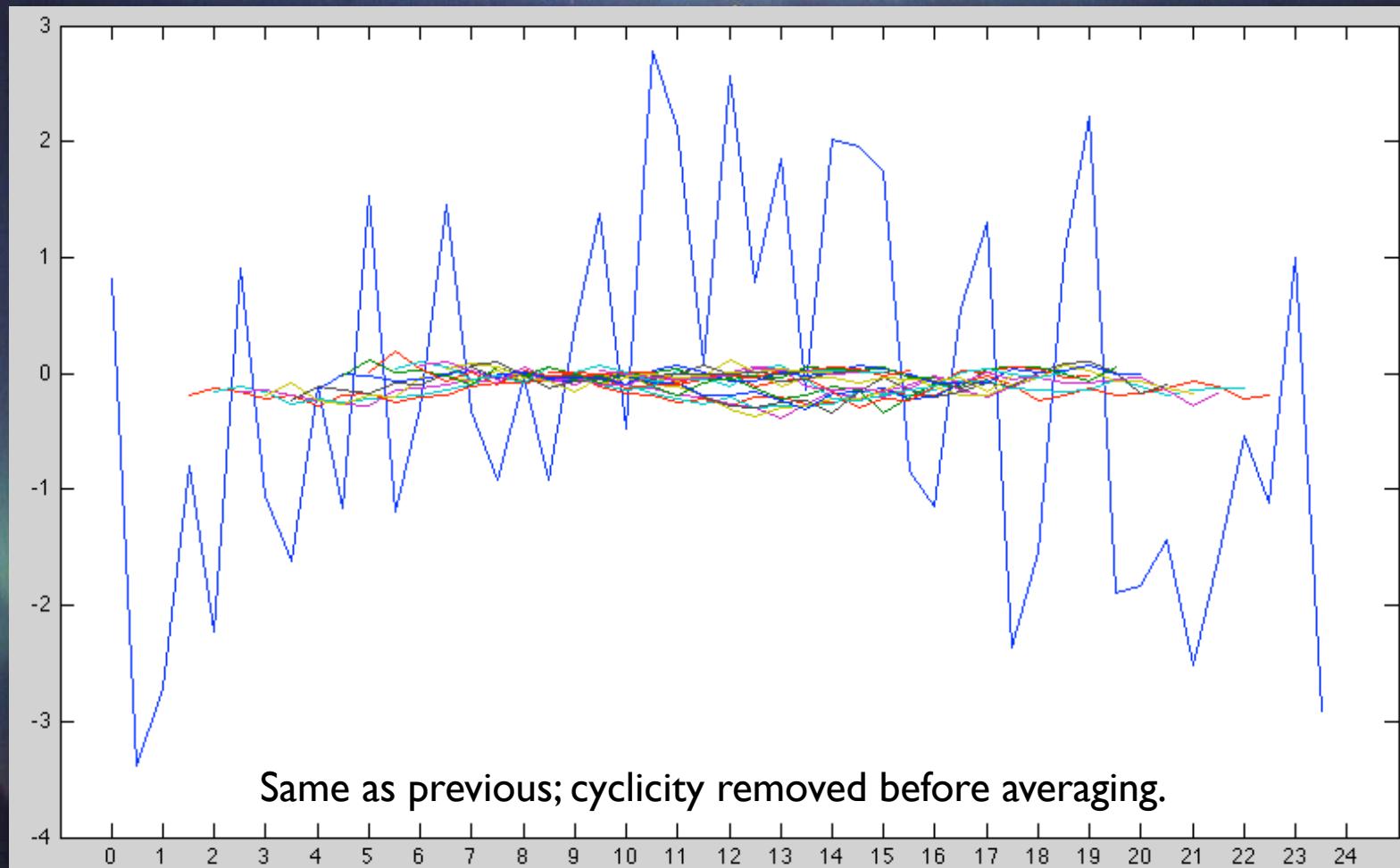
Data Gaps



Data Gaps



Data Gaps



Problems

- Data resolution (h, 3-h, day, month(?), ...)
- Low-pass filtering or polynomial fitting...
- Removal of underlying (cyclic) variability: ...
- Data gaps
- Measurement errors
- Mathematics of trend detection
 - stepwise or multi-parameter fit
 - error propagation

