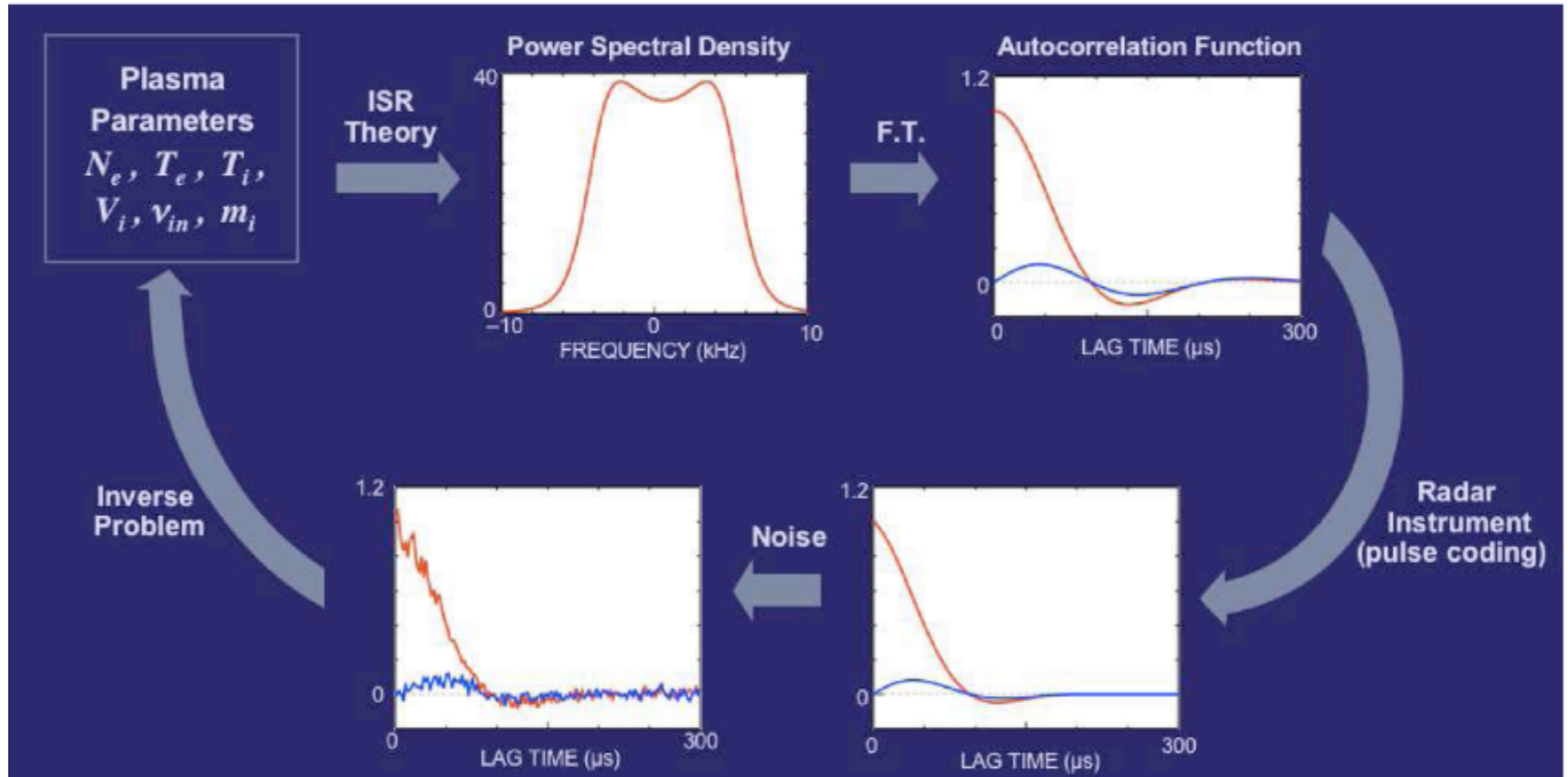
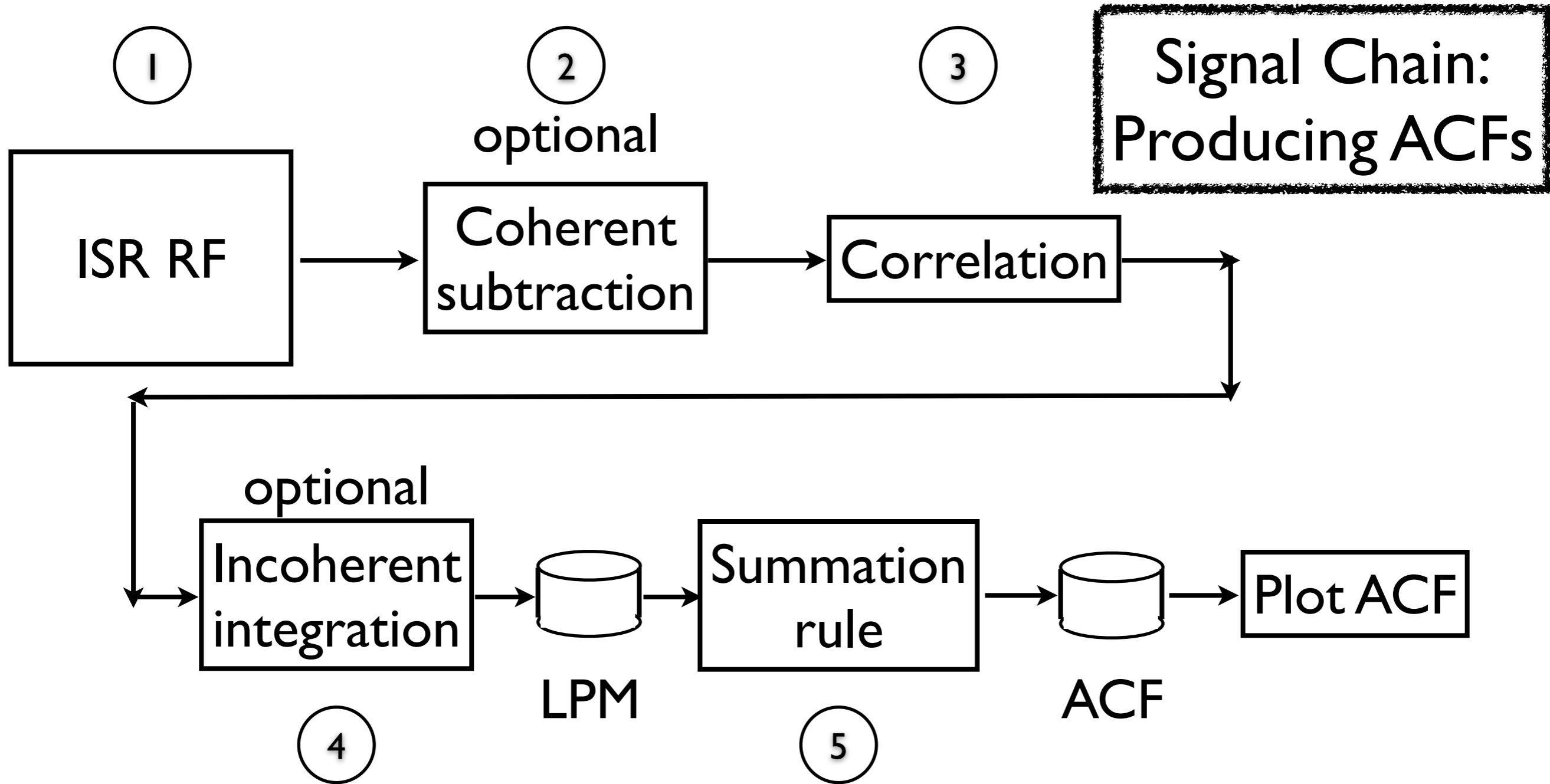


ISR Practicalities: Data Reduction

NB: Power spectrum (freq domain) \leftrightarrow Autocorrelation function (time domain)





① $V(m, t_k) \equiv V_{m,k} = I_{m,k} + jQ_{m,k}$ ③ $LPM_{m,n,p} = V_{m,n}V_{m,n+p}^*$

② $V_{m,k} = V_{m+1,k} - V_{m,k}$

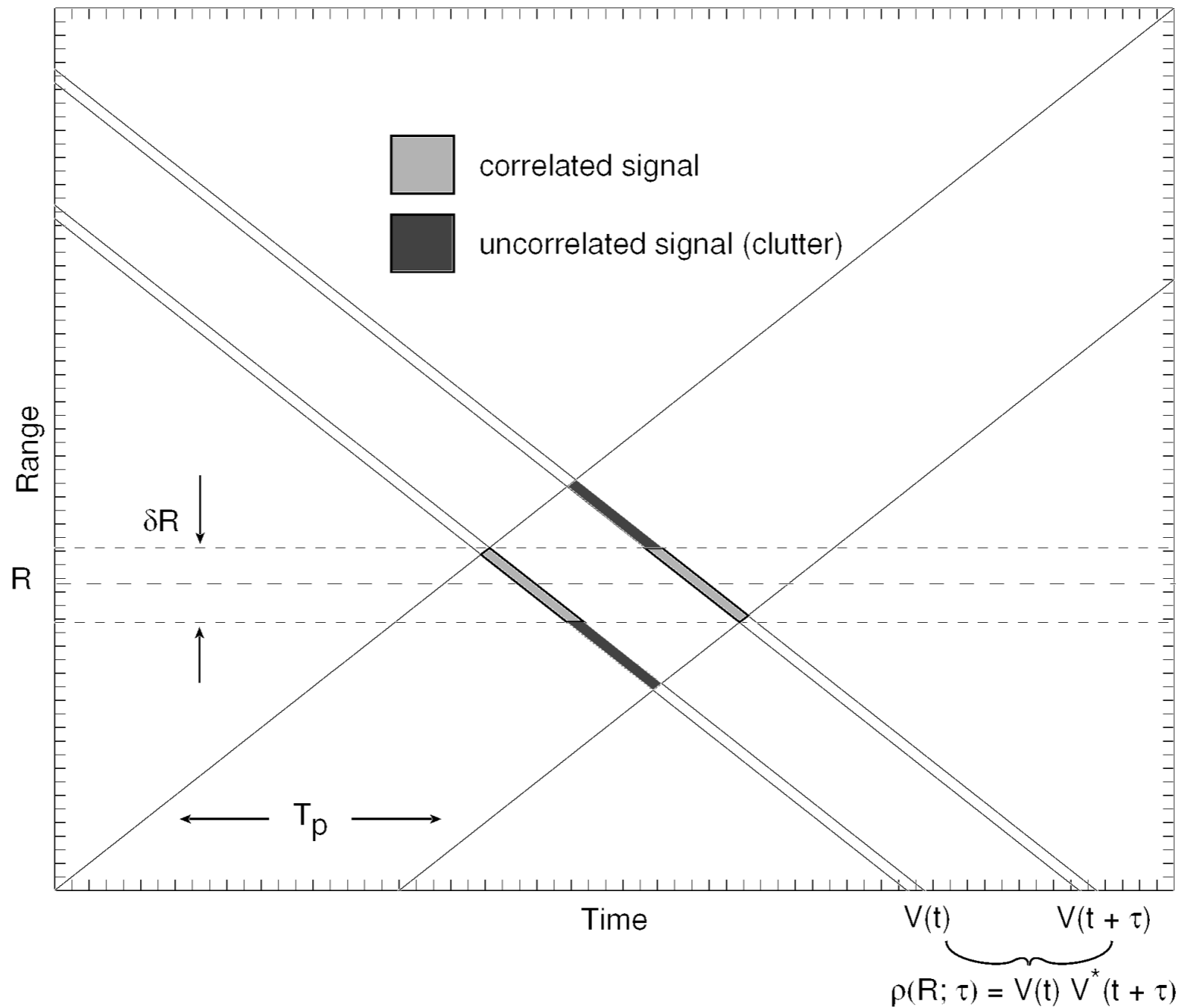
④ $LPM_{n,p} = \sum_{m=1}^M LPM_{m,n,p}$

⑤ Trapezoidal summation

Long Pulse: Range-Time Diagram

As lag increases, correlated signal goes down and uncorrelated signal (clutter = noise) goes up. Bad statistics!

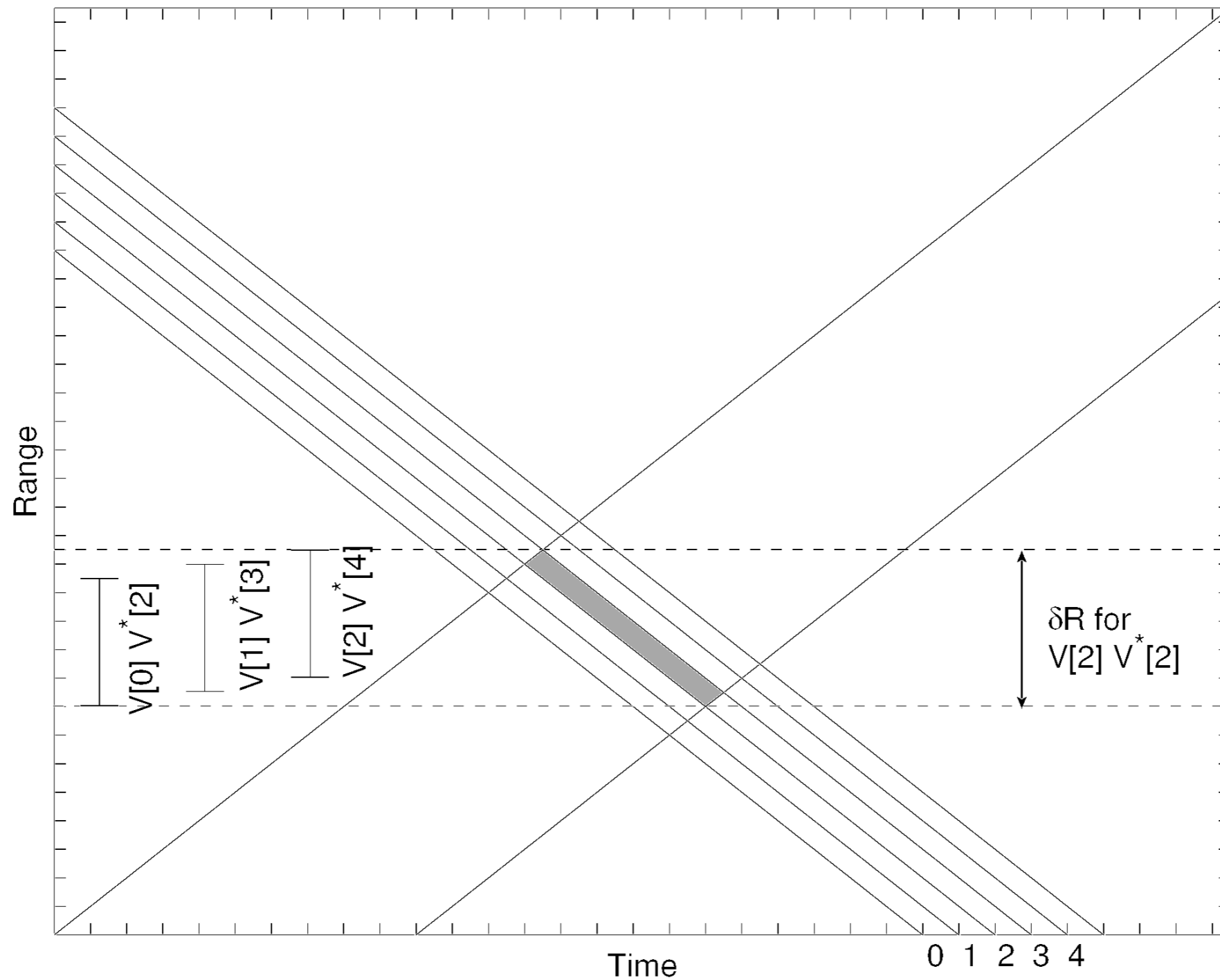
Altitude resolution of individual ACF lags not uniform as a function of lag!



Can't measure ACF at lags larger than pulse length (which sets frequency resolution in your measured power spectrum)*

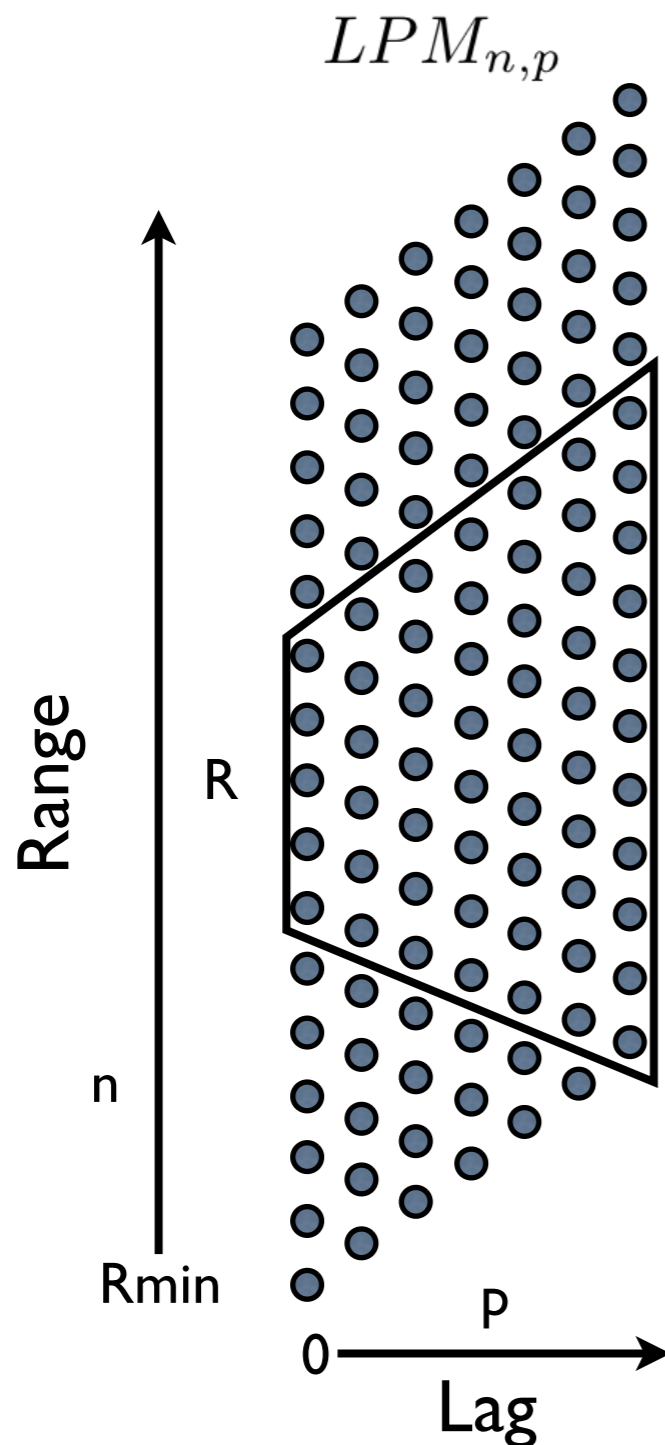
- This is true for any pulsed waveform when we are overspread! (note mismatched RX filter)

Long Pulse: Improving Statistics



But note that final altitude resolution is still the size of the transmitted pulse (i.e. zero lag).

Summation Rules: Improving Statistics for LPM -> ACF

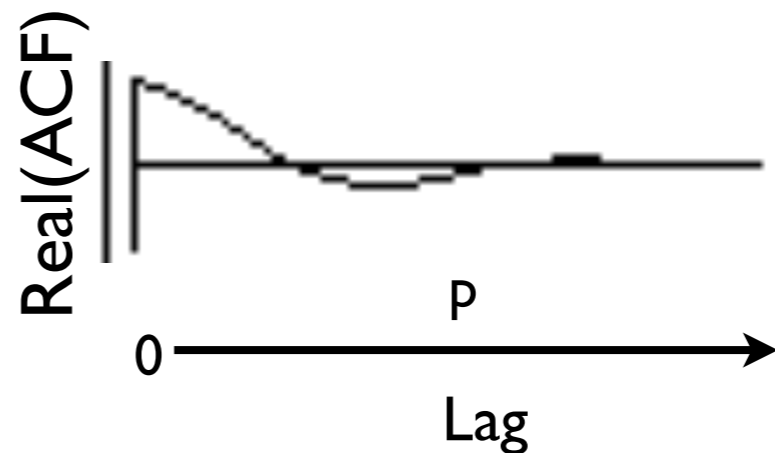


Trapezoidal summation rule

NB: Greatly improved statistics at longer lags comes at expense of spatial resolution!

