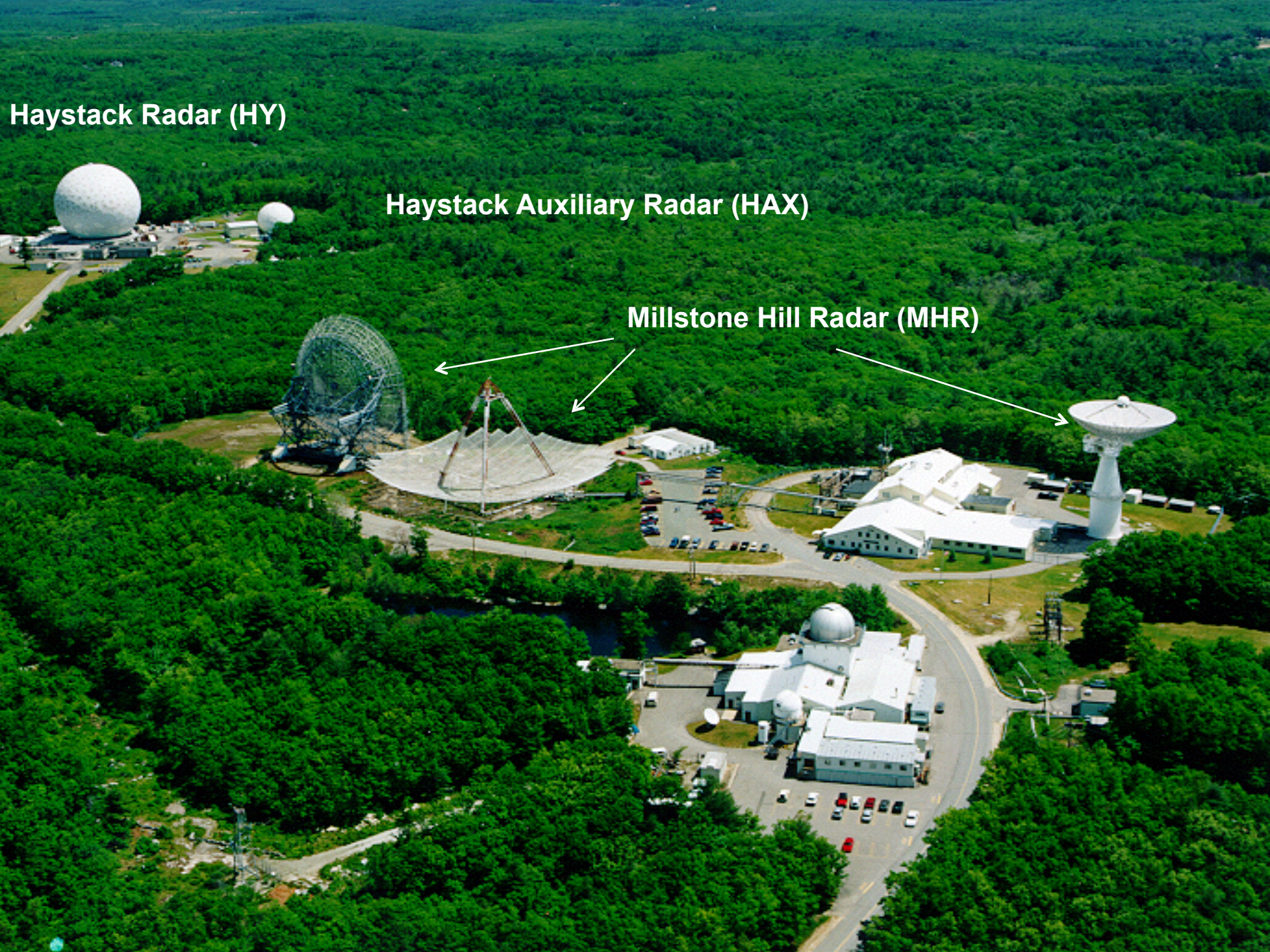


Haystack Radar (HY)