Making models

- Base functions of the model(s) are, e.g.:

$$m_i = \varepsilon_i + x_1 + x_2 t_i + x_3 F_{10.7}(t_i) + x_4 A_p(t_i) + x_5 \sin(2\pi t_i) + x_6 \cos(2\pi t_i) + x_7 \sin(4\pi t_i) + x_8 \cos(4\pi t_i) + \dots$$

-> measurement errors
-> constant
-> sampling times
-> solar activity
-> geomagnetic activity
-> annual variation
-> semi-annual variation

Modelling the data

The ionospheric property of interest is function of time and a number of other parameters. The model of the data is therefore

$$m(t) = \mathcal{F}(t, x_1, \dots, x_M)$$

where

$$\mathcal{F}(t, x_1, \dots, x_M) = \sum_{i=1}^M x_i f_i(t)$$

The actual measurements m_i observed at time t_i are equal to the model plus some measurement error ε_i ,

$$m_i = \mathcal{F}(t_i, x_1, \dots, x_M) + \varepsilon_i$$

Inverse problem I

This can be expressed as a matrix equation. Usually there are many more data points than unknowns x_i and the problem is over-determined:

$$\begin{pmatrix} m_1 \\ m_2 \\ \vdots \\ m_N \end{pmatrix} = \begin{pmatrix} f_1(t_1) & f_2(t_1) & \cdots & f_M(t_1) \\ f_1(t_2) & f_2(t_2) & \cdots & f_M(t_2) \\ \vdots & \vdots & \ddots & \vdots \\ f_1(t_N) & f_2(t_N) & \cdots & f_M(t_N) \end{pmatrix} \cdot \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_M \end{pmatrix} + \begin{pmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \vdots \\ \varepsilon_N \end{pmatrix}$$

In other words:

$$\mathbf{m} = \mathbf{A} \cdot \mathbf{x} + \boldsymbol{\varepsilon}$$

Inverse problem II

Measurements and theory are weighted by the measurement errors:

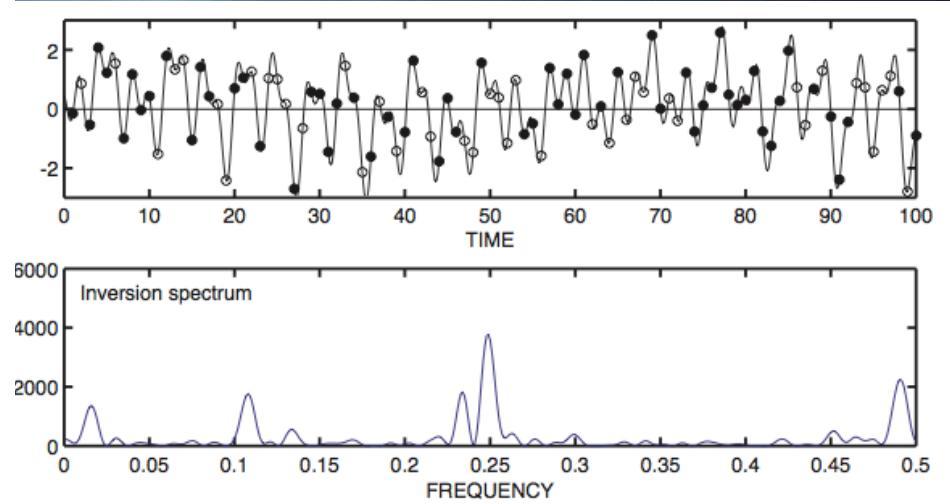
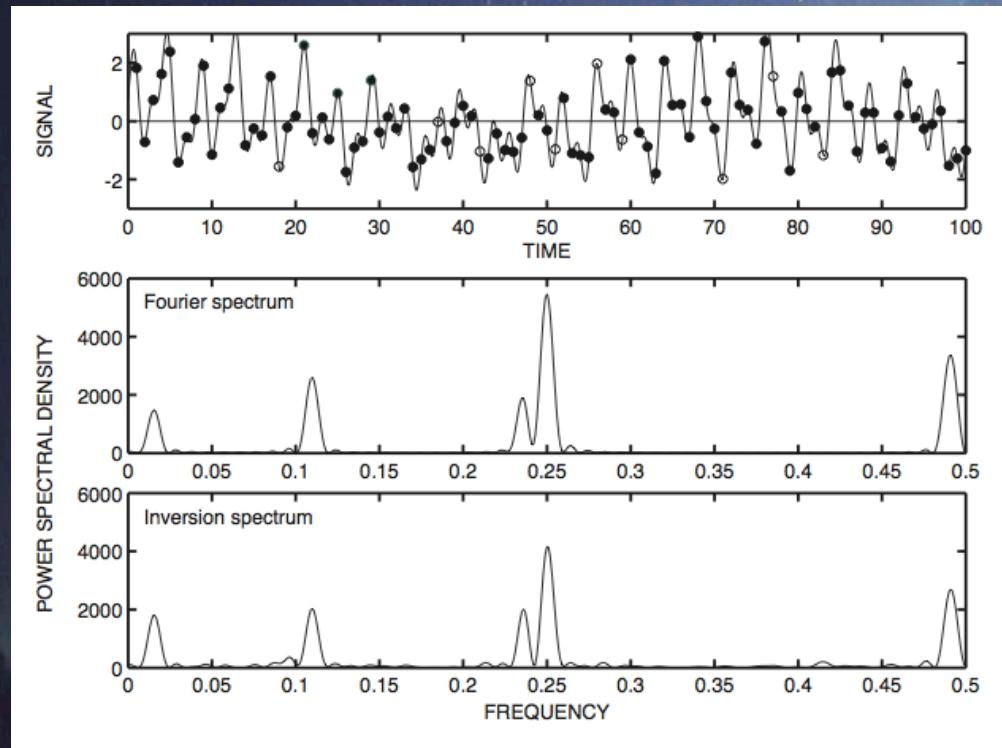
$$B_{ij} := \frac{A_{ij}}{\varepsilon_i} \quad \text{and} \quad b_i := \frac{m_i}{\varepsilon_i}$$

The solution is the vector \mathbf{x} , which minimises the following expression:

$$\chi^2 = |\mathbf{B} \cdot \mathbf{x} - \mathbf{b}|^2$$

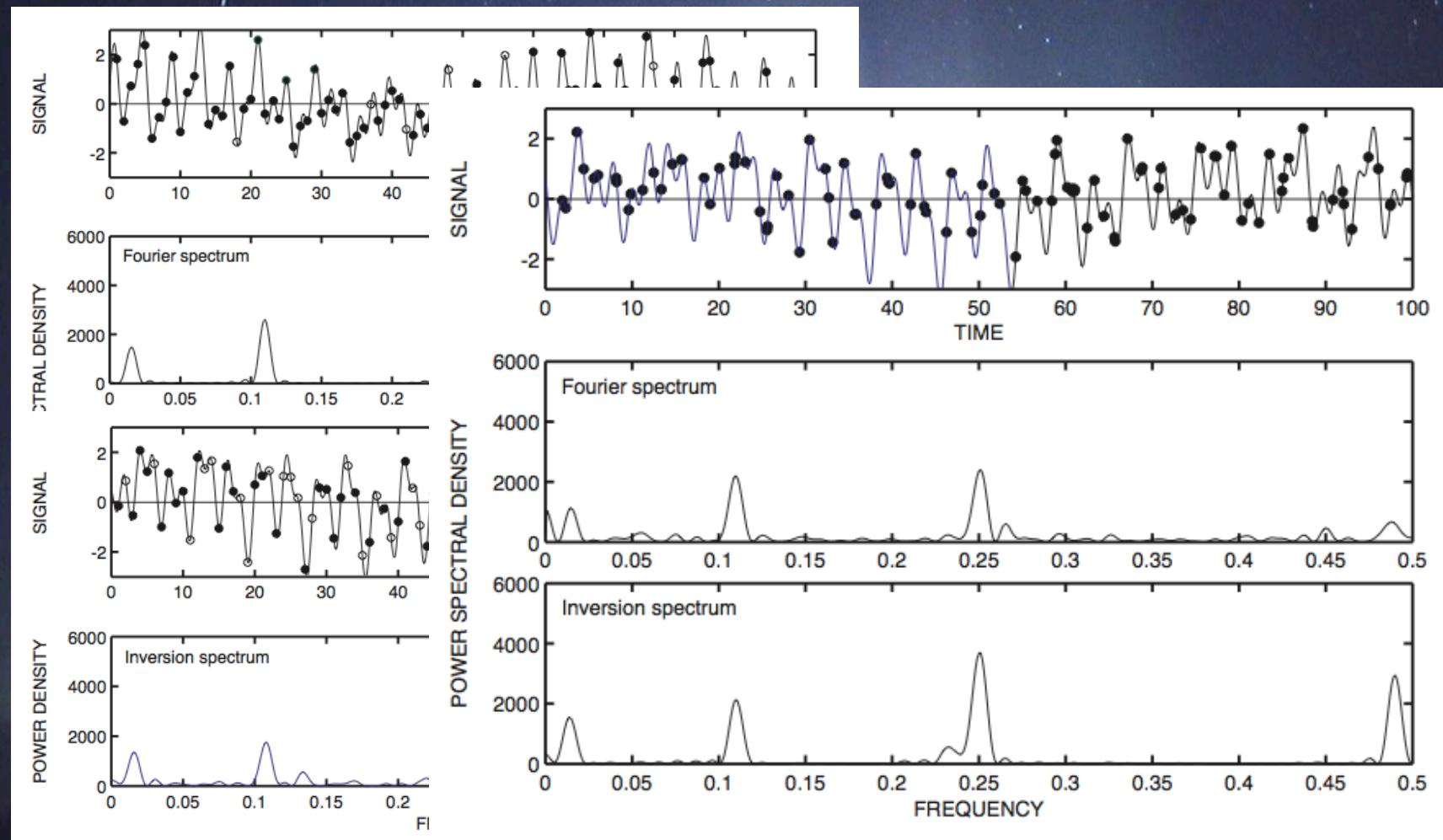
We are left with a general least squares problem.
Solving this results in the most probable solution for \mathbf{x} .