Lossy operation: information is lost.

$$\rho(R; \tau = p\Delta T)$$



Fitting data to a model

Goal: minimize

$$\chi^2 = \sum_{j=1}^n \frac{[y(x_j) - \text{model}(x_j; \vec{p})]^2}{\sigma_j^2}$$

“L2 Norm”

data

parameter vector

independent variable

uncertainties

Minimize by iterating over parameter vectors.

Some problems are linear least-squares: solvable in one step.

Others are nonlinear least-squares:

model has complicated variations with parameters.

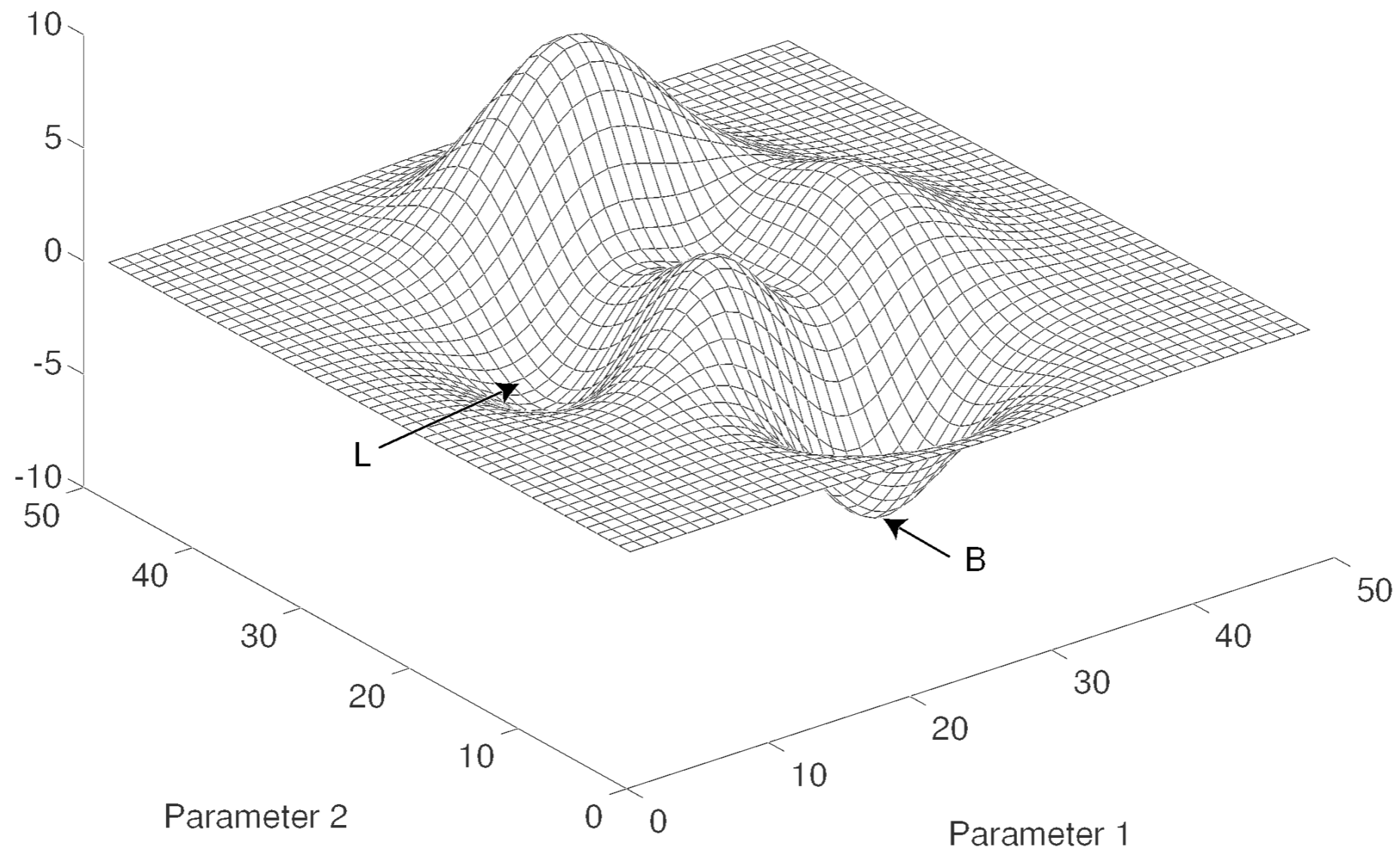
Incoherent scatter is this type.

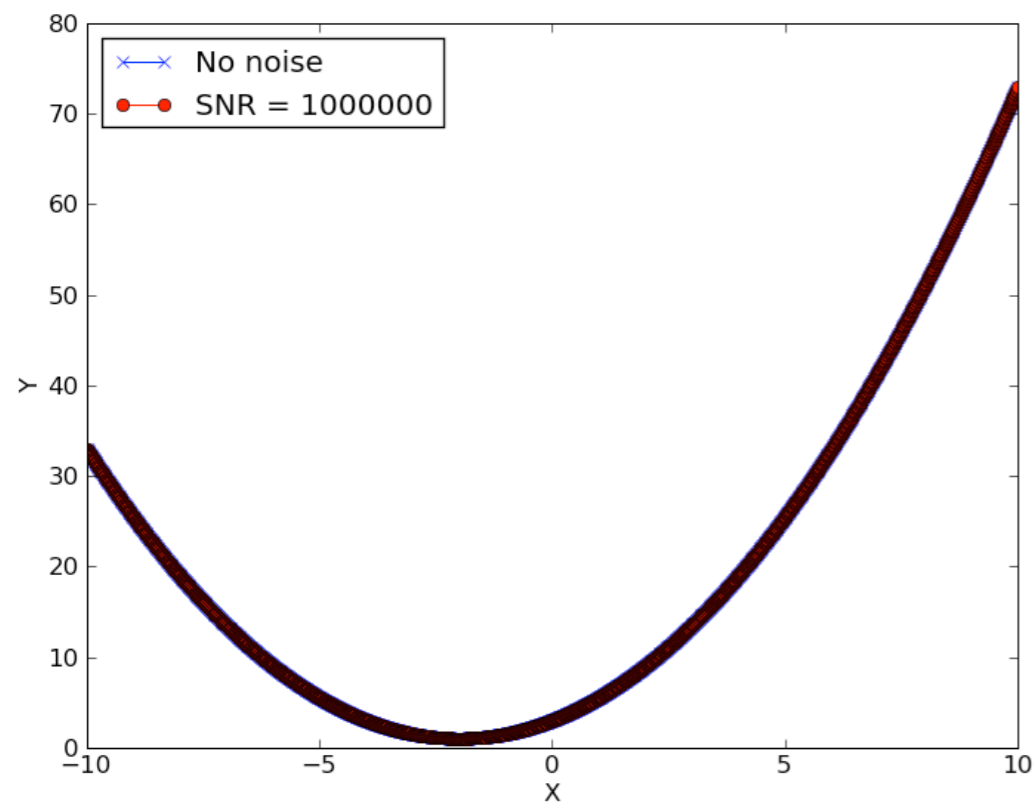
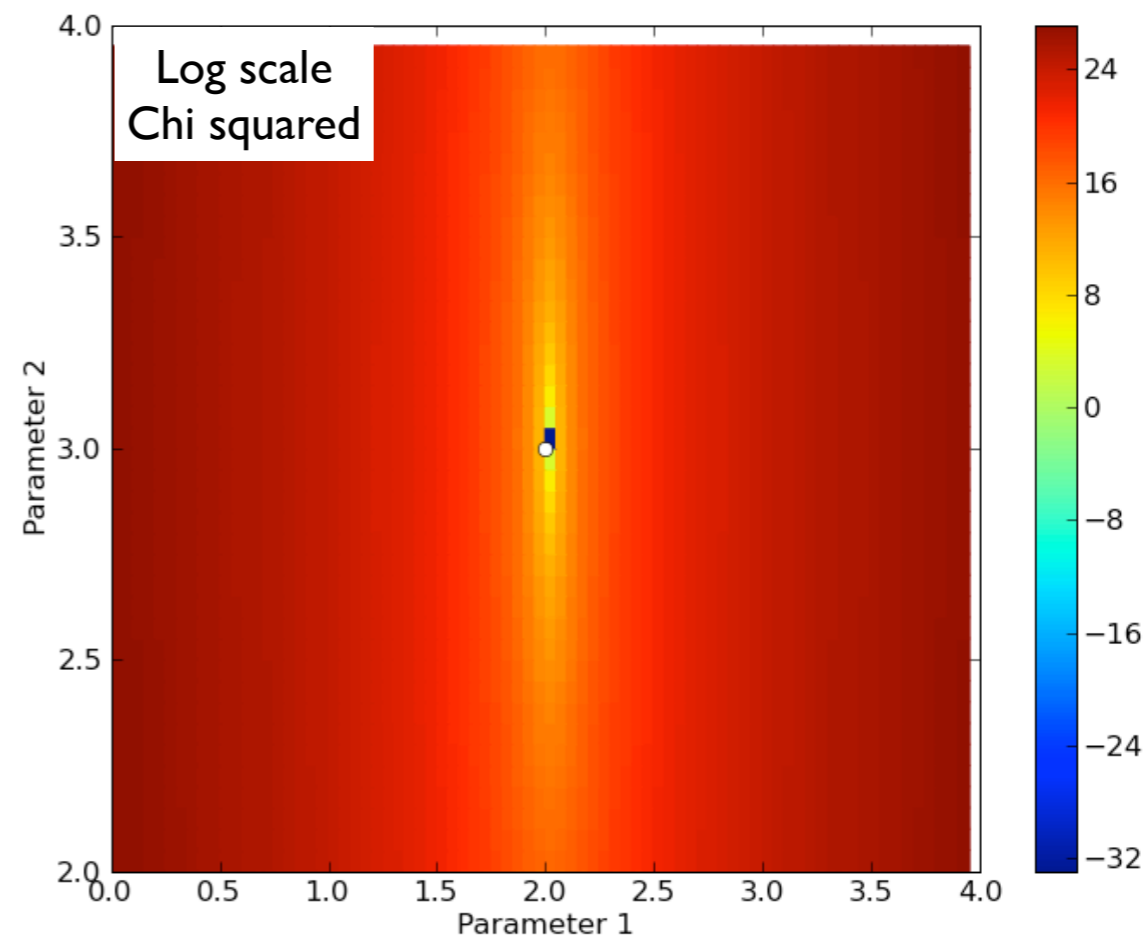
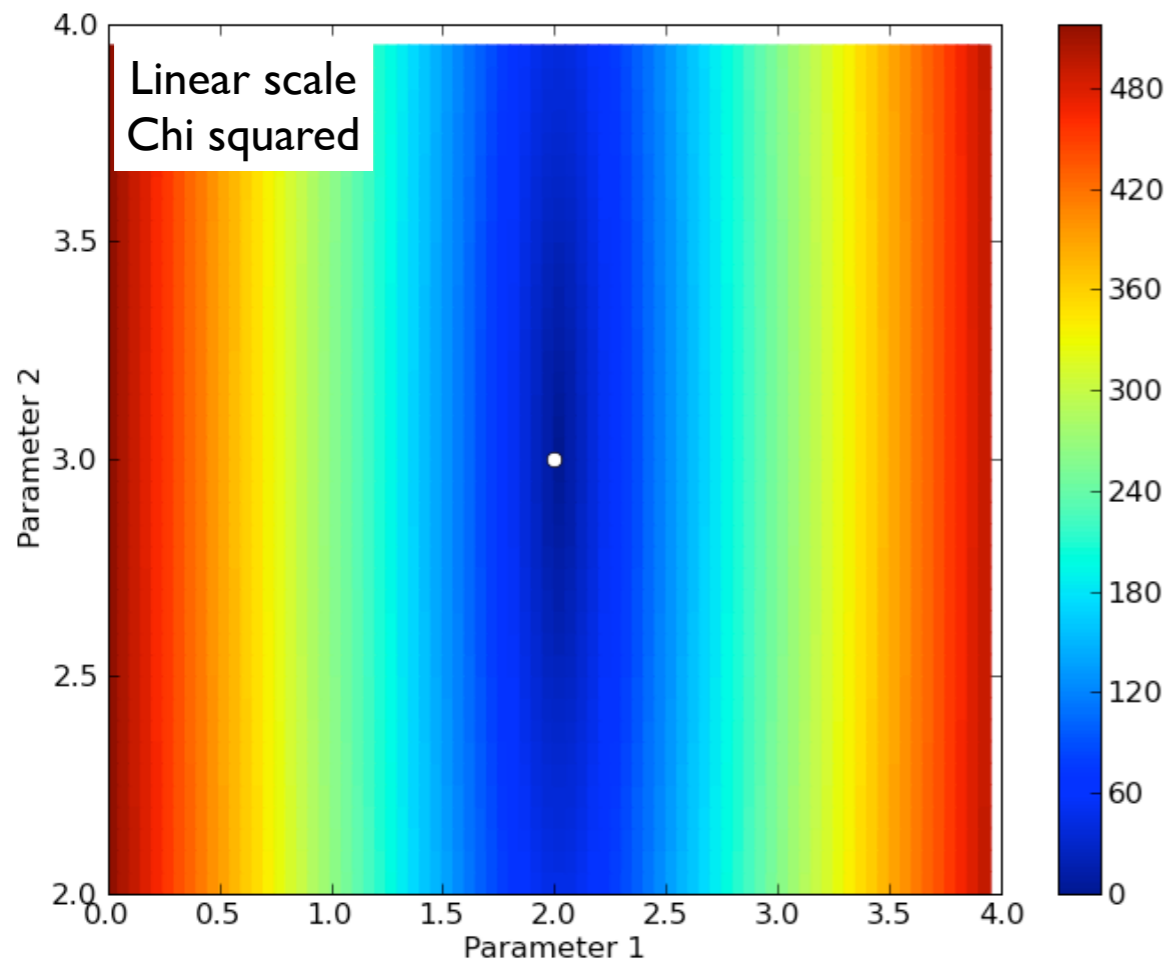
Many different fitting algorithms possible depending on how one analytically expands the minimization function:

- Gradient-search (Nelder-Mead simplex)
- Analytic expansion (parabolic surface)
- Levenberg-Marquardt (balance between gradient and analytic)
- Simulated annealing

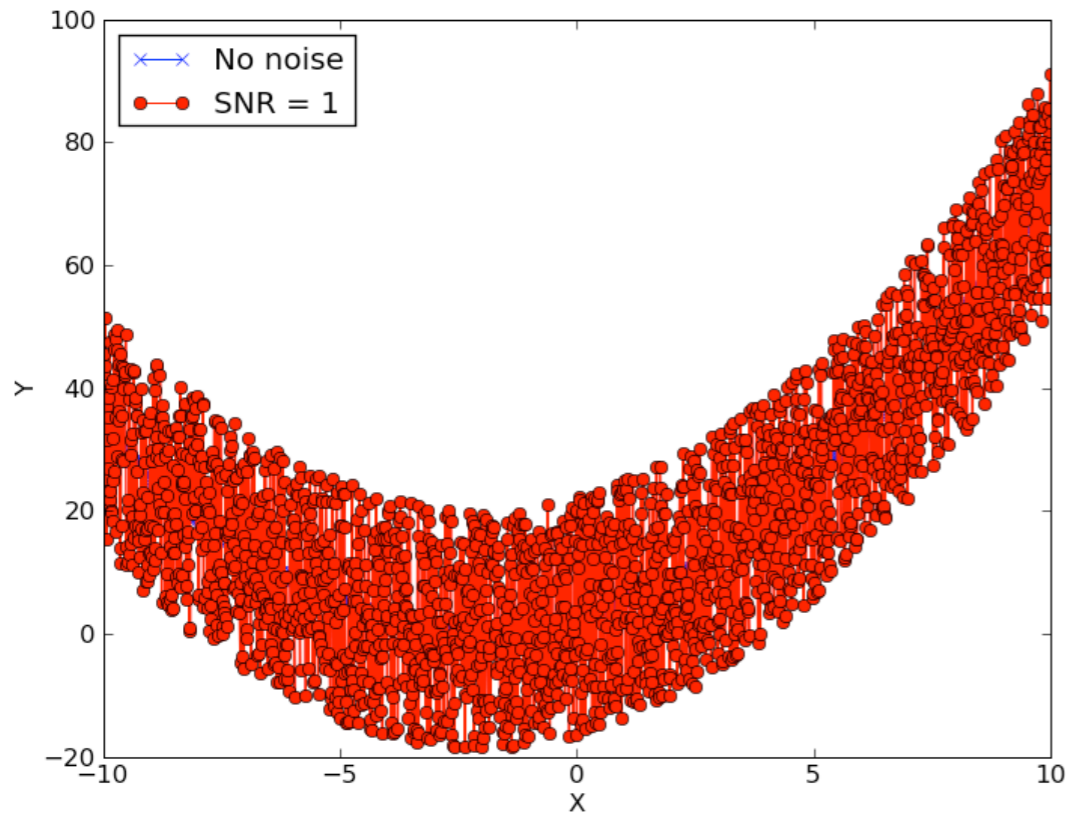
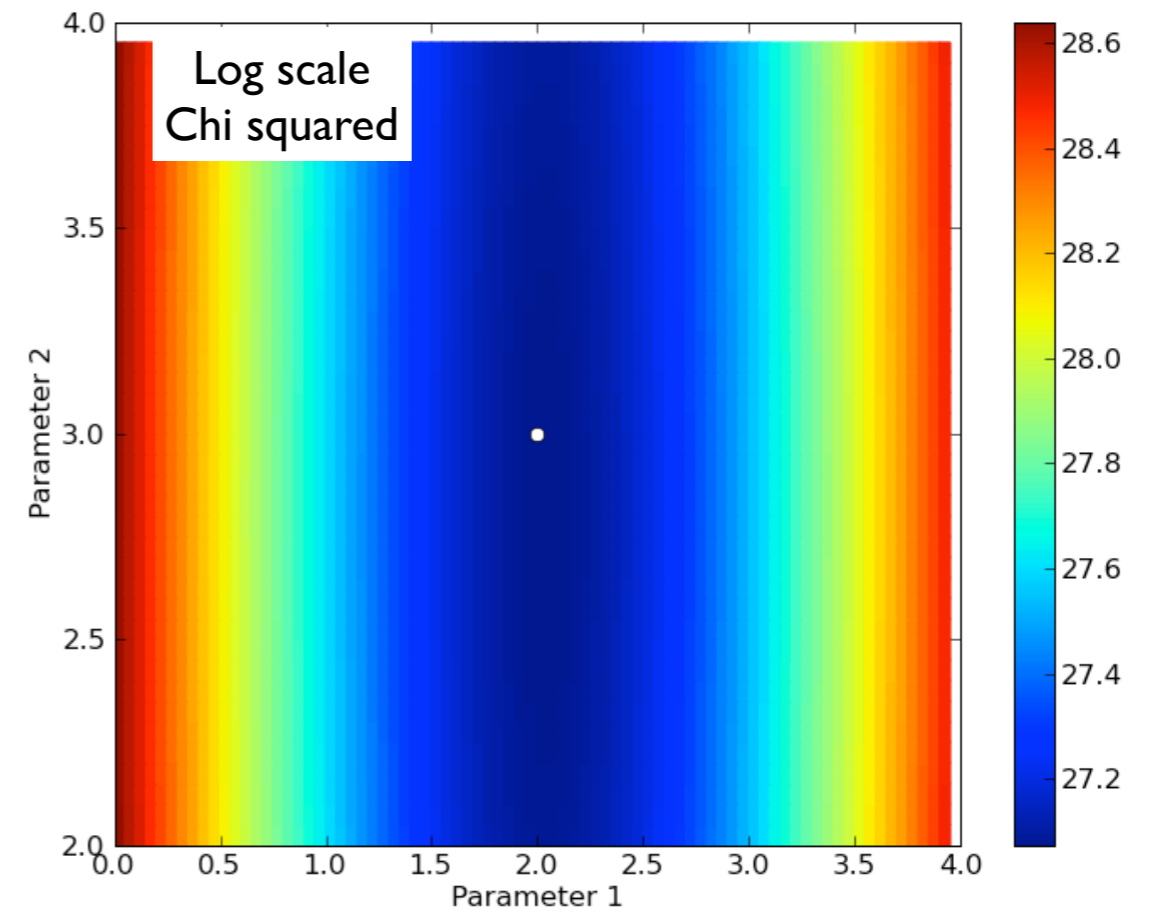
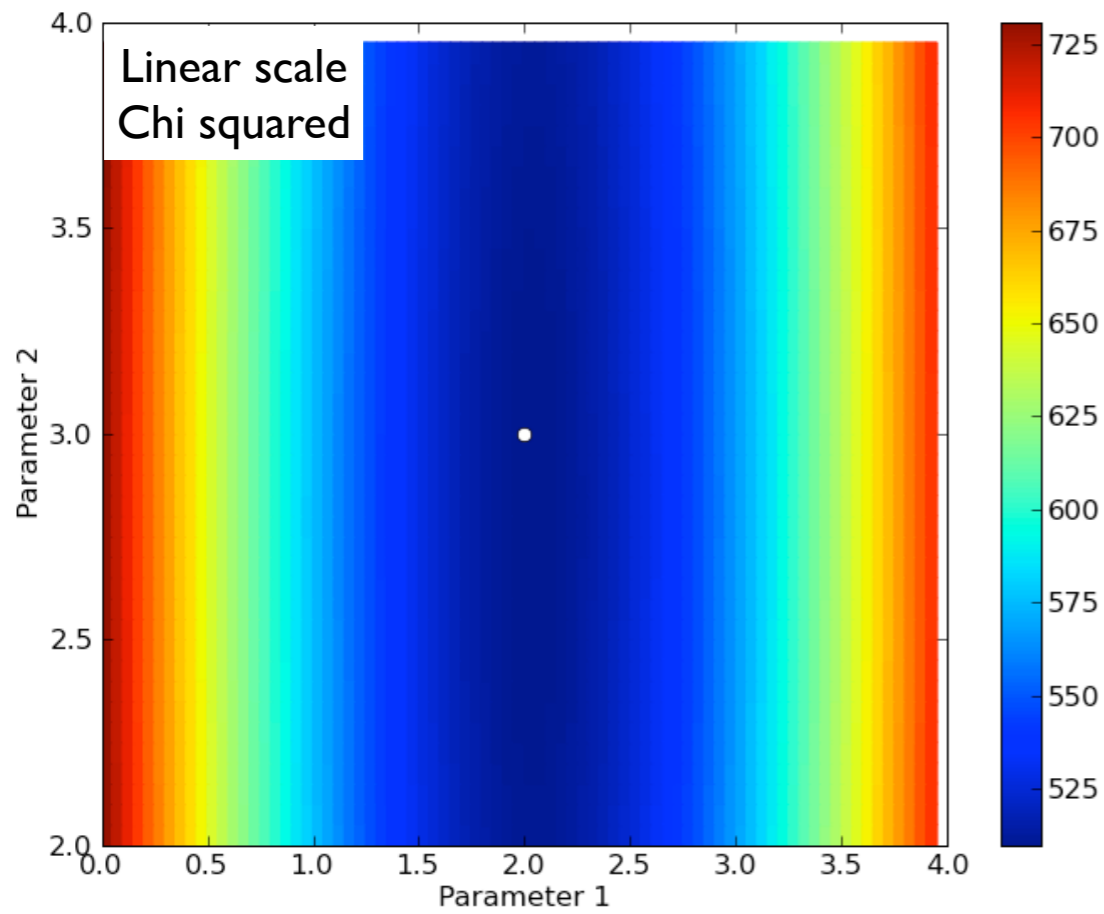
Incoherent Scatter Fit Ambiguities