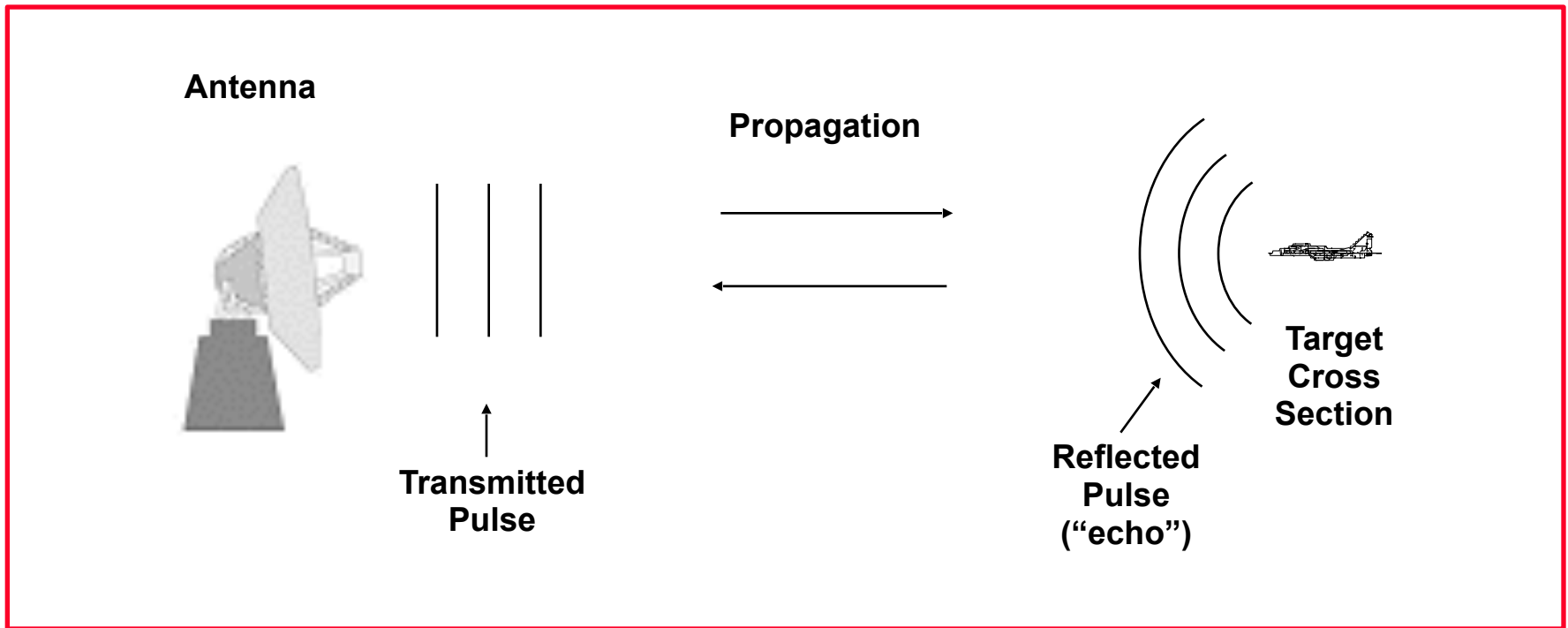
Haystack Auxiliary Radar (HAX)

Millstone Hill Radar (MHR)



RADAR

Radio Detection And Ranging



Radar observables:

- Target range
- Target angles (azimuth & elevation)
- Target size (radar cross section)
- Target speed (Doppler)
- Target features (imaging)