Signal Spectrum by Stochastic Inversion



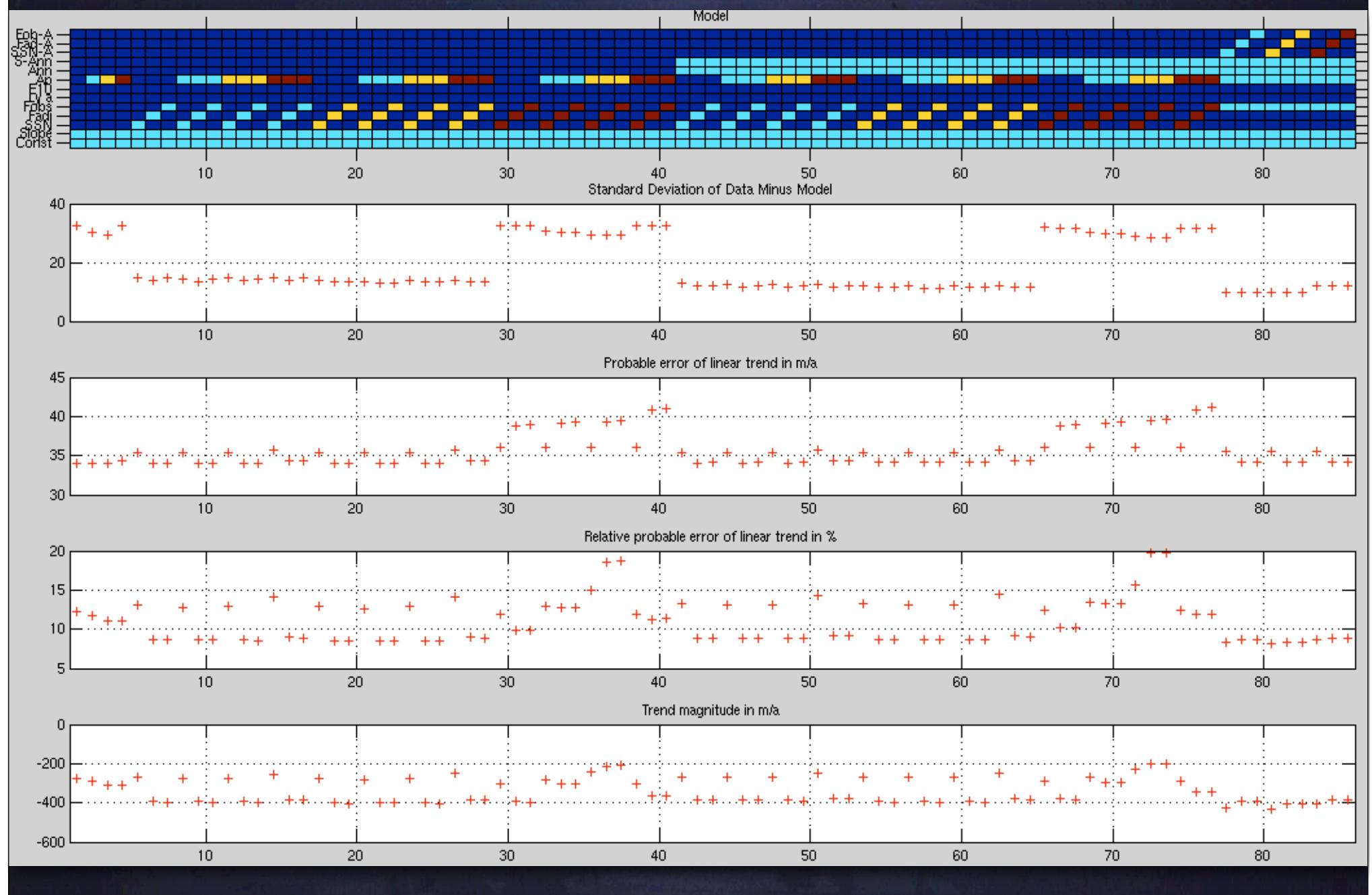
Left: 100 pts for Fourier, 90 for inversion.
Above: 59 pts.

Signal Spectrum by Stochastic Inversion



T. Nygrén and Th.Ulich, Calculation of signal spectrum by means of stochastic inversion, Ann. Geophys., 28, 1409-1418, 2010.

Sodankylä F2-layer peak height hmF2



Conclusion

- This is pointless?

I don't think so...