L, B might both be valid parameter solutions. Might need to use constraints on the parameters to decide which one.

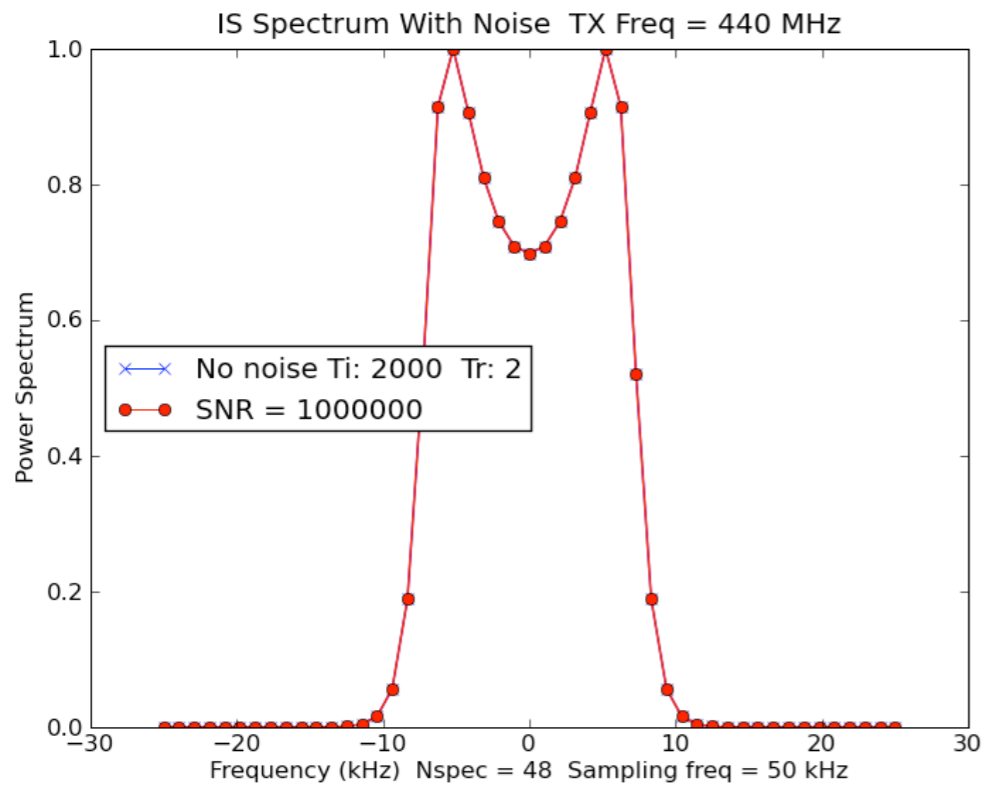
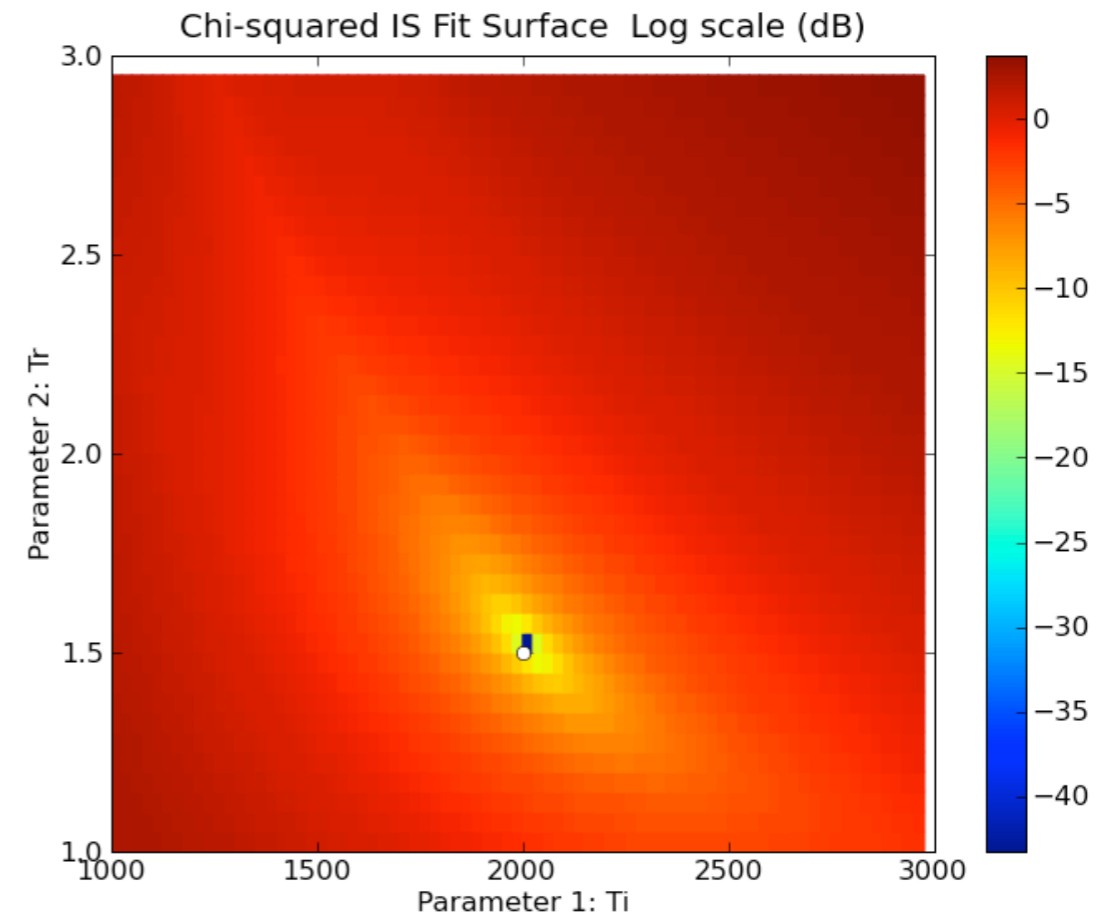
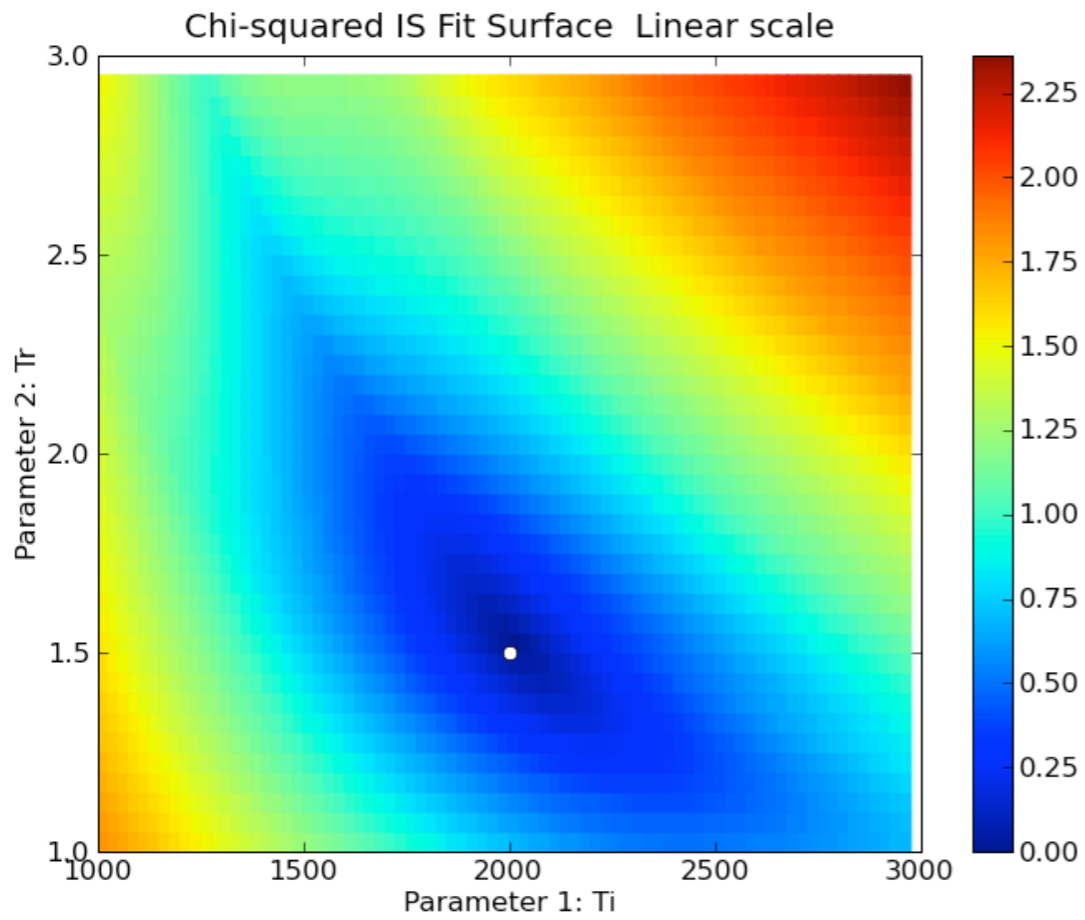




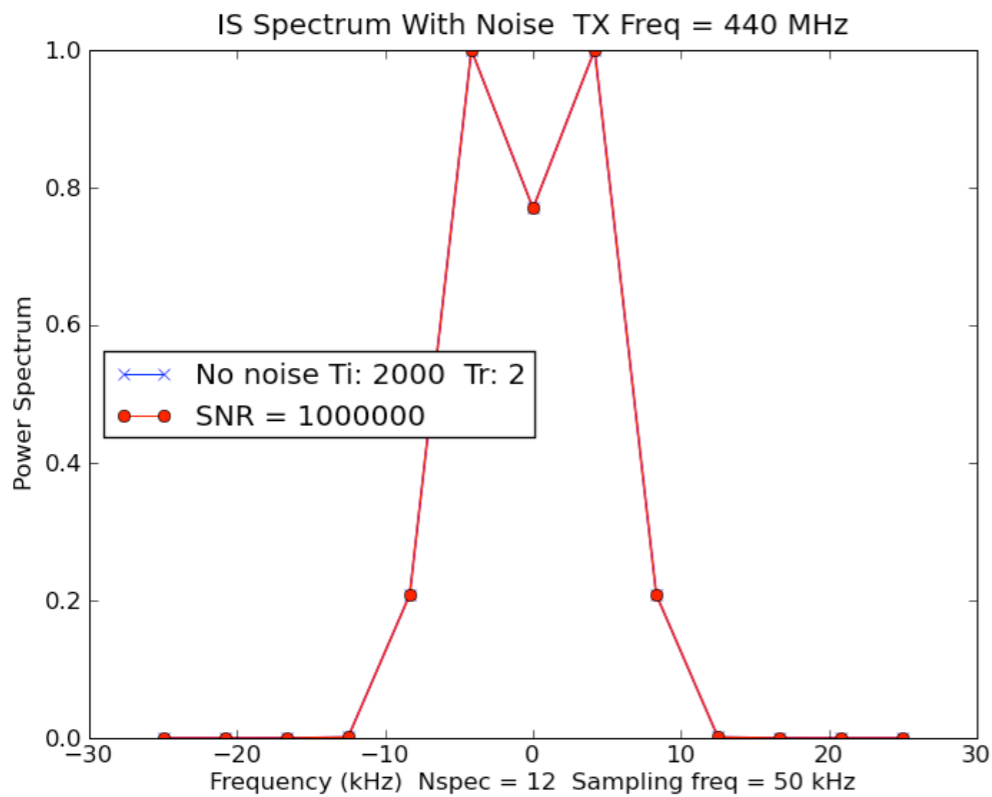
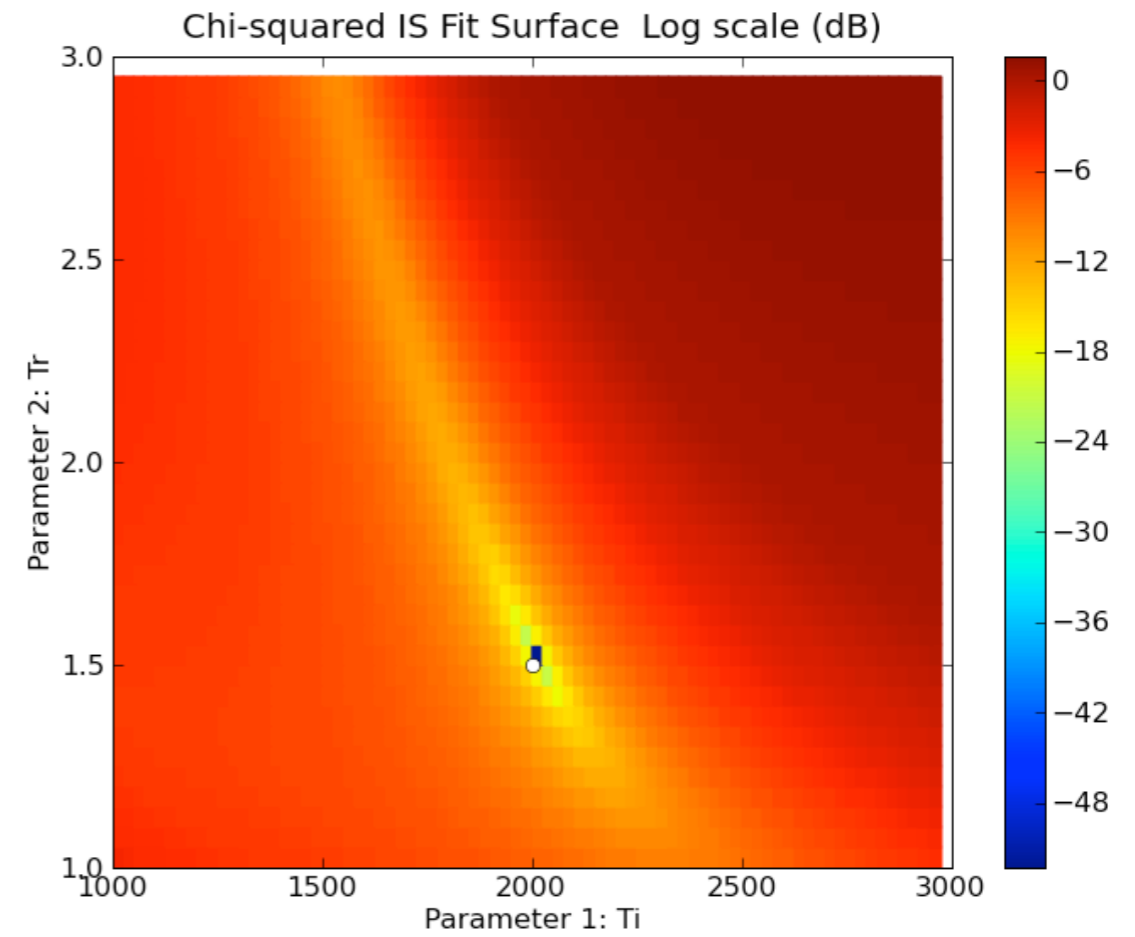
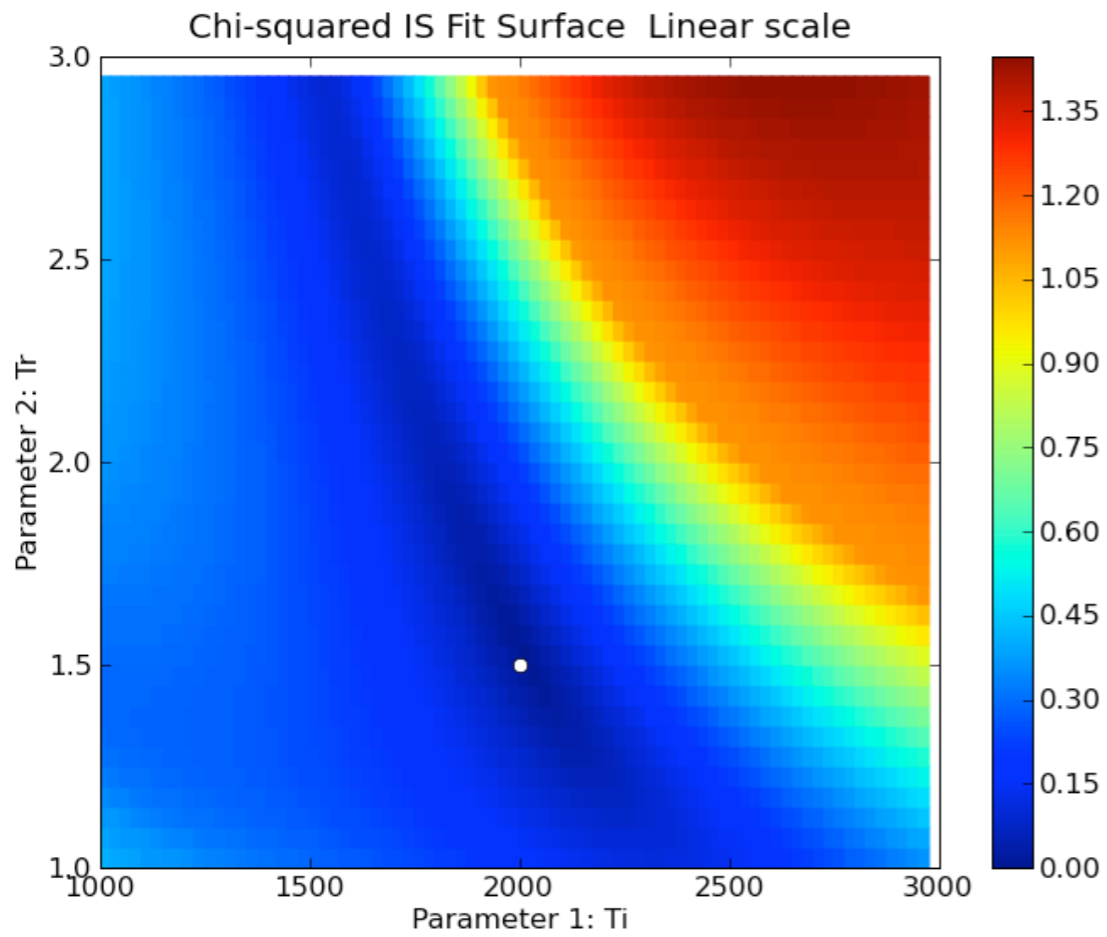
Parabola
 $y = 0.5 x^2 + 2 x + 3$
 Slope, intercept fit
 No noise