OUTLINE

RADAR –definition

 Basic principles of radio waves:

properties of waves

amplitude phase coherent/destructive interference

polarization

Doppler

Antennas

Radar Equation

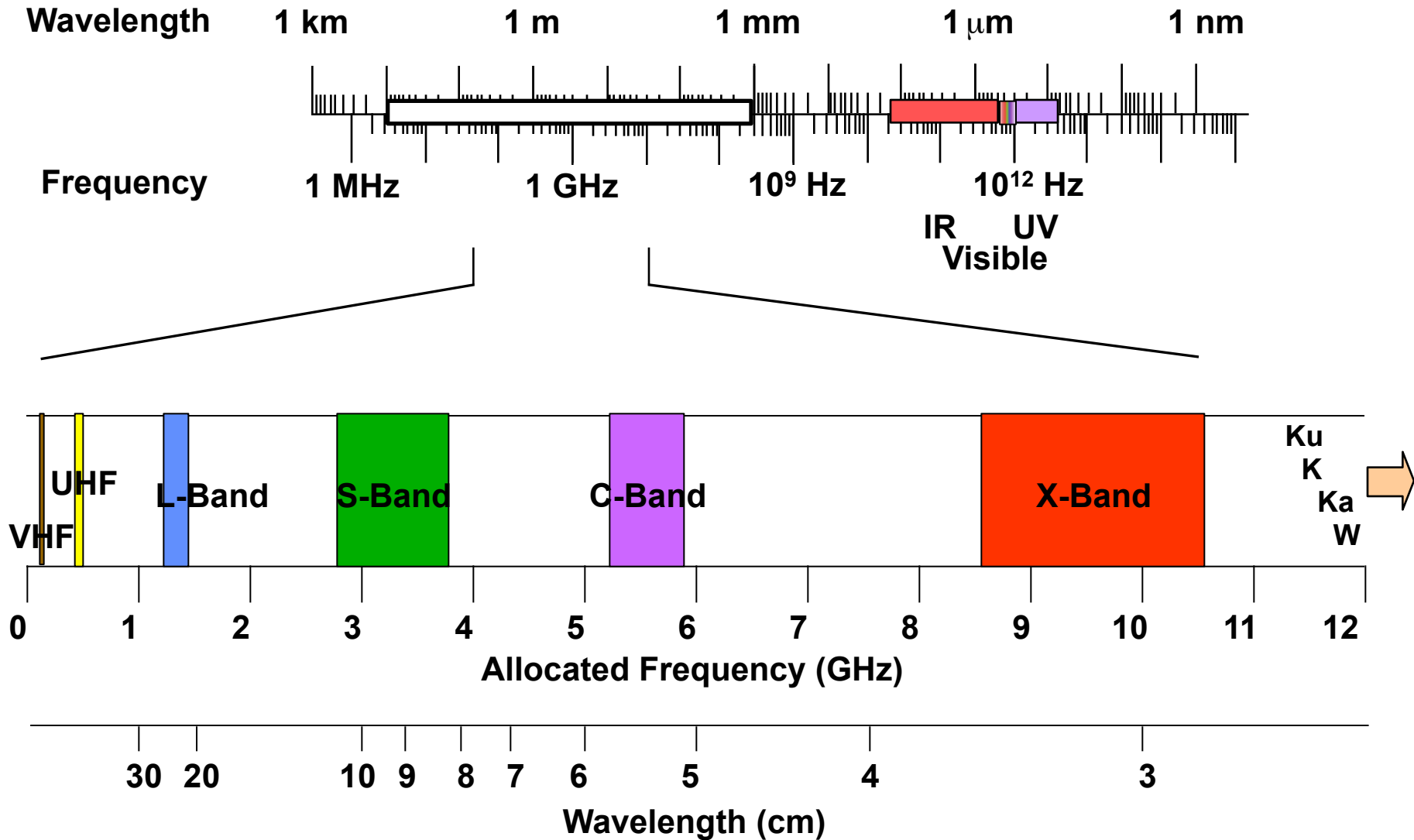
Hard Targets versus Soft Targets

Signal Processing

correlation versus convolution

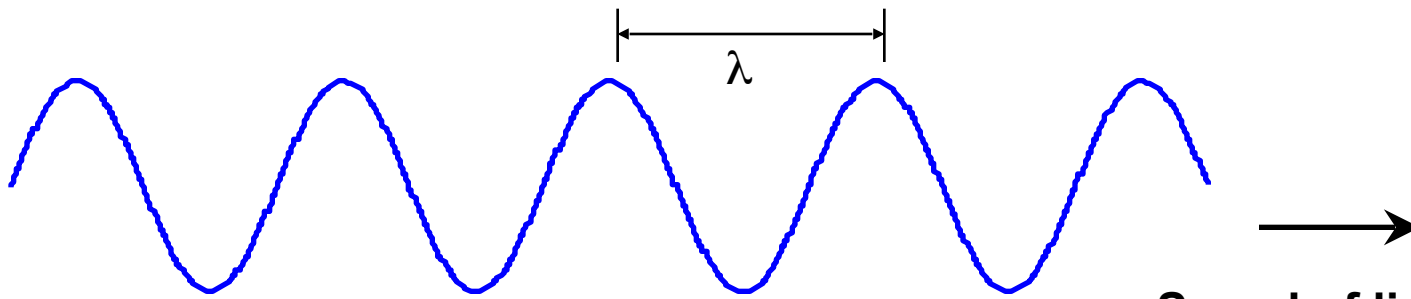


Radar Frequency Bands



Properties of Waves

Relationship Between Frequency and Wavelength