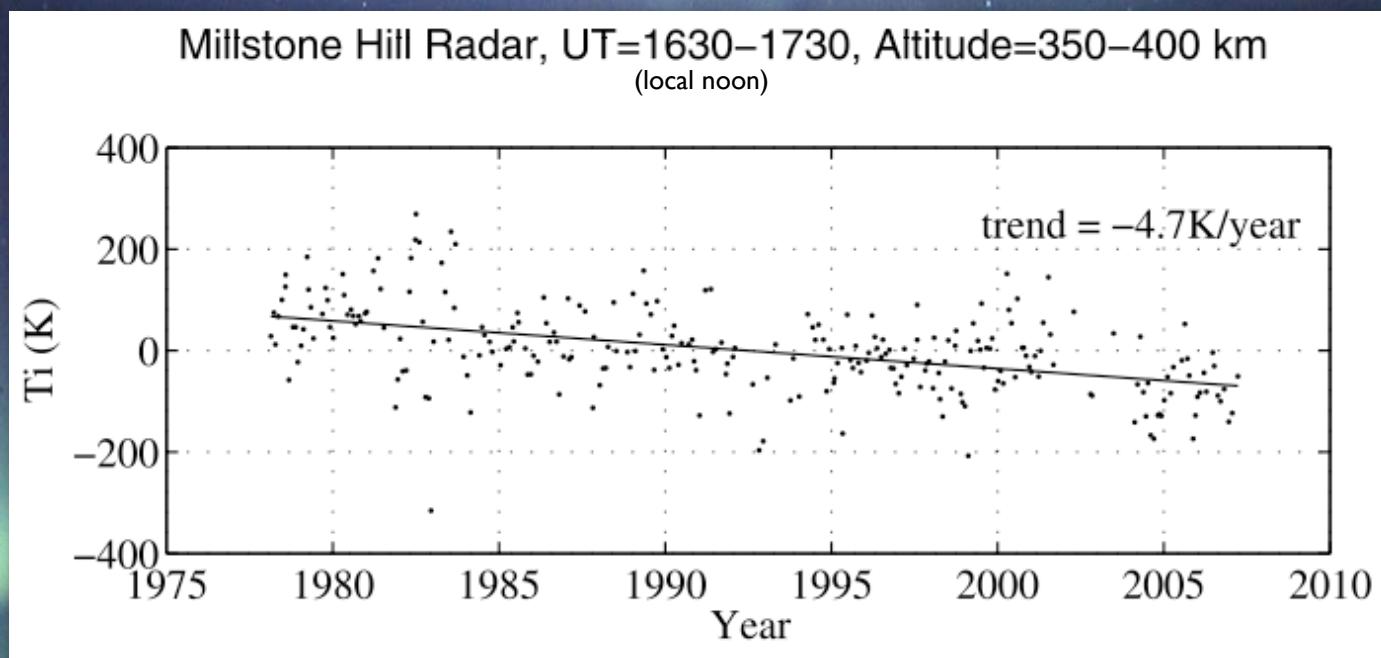
...yet!



Trends in other Observations

Height in km	Method	Parameter	Trend per Year	Reference
75	Sounding rocket	Temperature	-0.6 K	Kokin and Lysenko, 1994
70	Sounding rocket	Temperature	-0.7 K	Golitsyn et al., 1996
60-70	Lidar	Temperature	-0.4 K	Hauchecorne et al., 1991
60	Sounding rocket	Temperature	-0.4 K	Golitsyn et al., 1996
60	Sounding rocket	Temperature	-0.33 K	Keckhut et al., 1999
50-60	Lidar	Temperature	-0.25 K	Aikin et al., 1991
50	Sounding rocket	Temperature	-0.25 K	Golitsyn et al., 1996
40	Sounding rocket	Temperature	-0.1 K	Golitsyn et al., 1996
30-60	Sounding rocket	Temperature	-0.17 K	Dunkerton et al., 1998
30-50	Sounding rocket	Temperature	-0.17 K	Keckhut et al., 1999
30	Sounding rocket	Temperature	-0.1 K	Golitsyn et al., 1996
25	Sounding rocket	Temperature	-0.1 K	Golitsyn et al., 1996
25	Sounding rocket	Temperature	-0.11 K	Keckhut et al., 1999

Direct F-Region Temperature



Long-term temperature trends in the ionosphere above Millstone Hill

J. M. Holt¹ and S. R. Zhang¹

GEOPHYSICAL RESEARCH LETTERS, VOL. 35, L05813, doi:10.1029/2007GL031148, 2008

Conclusion

(the last one, I promise!)

- Definitely, there's long-term change in the ionosphere and thermosphere!
- The enhanced greenhouse effect is probably a part of it.
- Other (unknown?) processes are involved.
- Solution in modelling?
- We don't understand what's going on.
- Student exercise: Find out!

Conclusion

(I lied to you!)