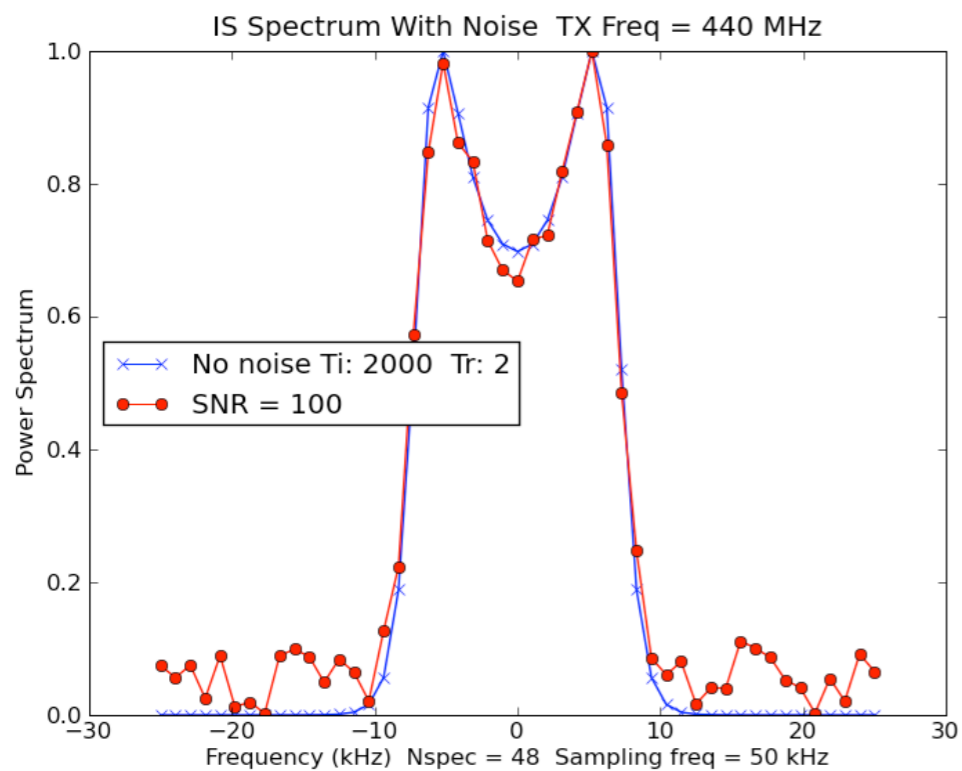
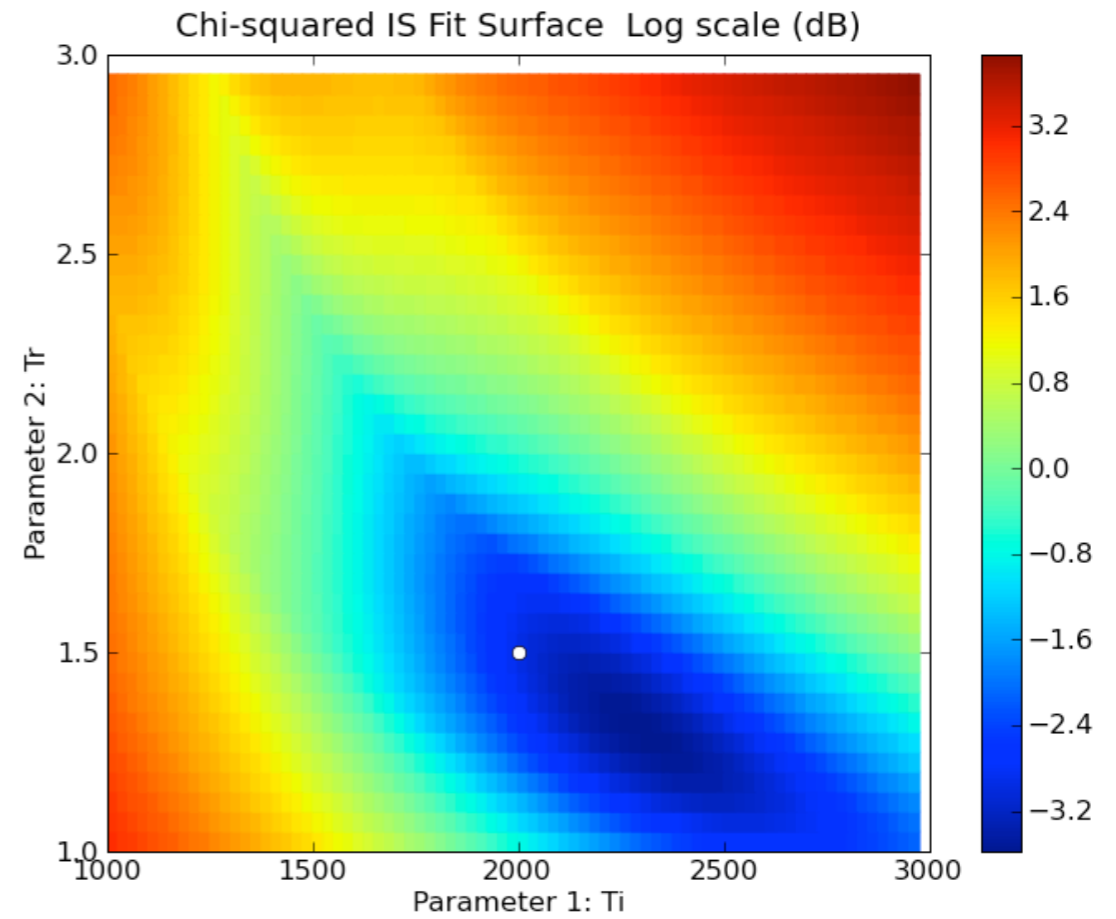
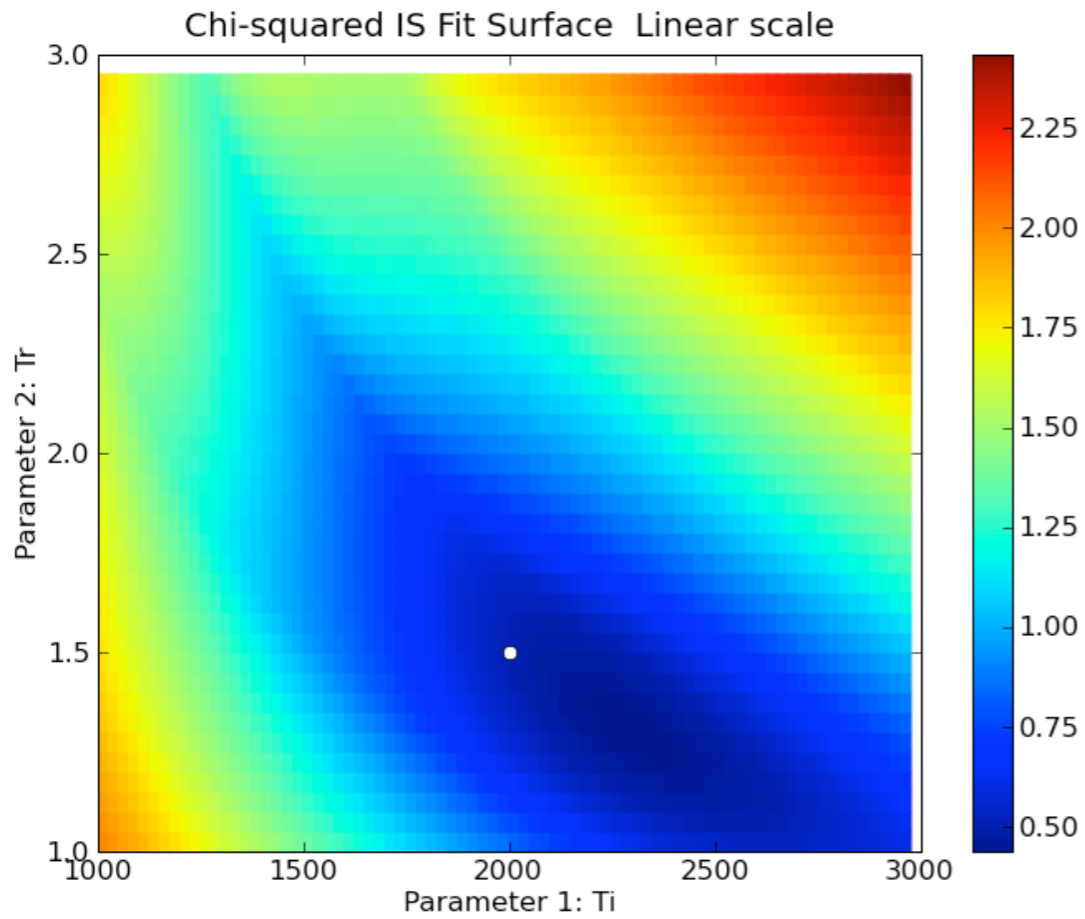
Parabola
 $y = 0.5 x^2 + 2 x + 3$
 Slope, intercept fit
 Noisy



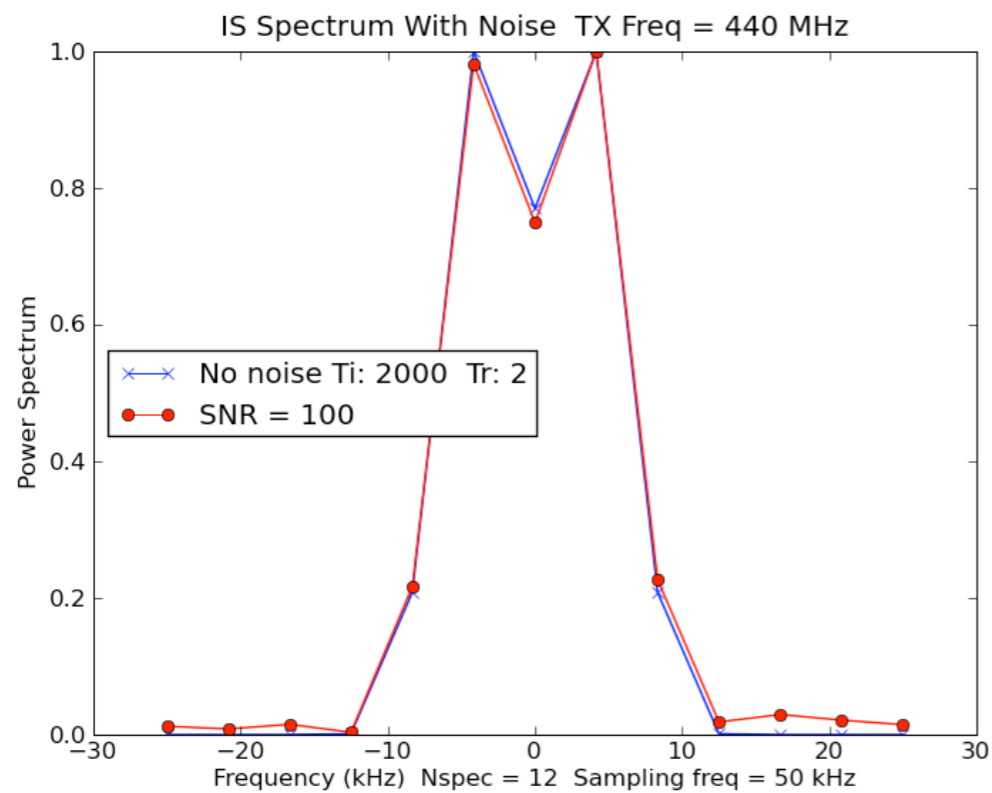
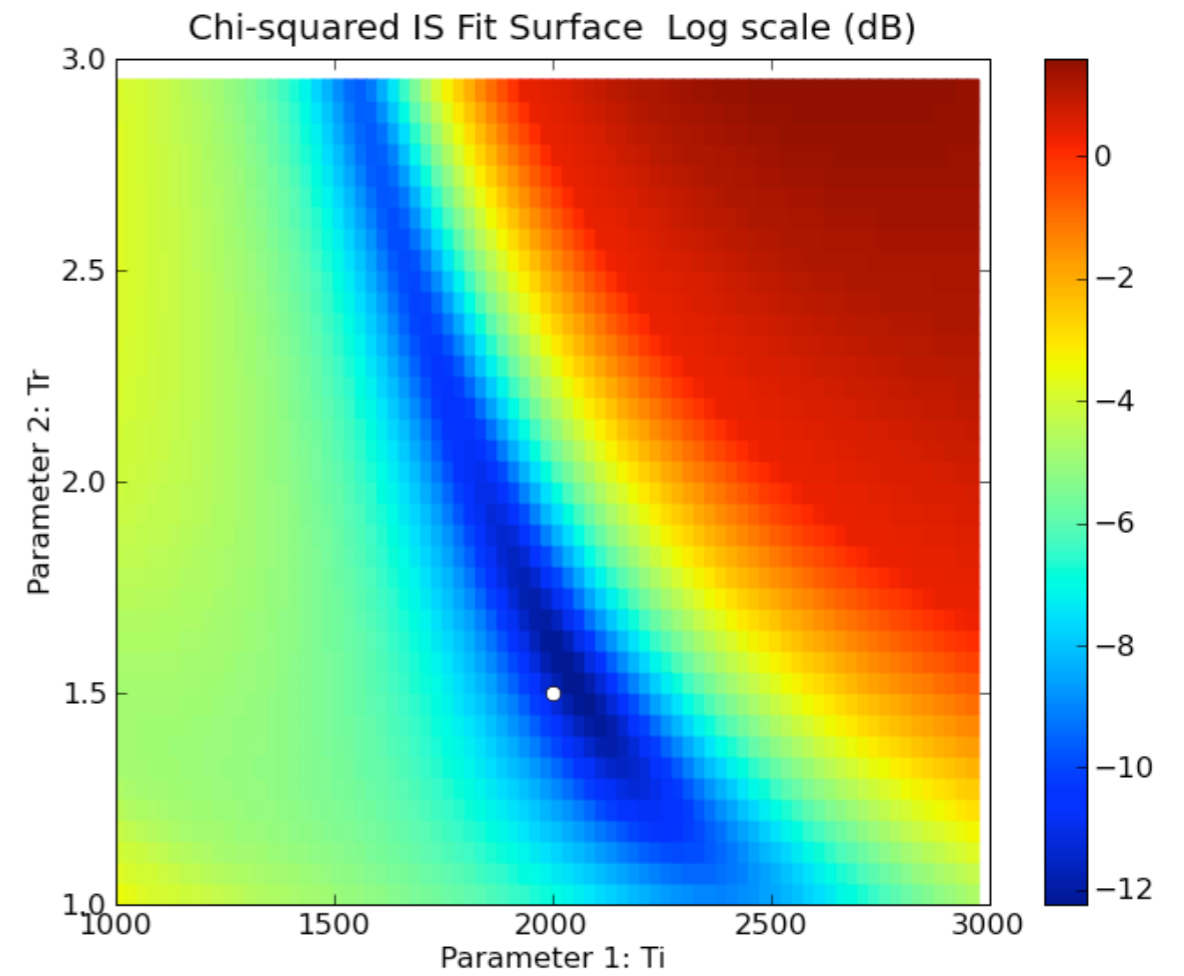
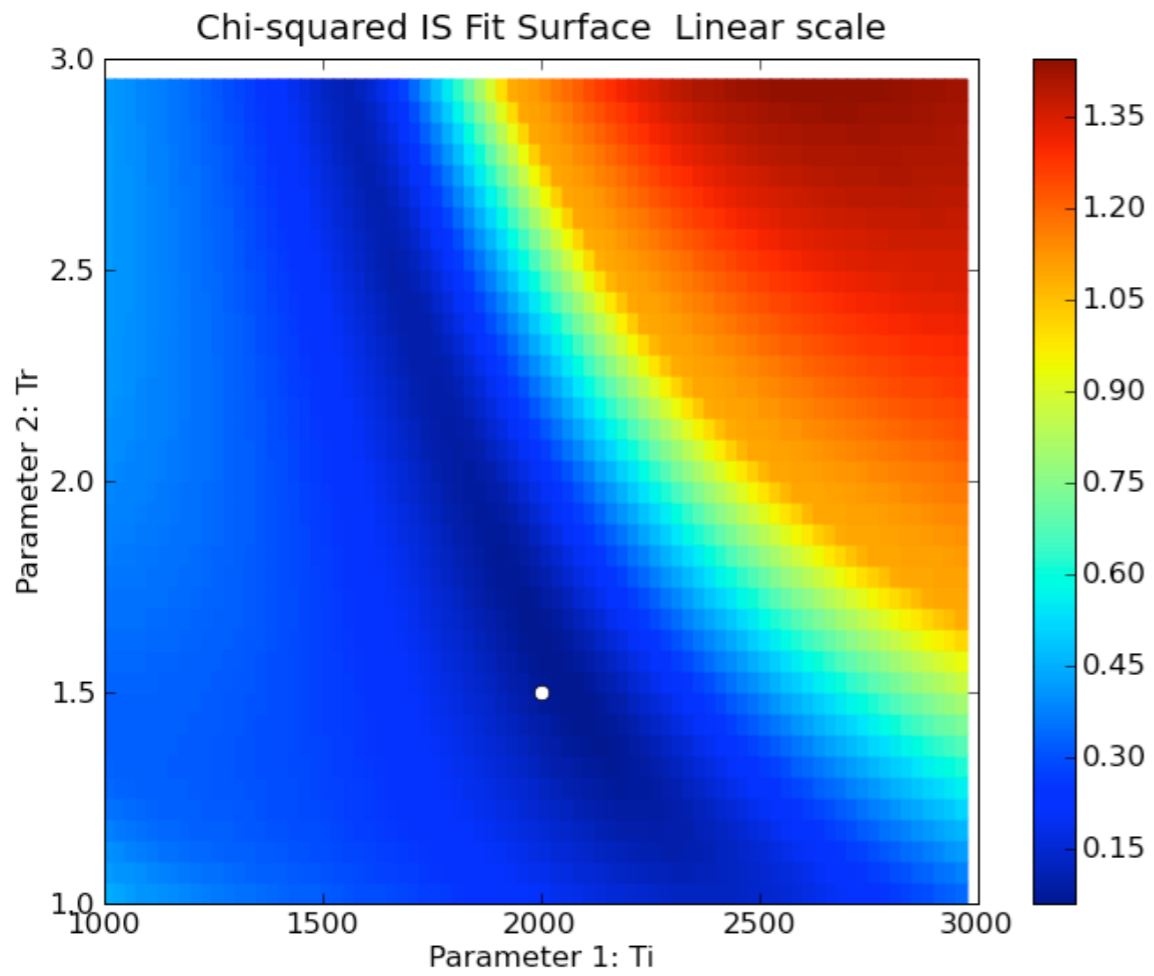
440 MHz IS Spectrum
 Ti/Tr space
 Ti = 2000 Tr = 2
 No noise