Speed of light, c
 $c = 3 \times 10^8$ m/sec
 $= 300,000,000$ m/sec

$$\text{Frequency (1/s)} = \frac{\text{Speed of light (m/s)}}{\text{Wavelength } \lambda \text{ (m)}}$$

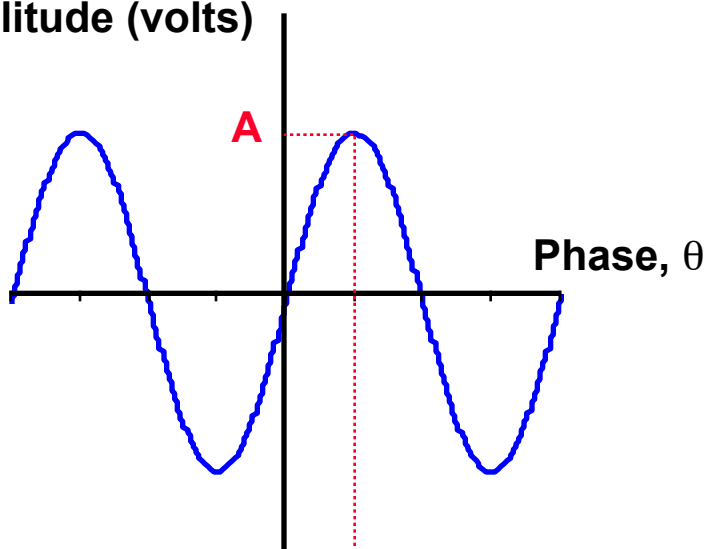
Examples:

<u>Frequency</u>	<u>Wavelength</u>
100 MHz	3 m
1 GHz	30 cm
3 GHz	10 cm
10 GHz	3 cm

Properties of Waves

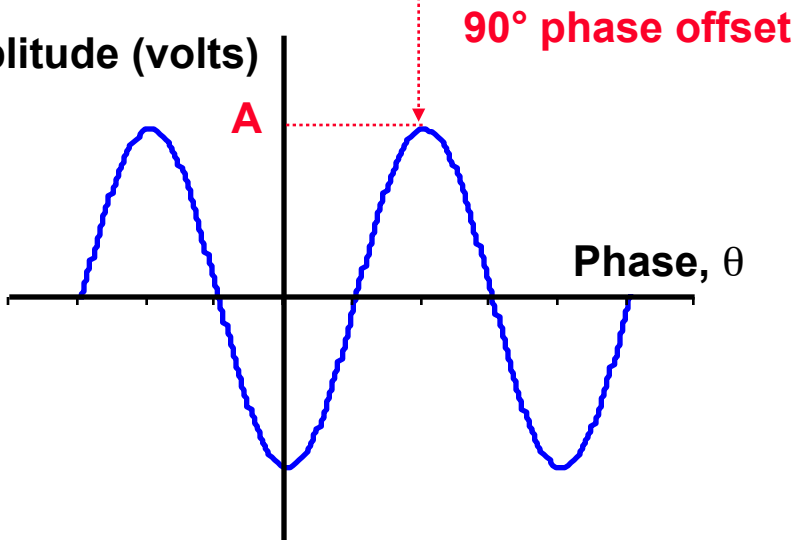
Phase and Amplitude

Amplitude (volts)