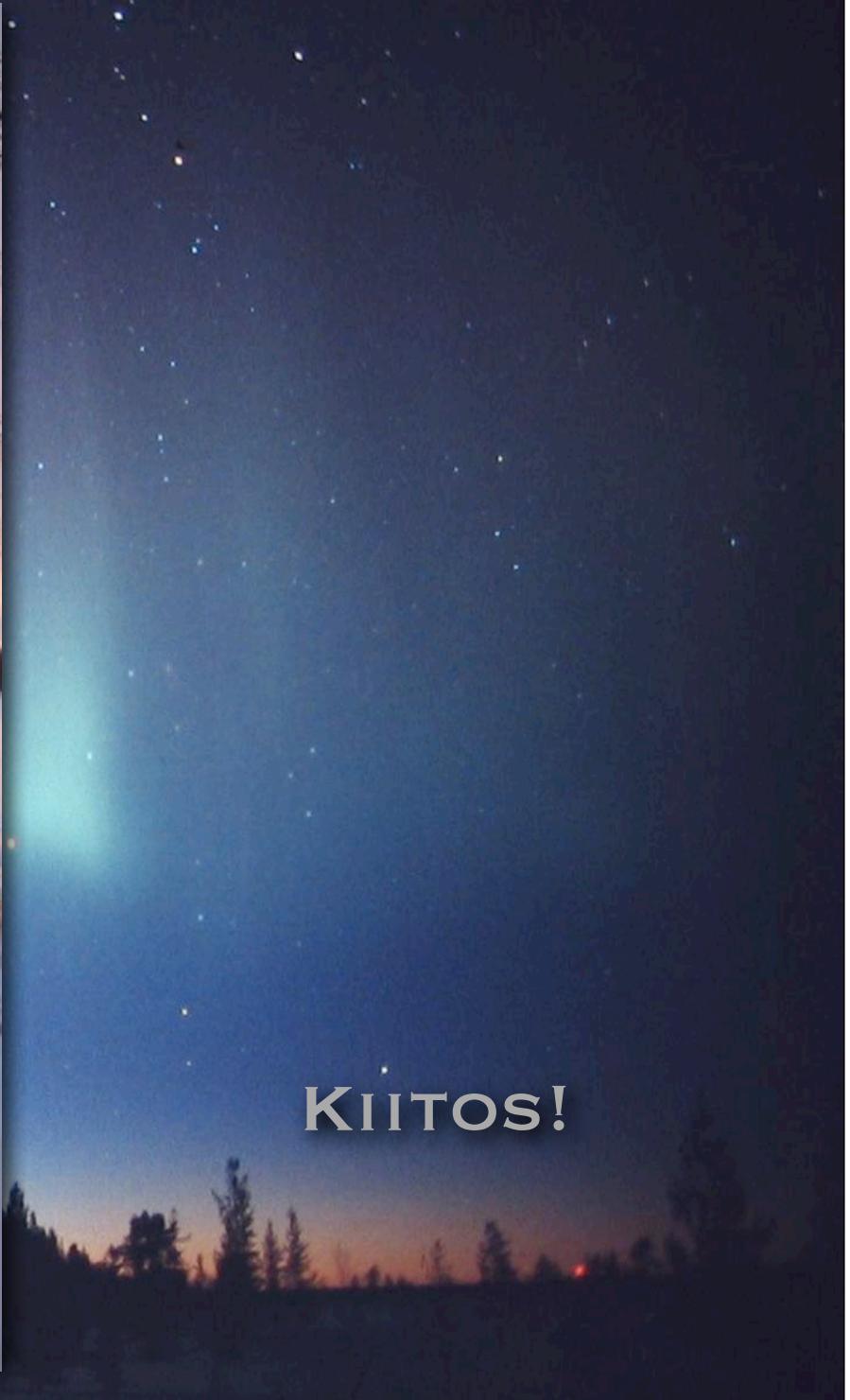
Ion sondes, originally deployed for monitoring ionospheric conditions for HF radio communication and for studying short-term events, are becoming useful in an environmental context.

They provide long-term measurements of our environment!

Do not discontinue atmospheric observations at a time of climate change!



Photo: Sally Ulich



KIITOS!