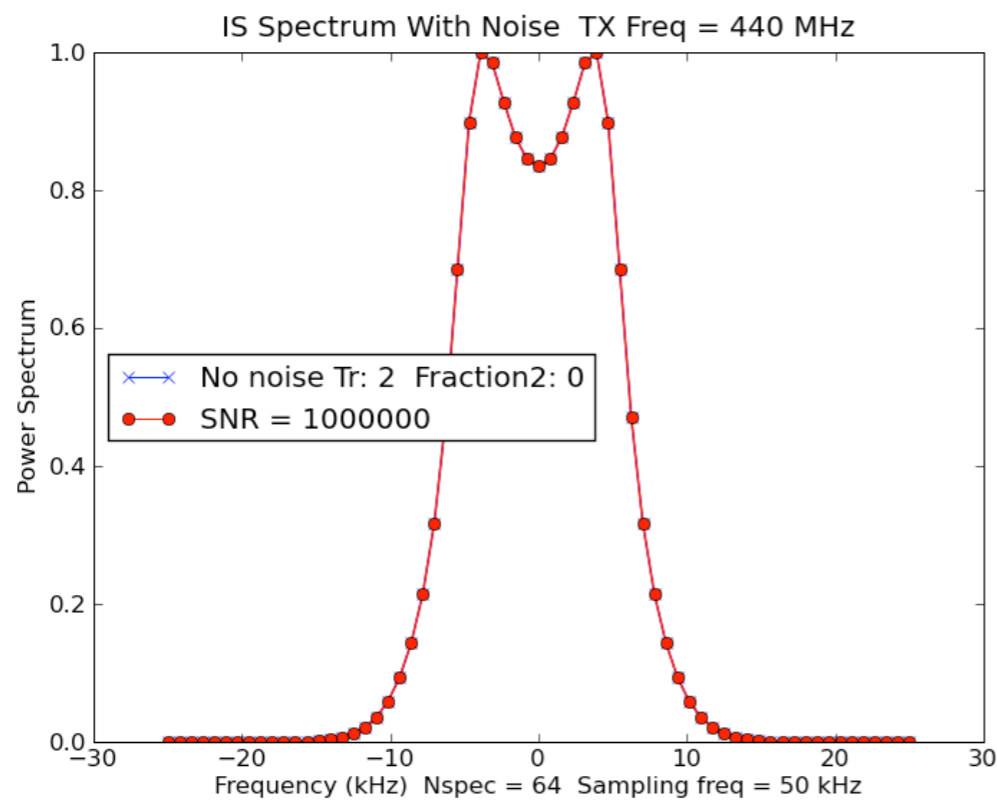
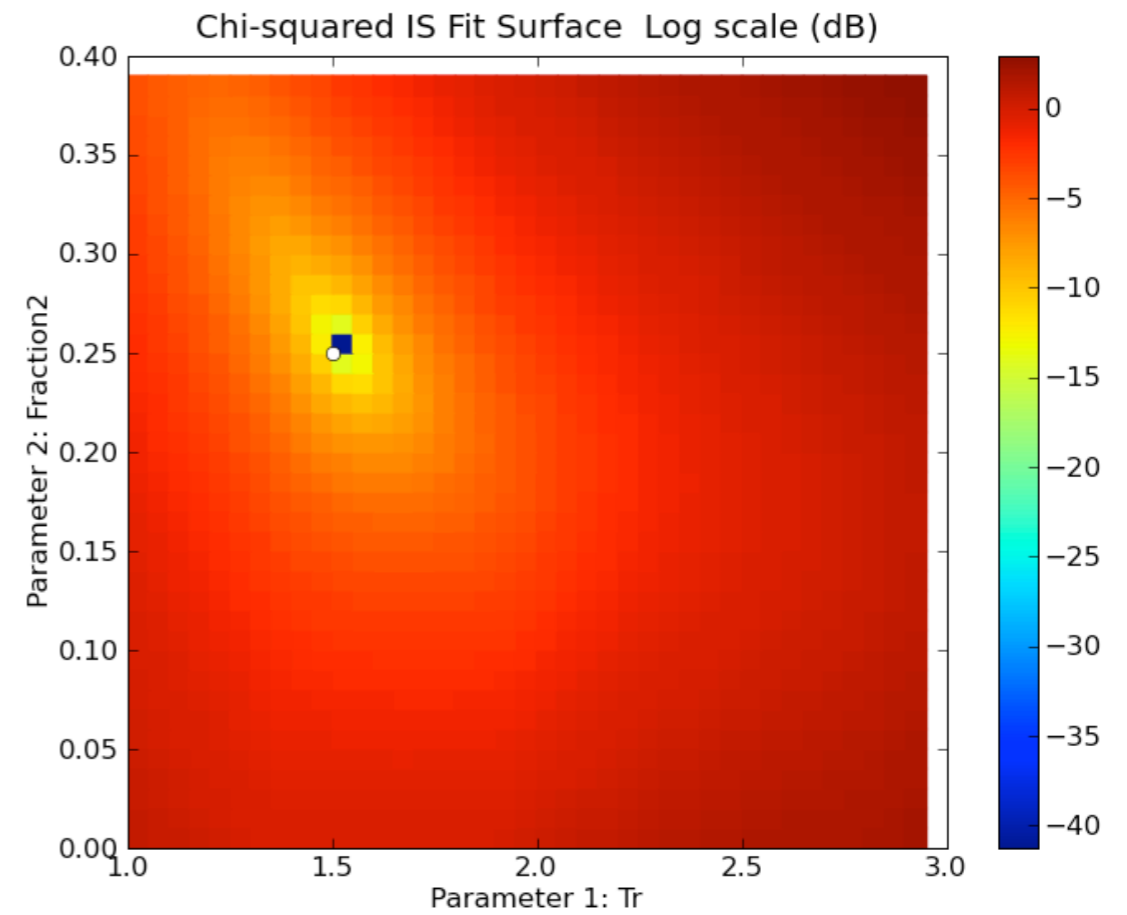
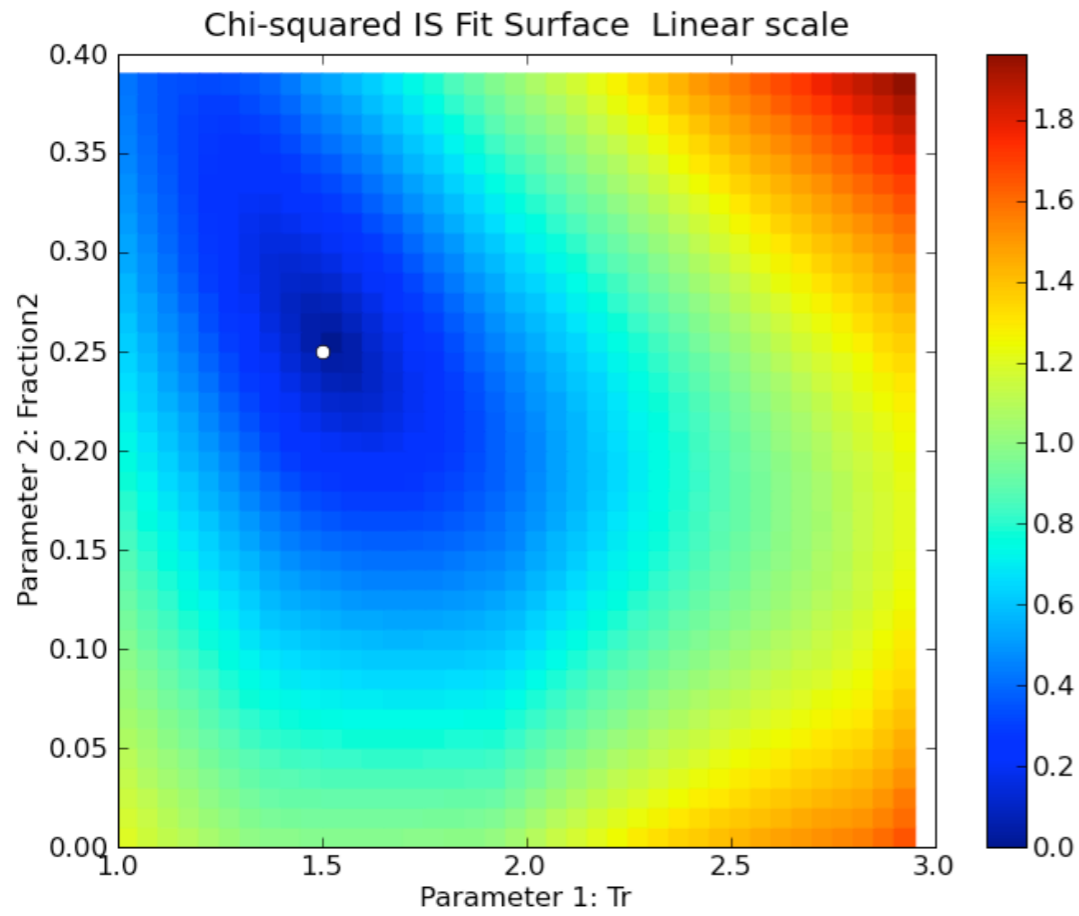
440 MHz IS Spectrum
 Ti/Tr space
 Ti = 2000 Tr = 2
 Poor sampling



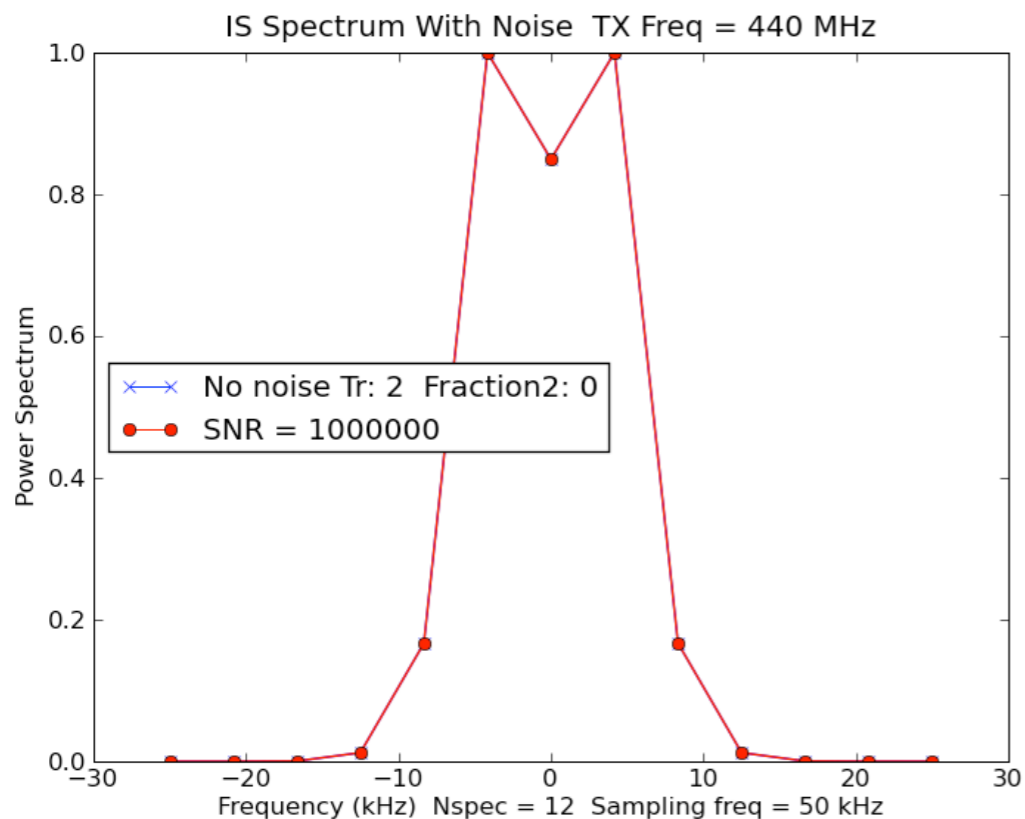
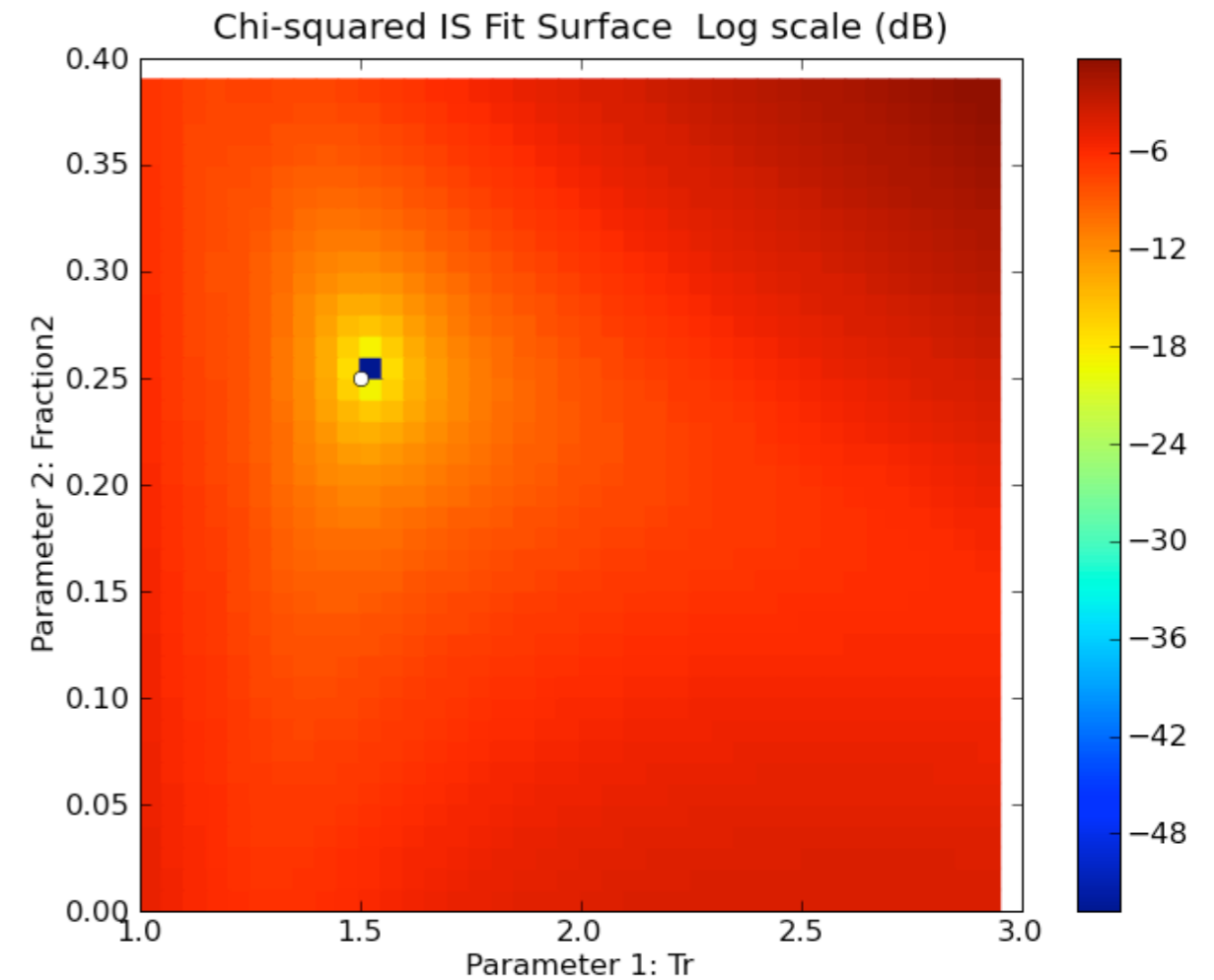
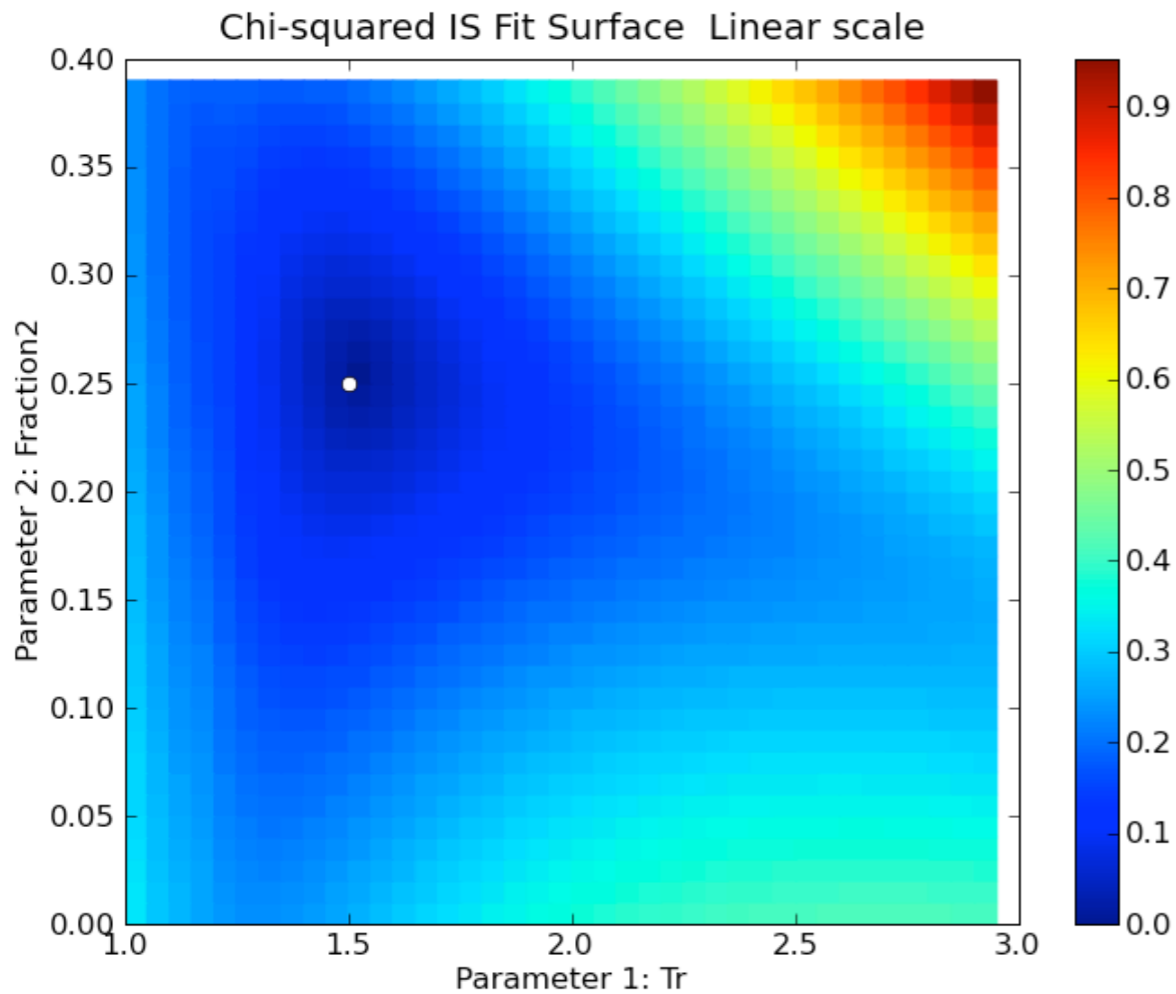
440 MHz IS Spectrum
 Ti/Tr space
 Ti = 2000 Tr = 2
 Noisy