$$A \sin(\theta)$$

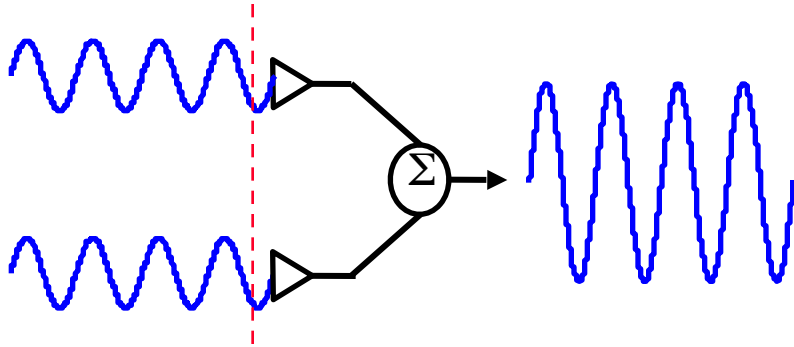
Amplitude (volts)



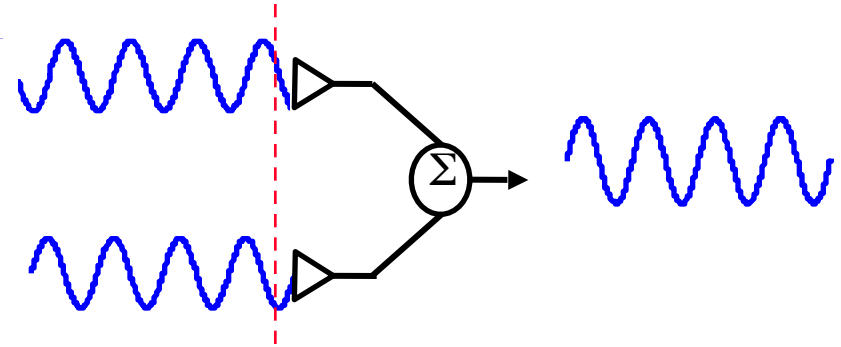
$$A \sin(\theta - 90^\circ)$$

Properties of Waves

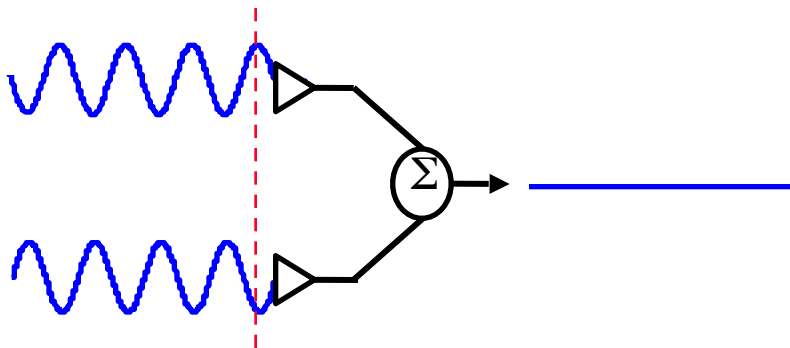
Constructive vs. Destructive Addition



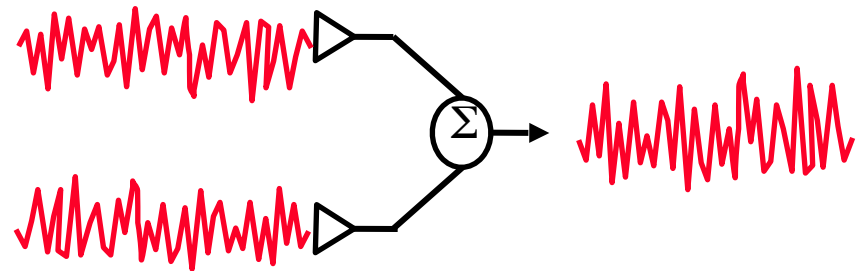
Constructive
(in phase)