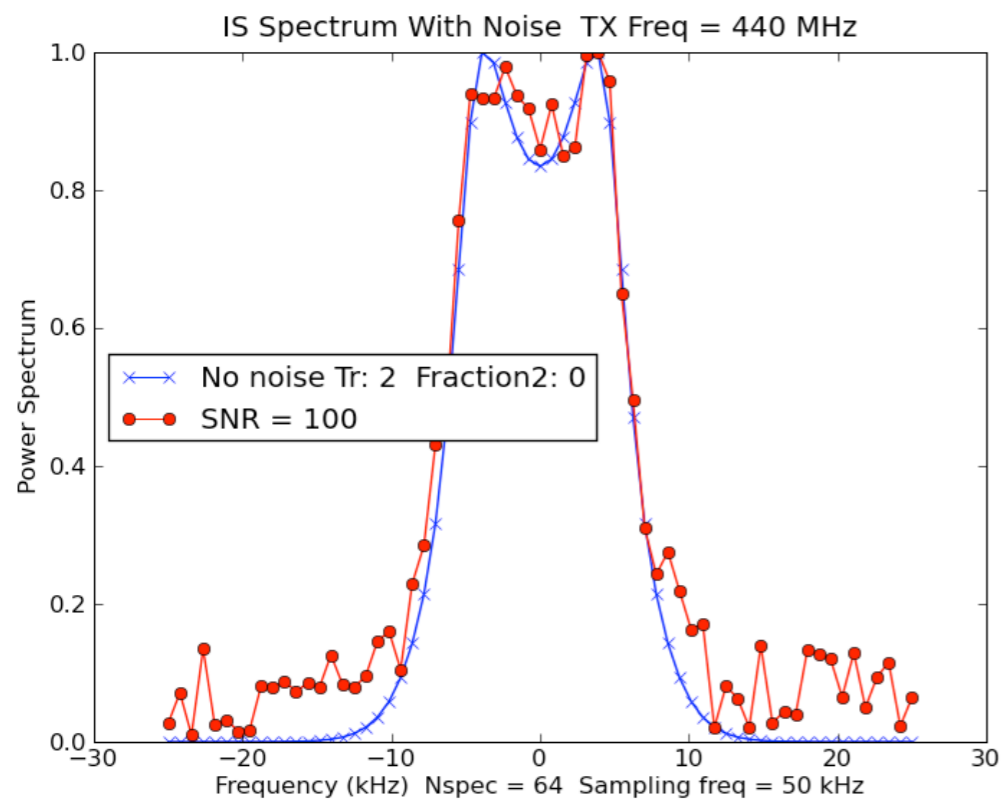
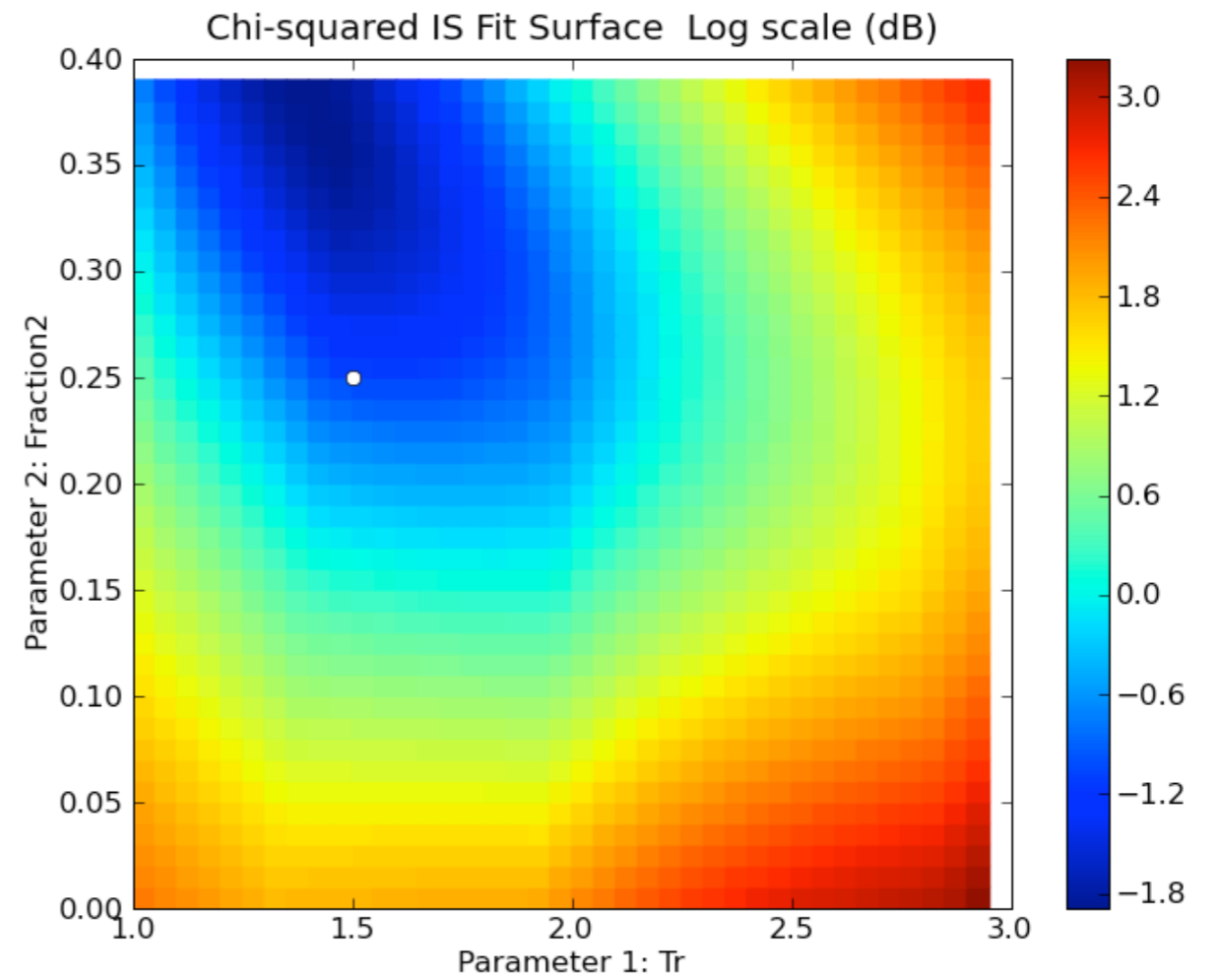
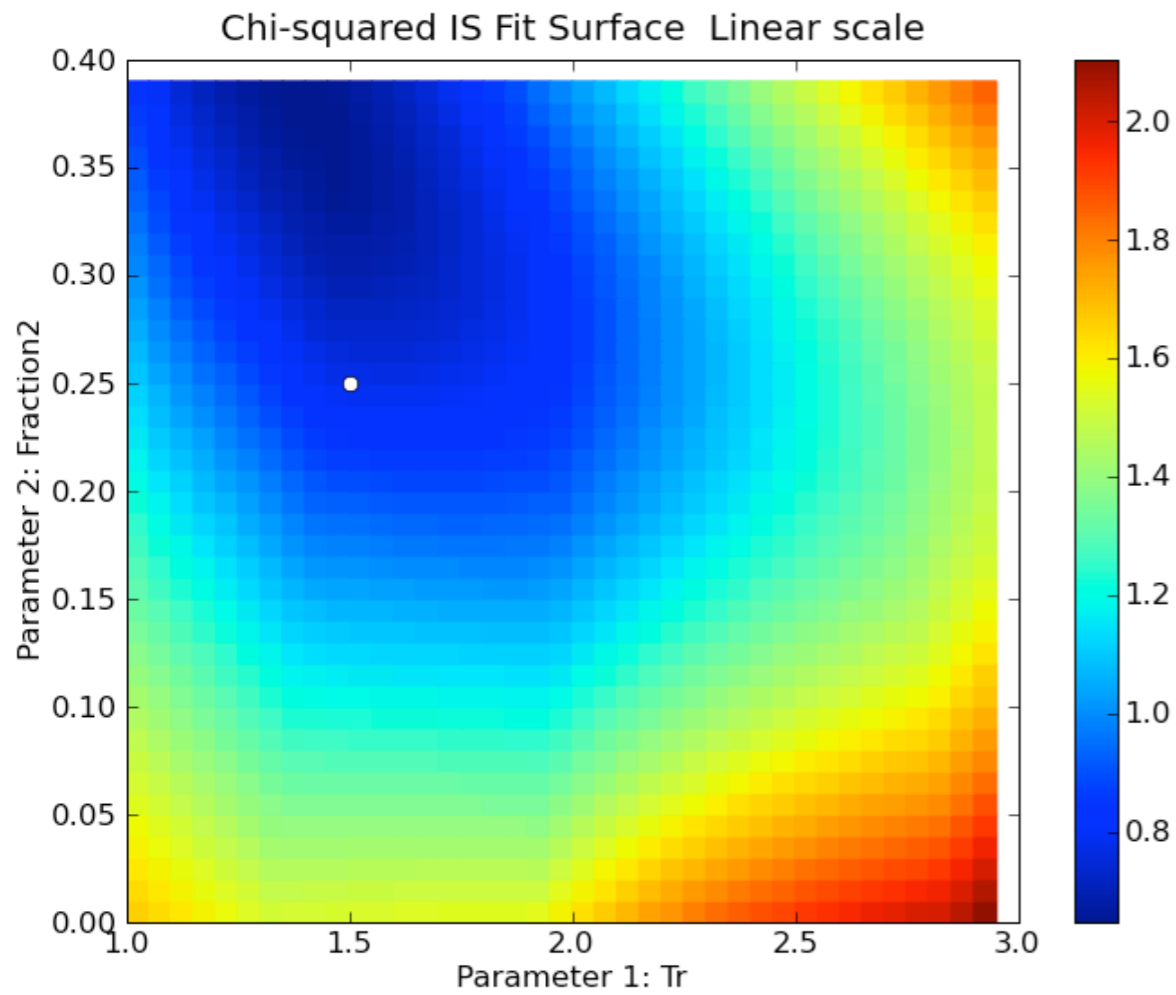
440 MHz IS Spectrum
 Ti/Tr space
 Ti = 2000 Tr = 2
 Noisy, poor sampling



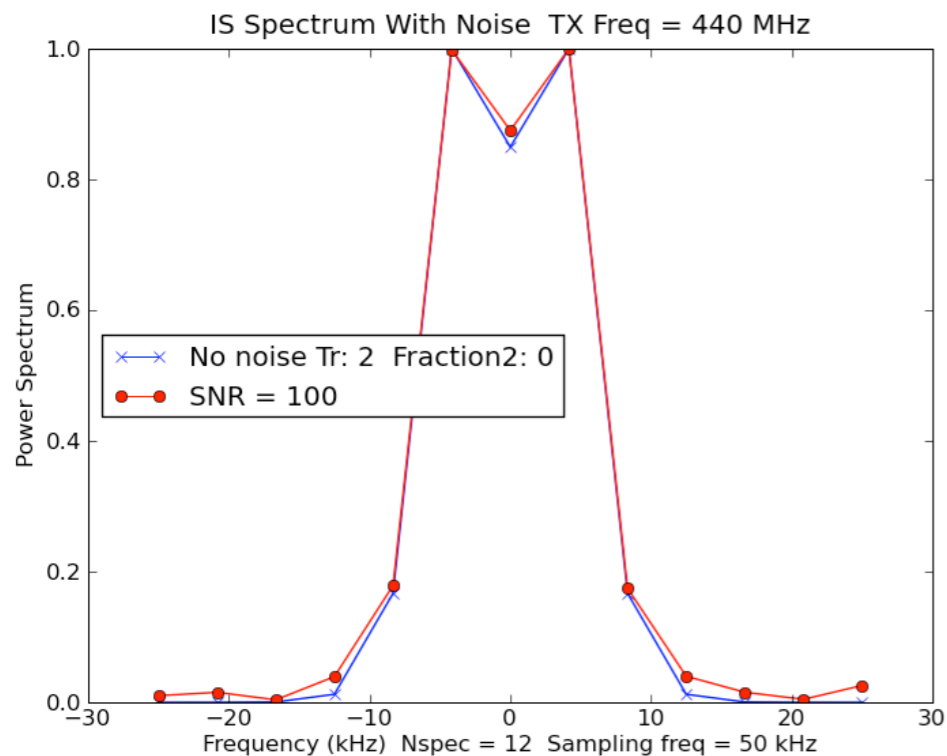
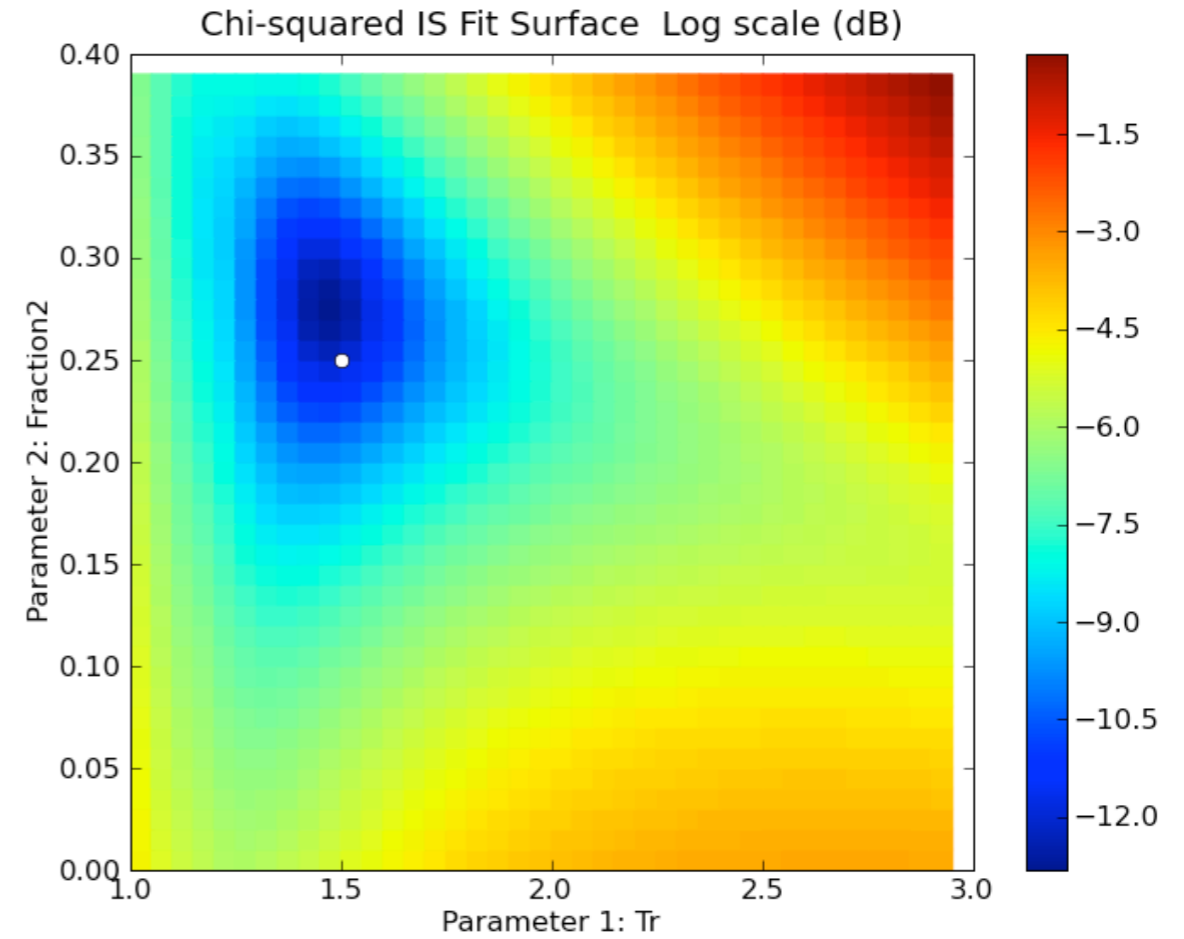
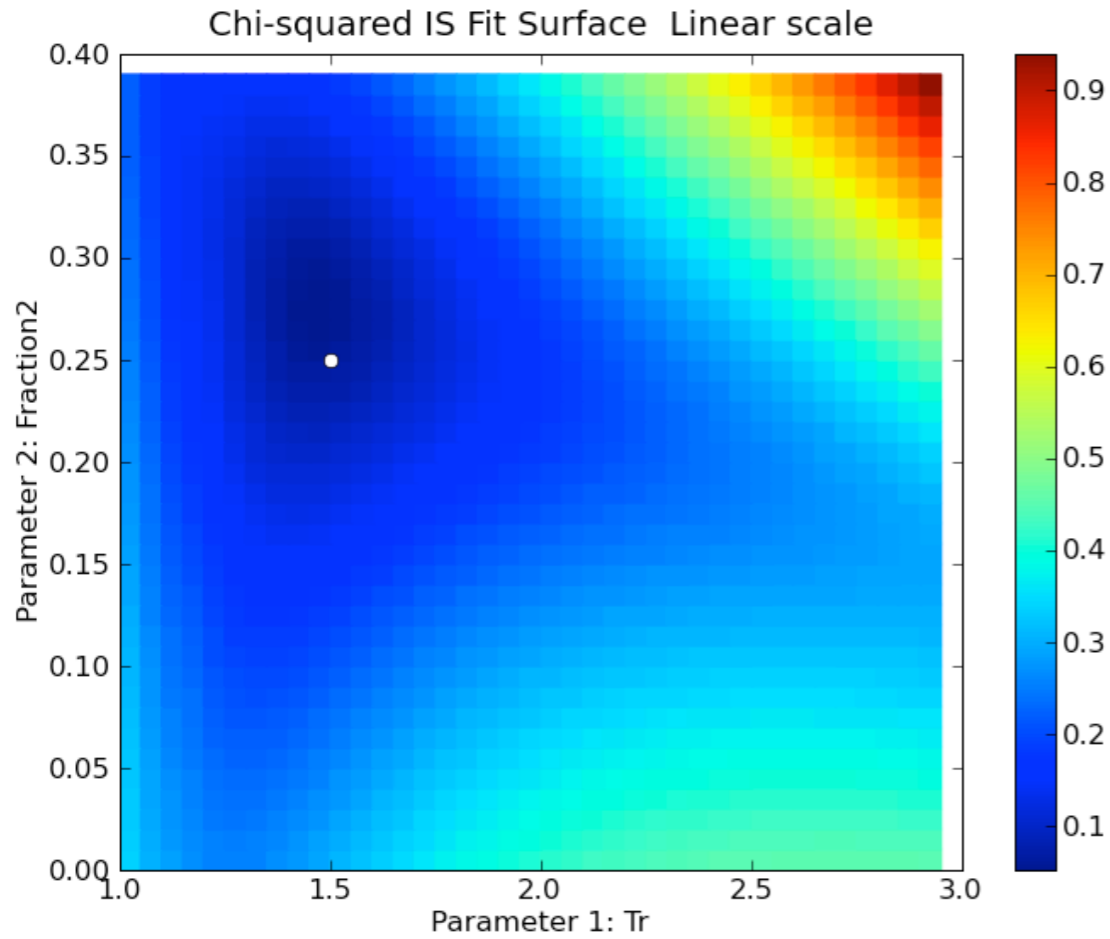
440 MHz IS Spectrum
 Tr / frac [He+] space
 Tr = 1.5 Ti = 1000 O+/He+ mix
 frac[He+]=0.25
 No noise



440 MHz IS Spectrum
 Tr / frac [He+] space
 Tr = 1.5 Ti = 1000 O+/He+ mix
 frac[He+]=0.25
 Poor sampling

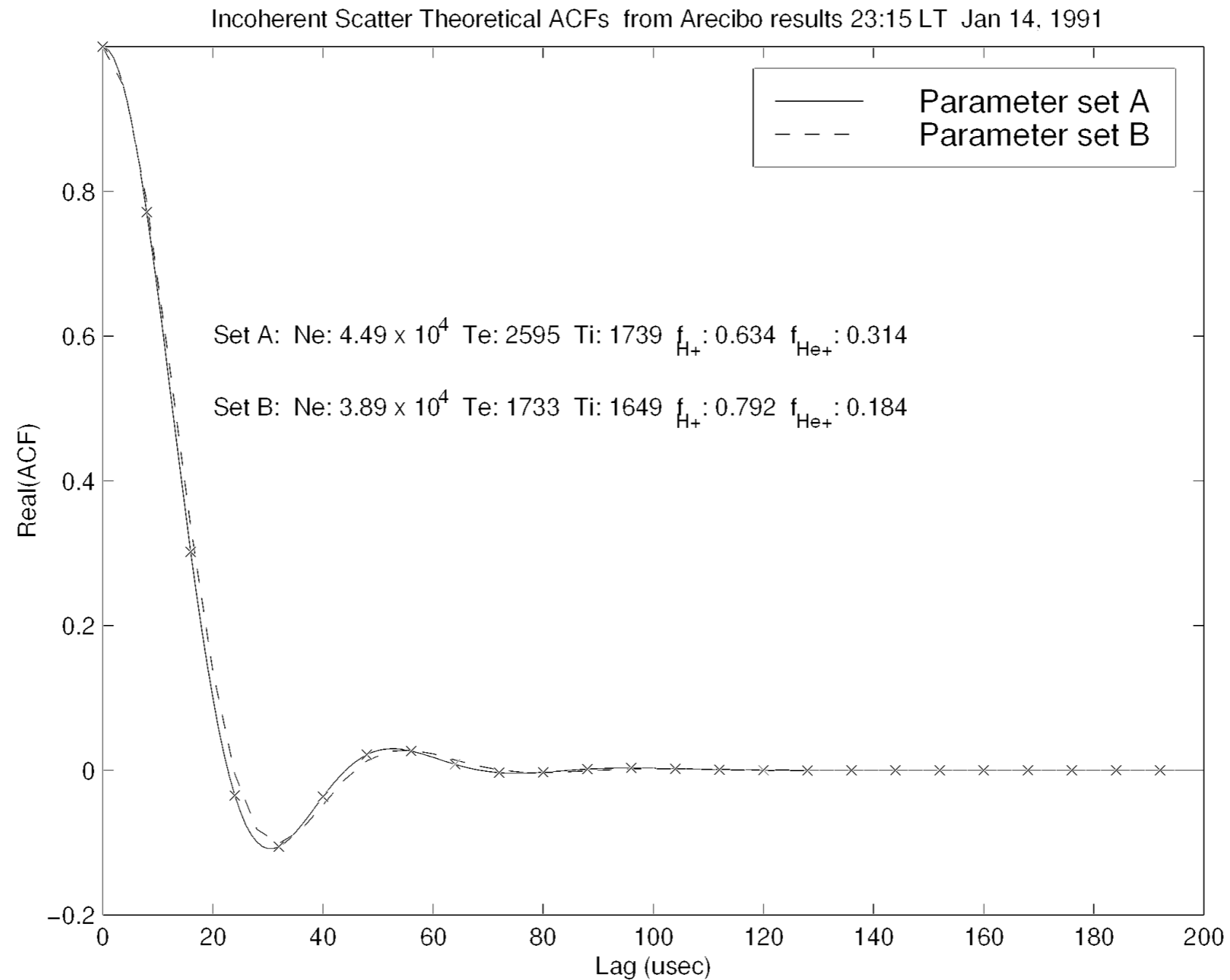


440 MHz IS Spectrum
 Tr / frac [He⁺] space
 Tr = 1.5 Ti = 1000 O⁺/He⁺ mix
 frac[He⁺]=0.25
 Noisy



440 MHz IS Spectrum
 Tr / frac [He⁺] space
 Tr = 1.5 Ti = 1000 O⁺/He⁺ mix
 frac[He⁺]=0.25
 Poor sampling, noisy

Arecibo Topside: O⁺/H⁺/He⁺/Te/Ti ambiguity



Eigenvalues of Hessian matrix (2nd derivative of min fn) has insights on parameter ambiguities

Table 5.1: Fit results and uncertainty values at 923 km for conditions over Arecibo at 20:41 LT on January 14, 1991. The most ill-defined parameter vector is found from the Hessian matrix eigenvector with the smallest eigenvalue.

Fitter results:

	Best-fit results	Uncertainty
N_e	6.41×10^4	7.39×10^3
T_e	2285	41.3
T_i	2223	23.4
f_{H^+}	0.490	0.00483
f_{He^+}	0.159	0.00341

Correlations between pairs of parameters:

Param Pair	Correlation	Param Pair	Correlation
$[N_e, T_e]$	0.958	$[T_e, f_{H^+}]$	-0.916
$[N_e, T_i]$	-0.649	$[T_e, f_{He^+}]$	-0.401
$[N_e, f_{H^+}]$	-0.849	$[T_i, f_{H^+}]$	0.414
$[N_e, f_{He^+}]$	-0.511	$[T_i, f_{He^+}]$	0.515
$[T_e, T_i]$	-0.440	$[f_{H^+}, f_{He^+}]$	0.099

Most ill-defined parameter combination:

$$+0.998 (N_e) + 0.0527 (T_e) - 0.0202 (T_i) + 5.46 \times 10^{-6} (f_{H^+}) - 2.32 \times 10^{-6} (f_{He^+})$$

Improving the fit: adding constraints

Bayesian statistics: add apriori knowledge to stabilize fit.

Can come from other instruments, or from data at other altitudes/times.

One formulation: minimize

$$\chi^2 = \chi_{data}^2 + \chi_{apriori}^2$$

Here, the apriori information adds a cost for solutions which wander too far from the apriori knowledge. (DANGER!)

Many implementations in our field:

- Constrained temperature profiles
- Vector velocity fits
- Full profile analysis
- Regularization
- Etc.

Unconstrained Arecibo topside analysis

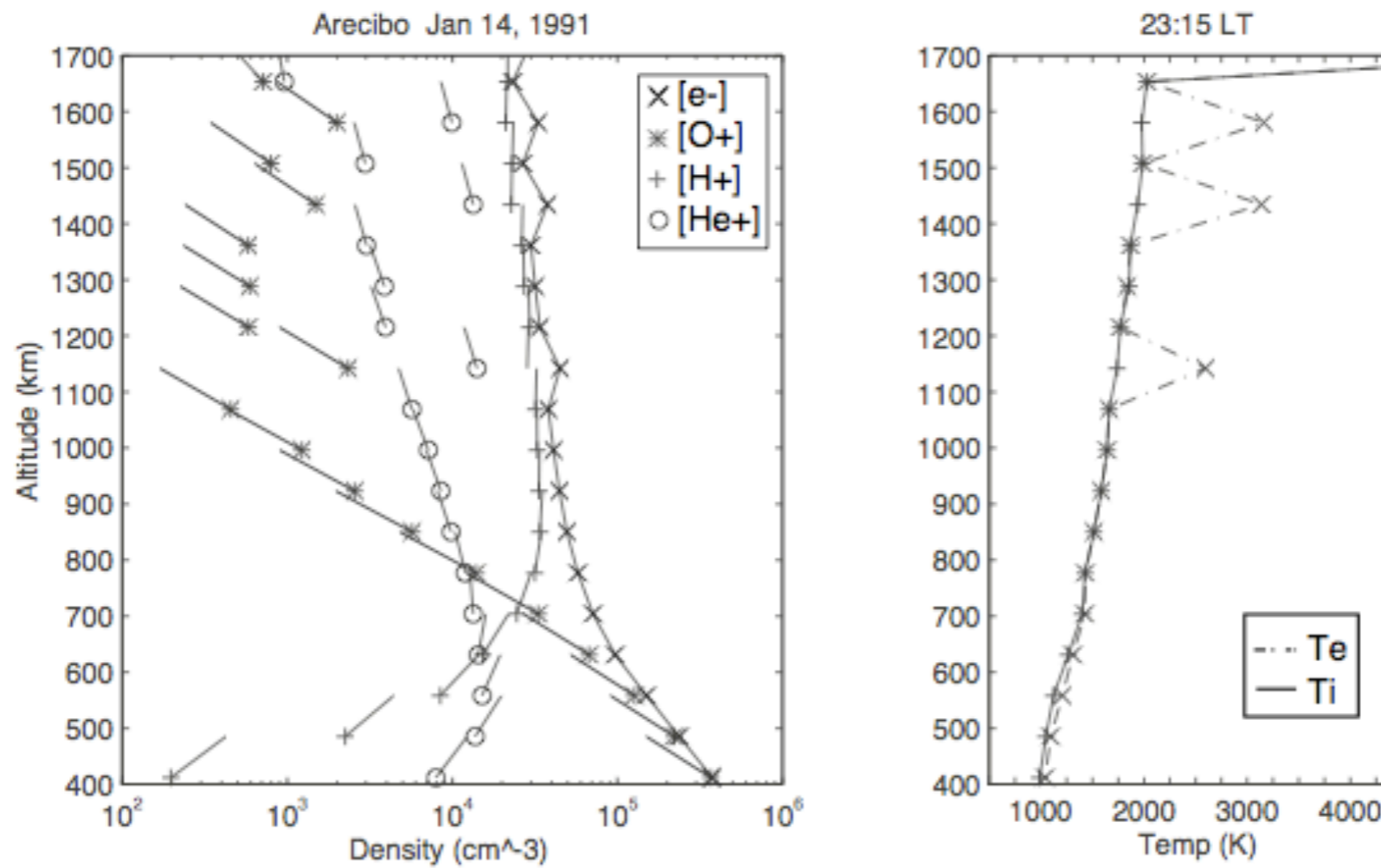


Figure 5.3: Density and temperature values as a function of altitude over Arecibo at 23:15 LT on January 14, 1991, using a 15 minute integration period. The lines emanating from each density value plotted in the left hand panel are predictions of density variation based on multicomponent diffusive equilibrium. There are clear inconsistencies in parameter values at several altitudes.

Erickson and Swartz, 1995;
Erickson, 1998

Constrained Arecibo topside analysis: Temperature gradient restriction

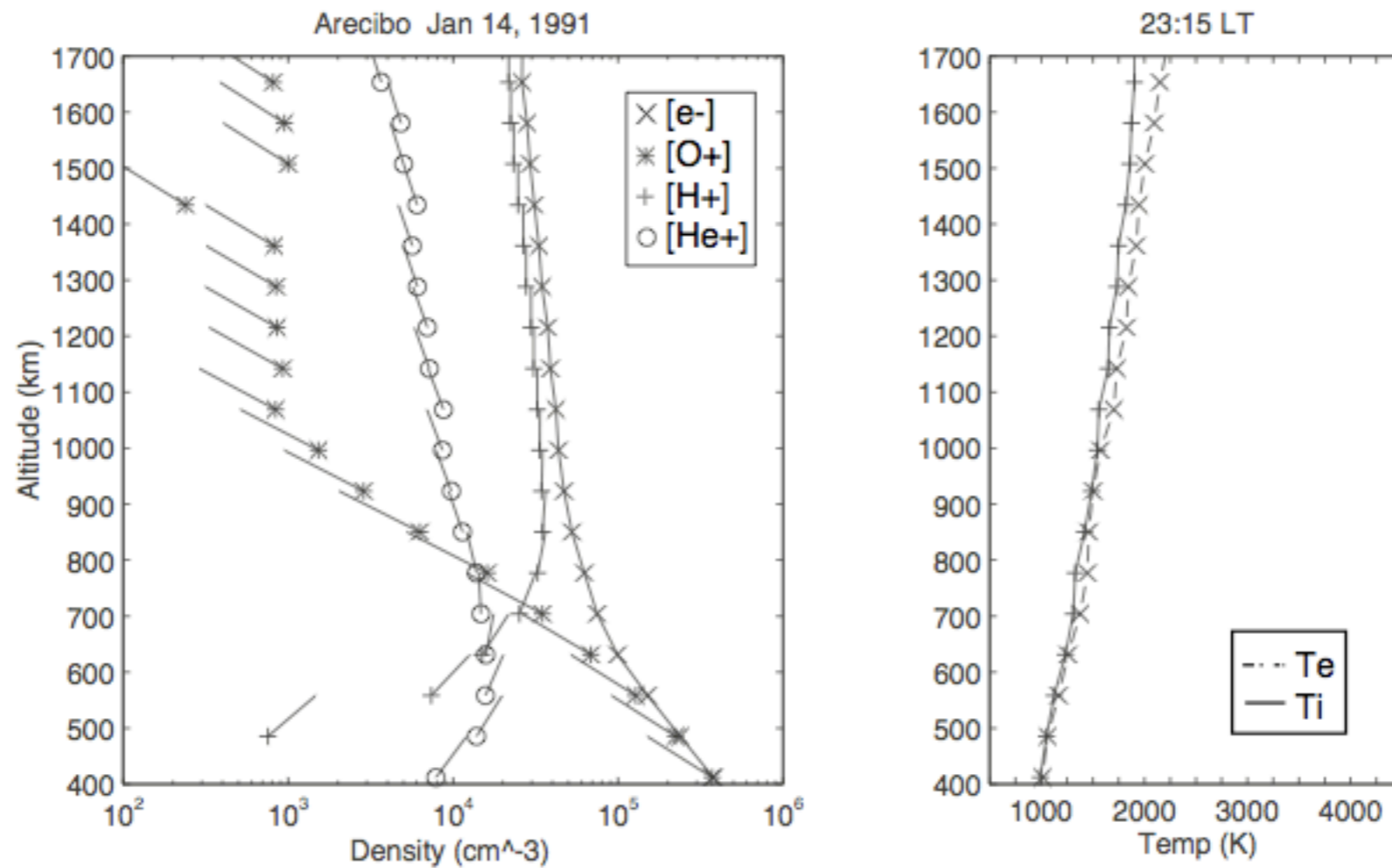


Figure 5.5: Density and temperature values as a function of altitude over Arecibo at 23:15 LT on January 14, 1991, using a 15 minute integration period. The lines emanating from each density value plotted in the left hand panel are predictions of density variation based on multicomponent diffusive equilibrium. The smooth temperature constraint results in a consistent set of fitted parameters.

Erickson and Swartz, 1995;
Erickson, 1998

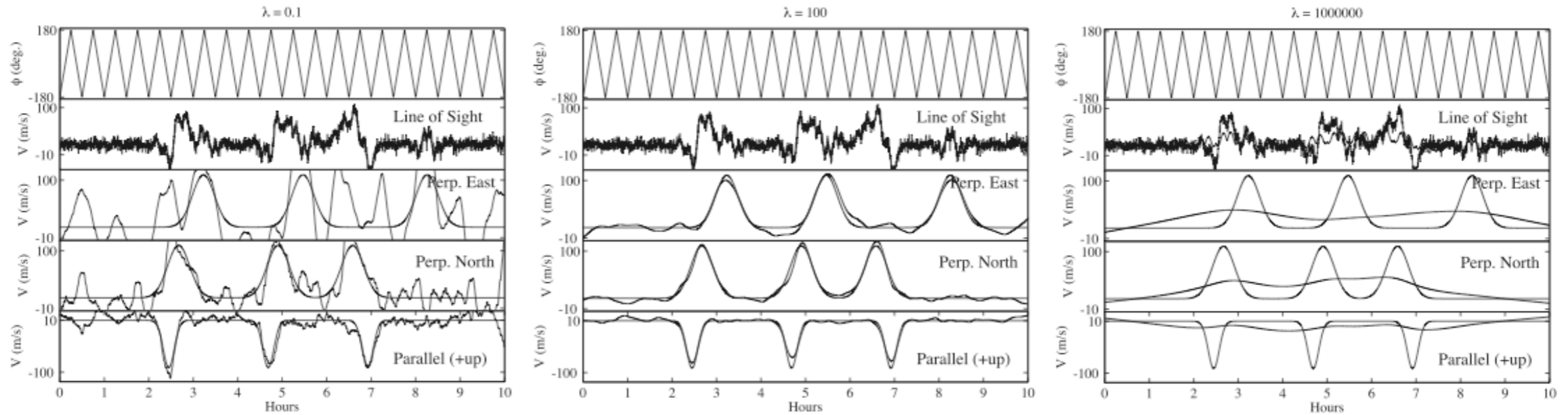


Figure 3. Vector velocity input-output comparison using a simulation assuming a single beam and applying the method of regularization. The panels on the left show the results for a small value of λ . The panels on the center were obtained from a simulation with an optimal value of λ , while the panels on the right correspond to a case with too much λ .

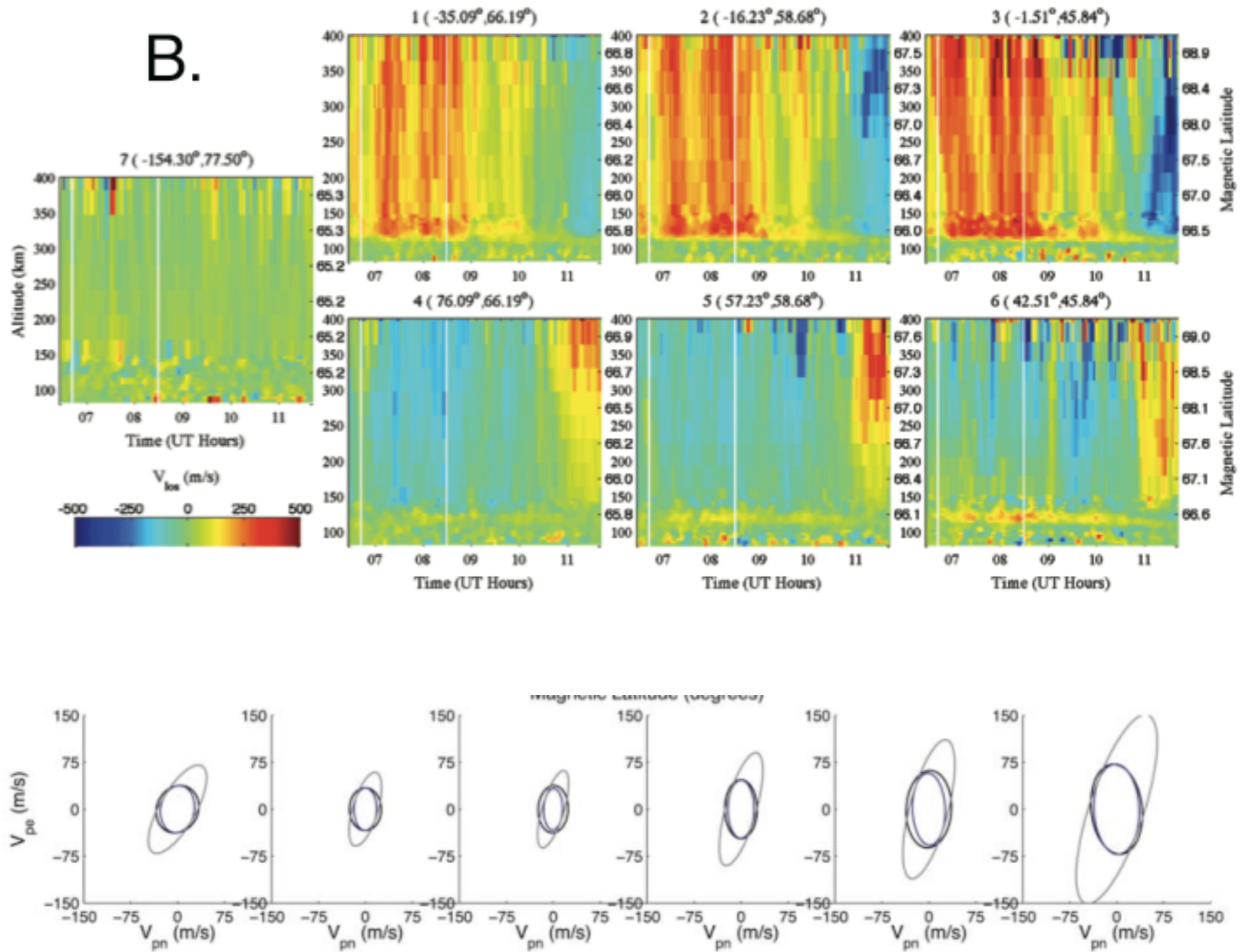
$$\begin{bmatrix} V_{pn} \\ V_{pe} \\ V_{par} \end{bmatrix} = \begin{bmatrix} -\cos \delta \sin I & \sin \delta \sin I & \cos I \\ \sin \delta & \cos \delta & 0 \\ \cos \delta \cos I & -\sin \delta \cos I & \sin I \end{bmatrix} \begin{bmatrix} v_x \\ v_y \\ v_z \end{bmatrix}.$$

$$\begin{bmatrix} V_{LOS(1)} \\ \vdots \\ V_{LOS(n)} \end{bmatrix} = \begin{bmatrix} -\cos \phi_1 \sin \theta & \sin \phi_1 \sin \theta & \cos \theta \\ \vdots & \vdots & \vdots \\ -\cos \phi_n \sin \theta & \sin \phi_n \sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} v_x \\ v_y \\ v_z \end{bmatrix}$$

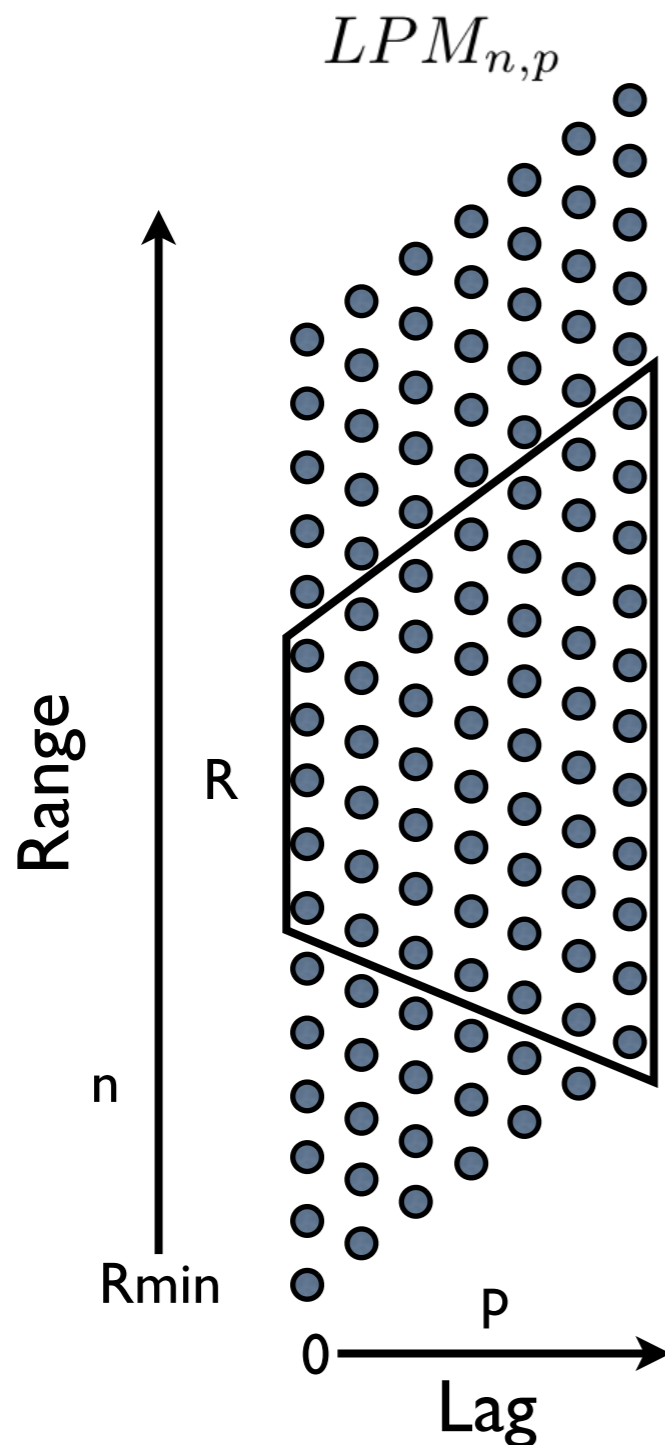
Arecibo linear regularization of line-of-sight velocities for full vector derivation

Sulzer et al, 2005

Poker Flat ISR E region winds, electric fields (covariances included)



Summation Rules: Improving Statistics for LPM -> ACF

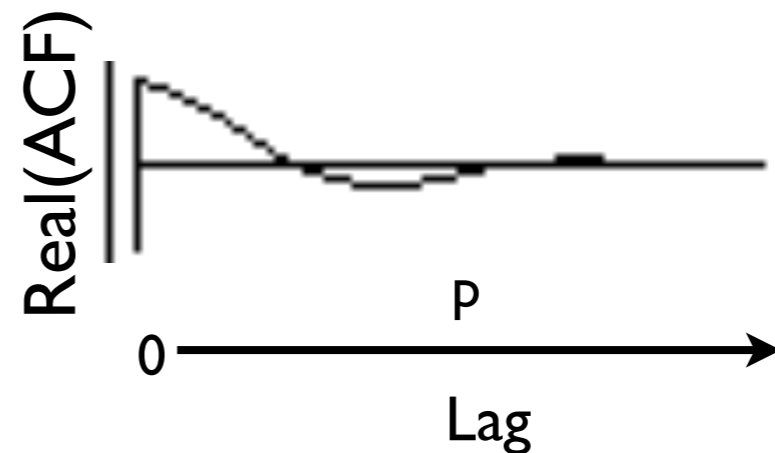


Trapezoidal summation rule

NB: Greatly improved statistics at longer lags comes at expense of spatial resolution!

Lossy operation: information is lost.

$$\rho(R; \tau = p\Delta T)$$



Remember this?

Direct LPM Fitting: Use More of the Information Available

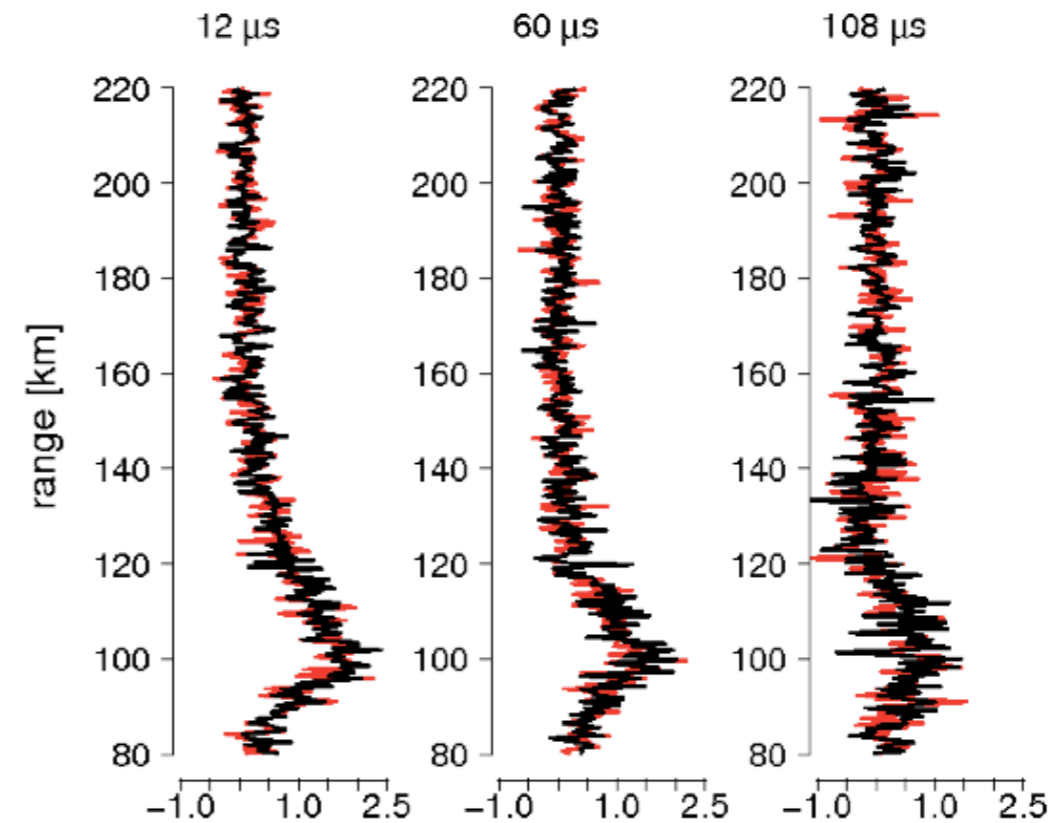
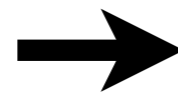
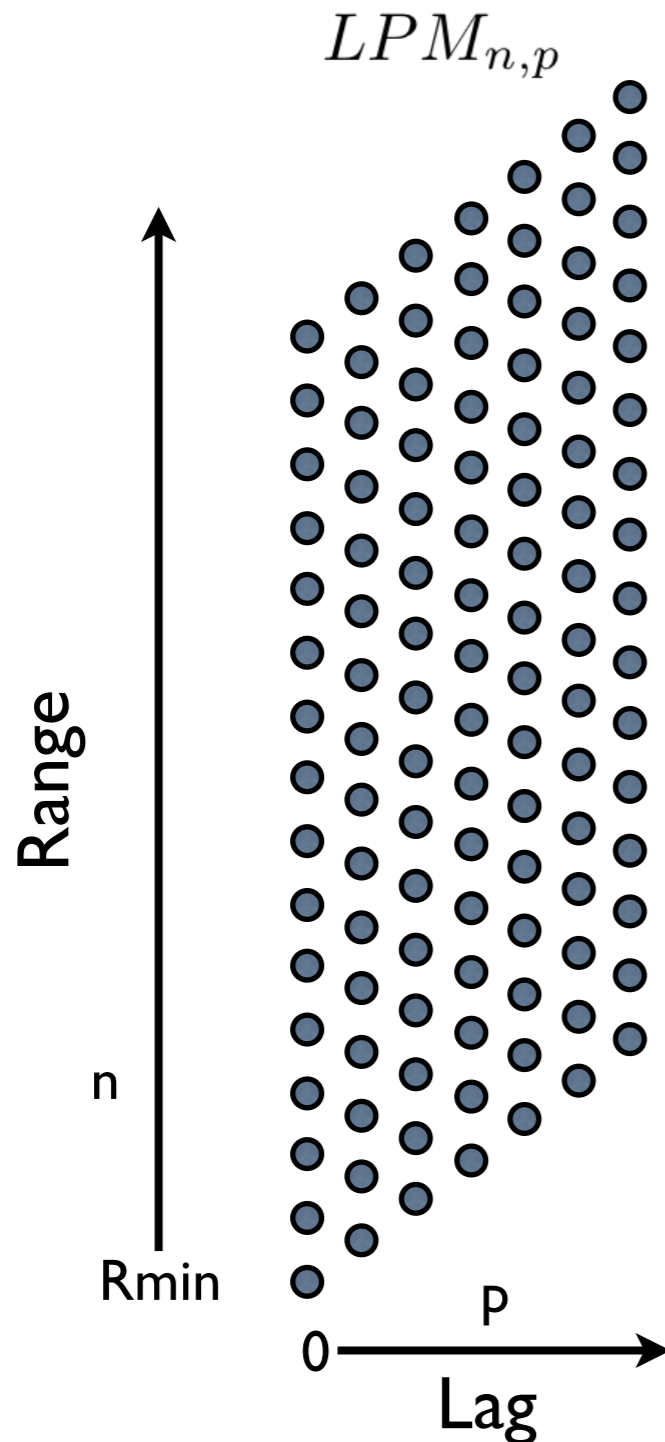


Fig. 3. Real parts of sample lag profiles at 12, 60 and 108 μ s from 25 November 2006. The decoding results are shown by red line and the inversion results by black line. The integration time is 6 s, the range resolution is 450 m and the ACF value is given in arbitrary units.

LPM inversion: First remove instrument effects, then fit each altitude's ACF independently
Virtanen et al 2008

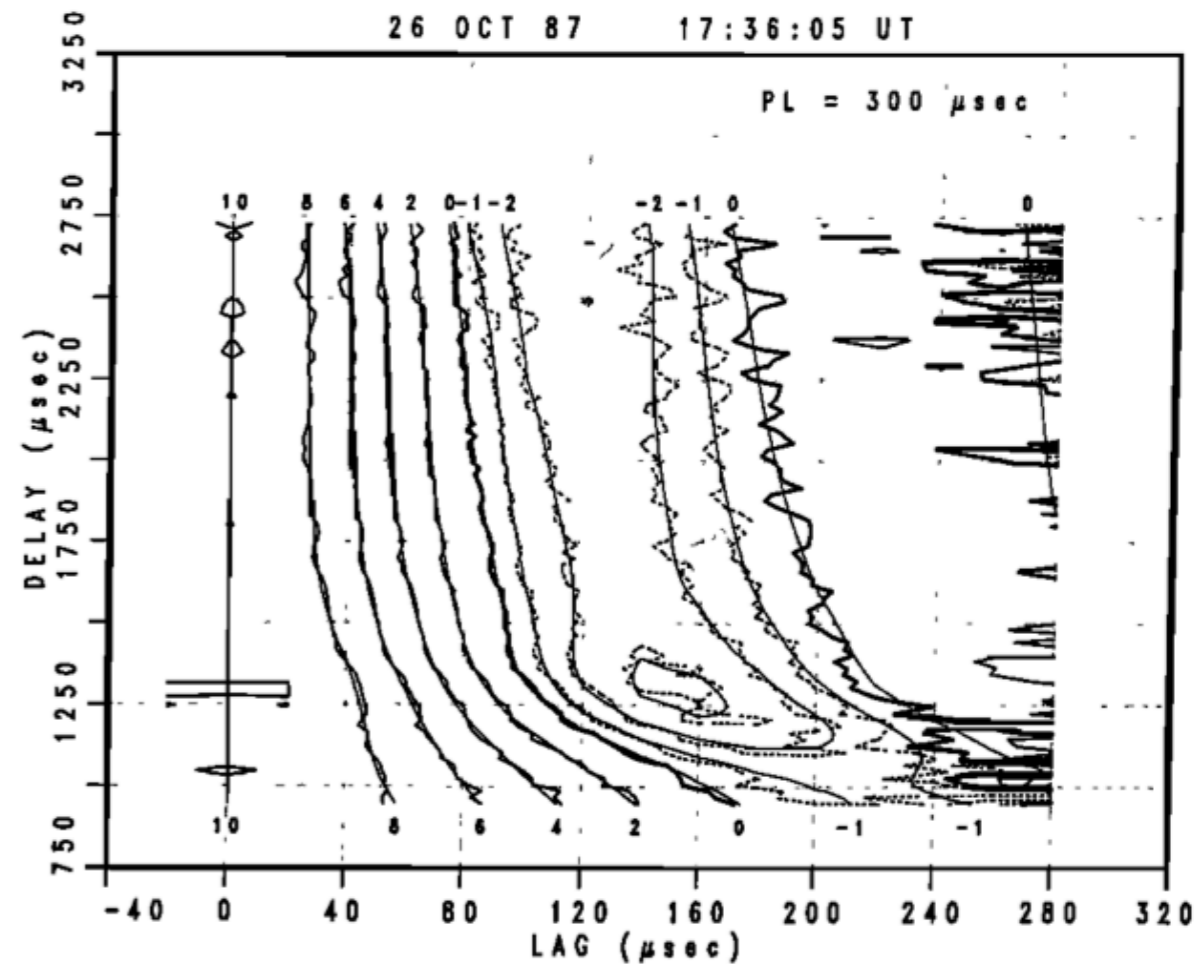
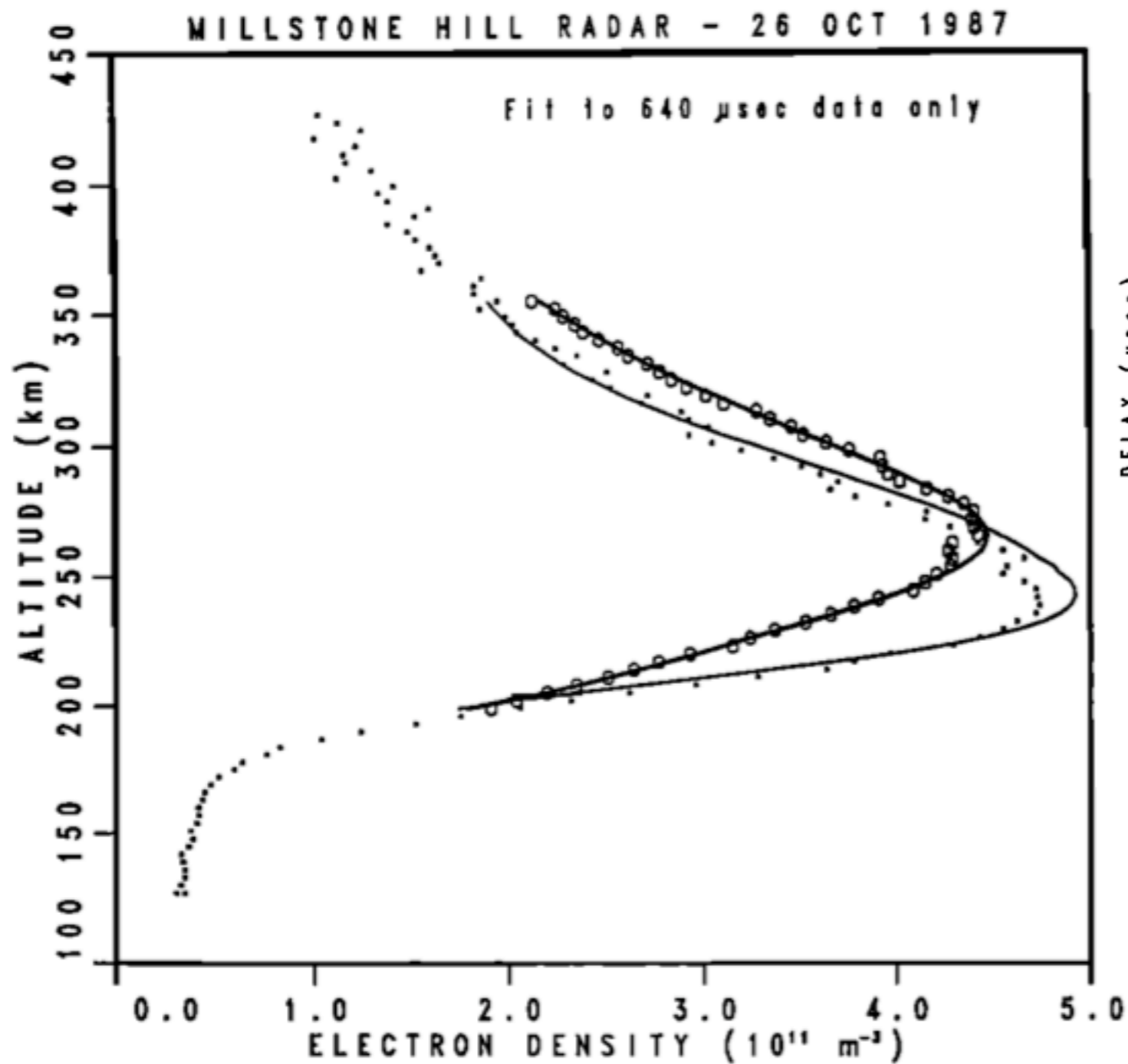


Fig. 7. OASIS power profile derived from measurements made with 640- μs single pulse. The data are shown as hexagons and the fit to the data as a thick line. The deconvolved profile is shown as a thin line and is compared to nearly simultaneous 100- μs data which is shown as dots.

OASIS Full profile analysis

Combines pulses with different resolution
 B-splines used for parameter variation - generate and fit LPMs directly

Holt et al, 1992

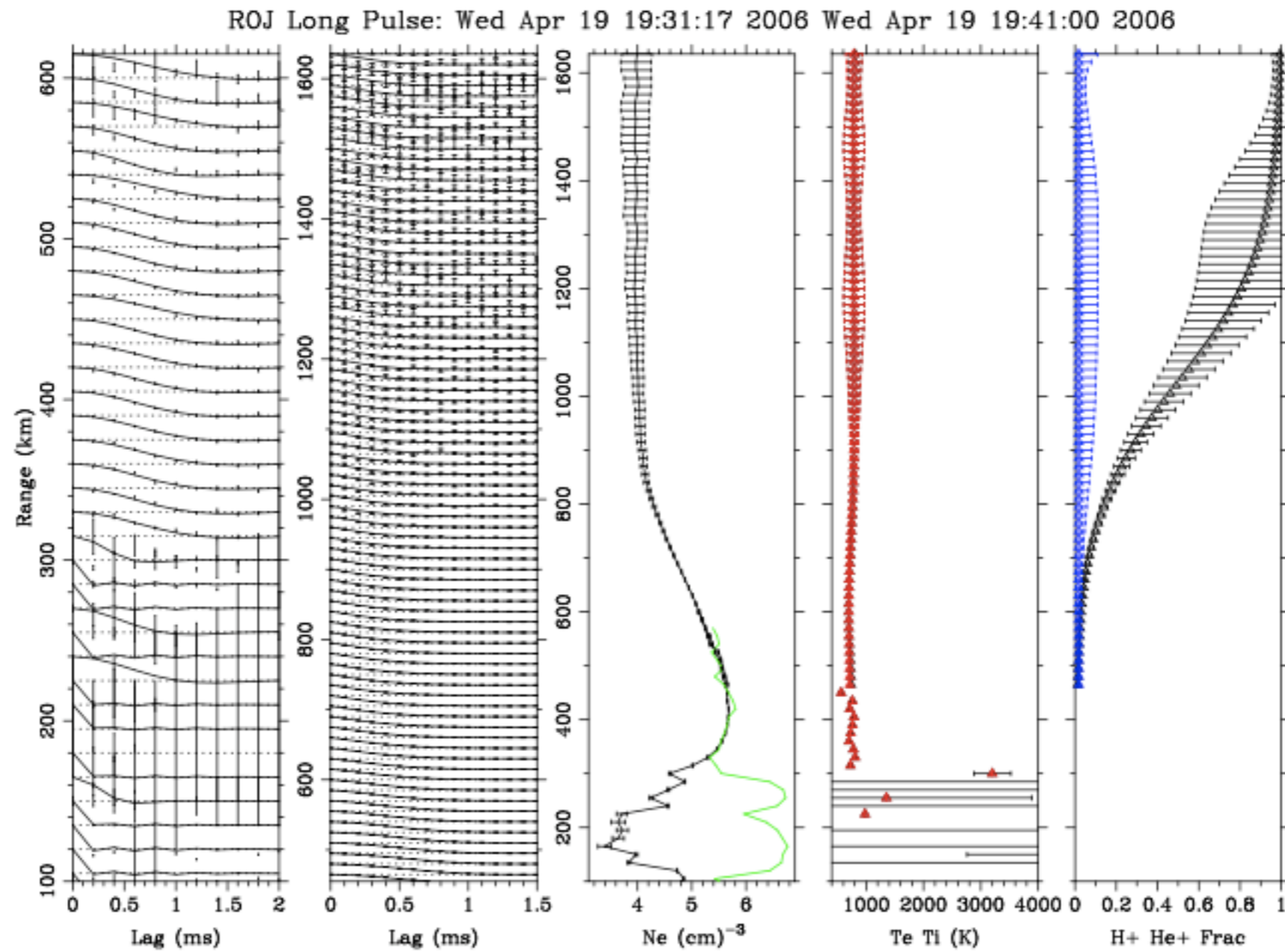


Fig. 3. Jicamarca profiles for 19:30 LT (00:30 UT). From left to right, the panels represent double-pulse lag products, long-pulse lag products, electron density, electron and ion temperature, and light ion fraction (see text).

Full profile at JRO Hysell et al, 2008
6 cost functions inject weighted apriori information