Partially Constructive
(somewhat out of phase)



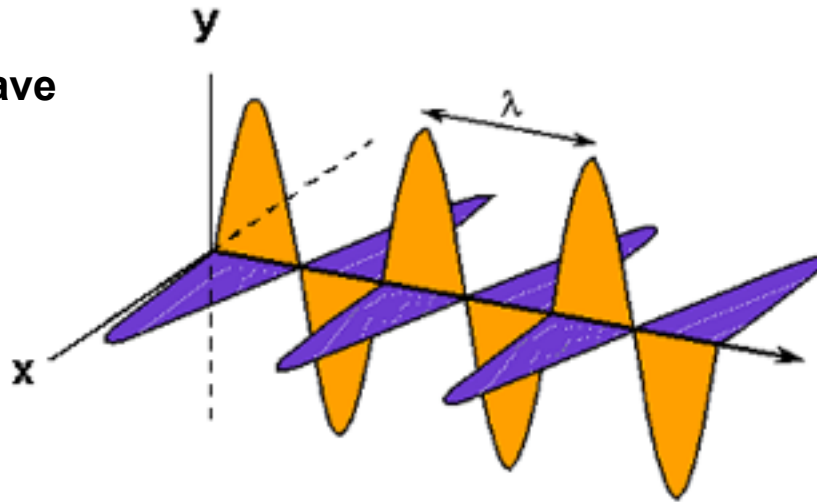
Destructive
(180° out of phase)



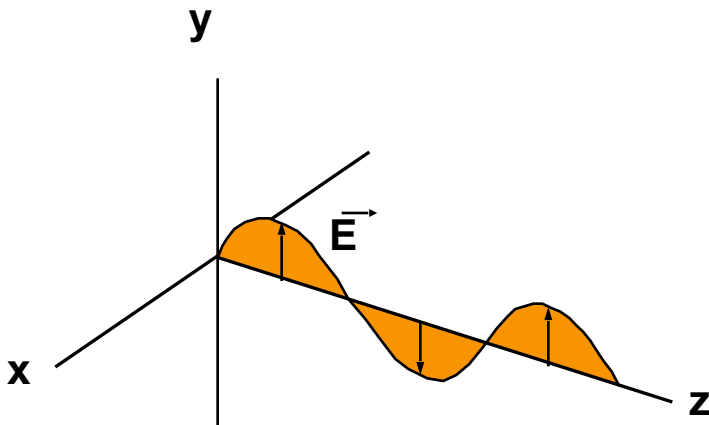
Non-coherent signals
(noise)

Polarization

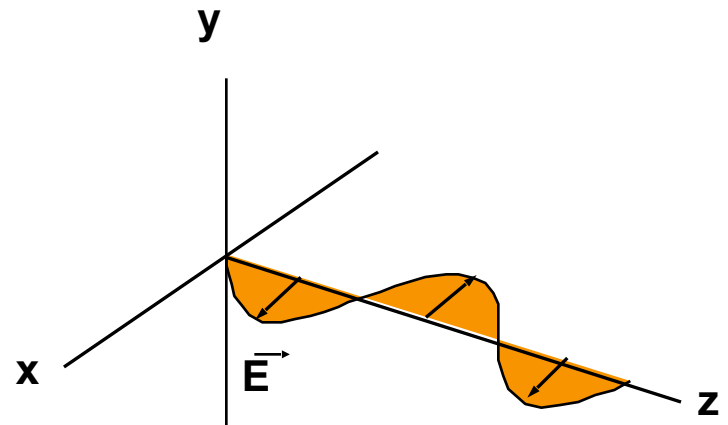
Electromagnetic Wave



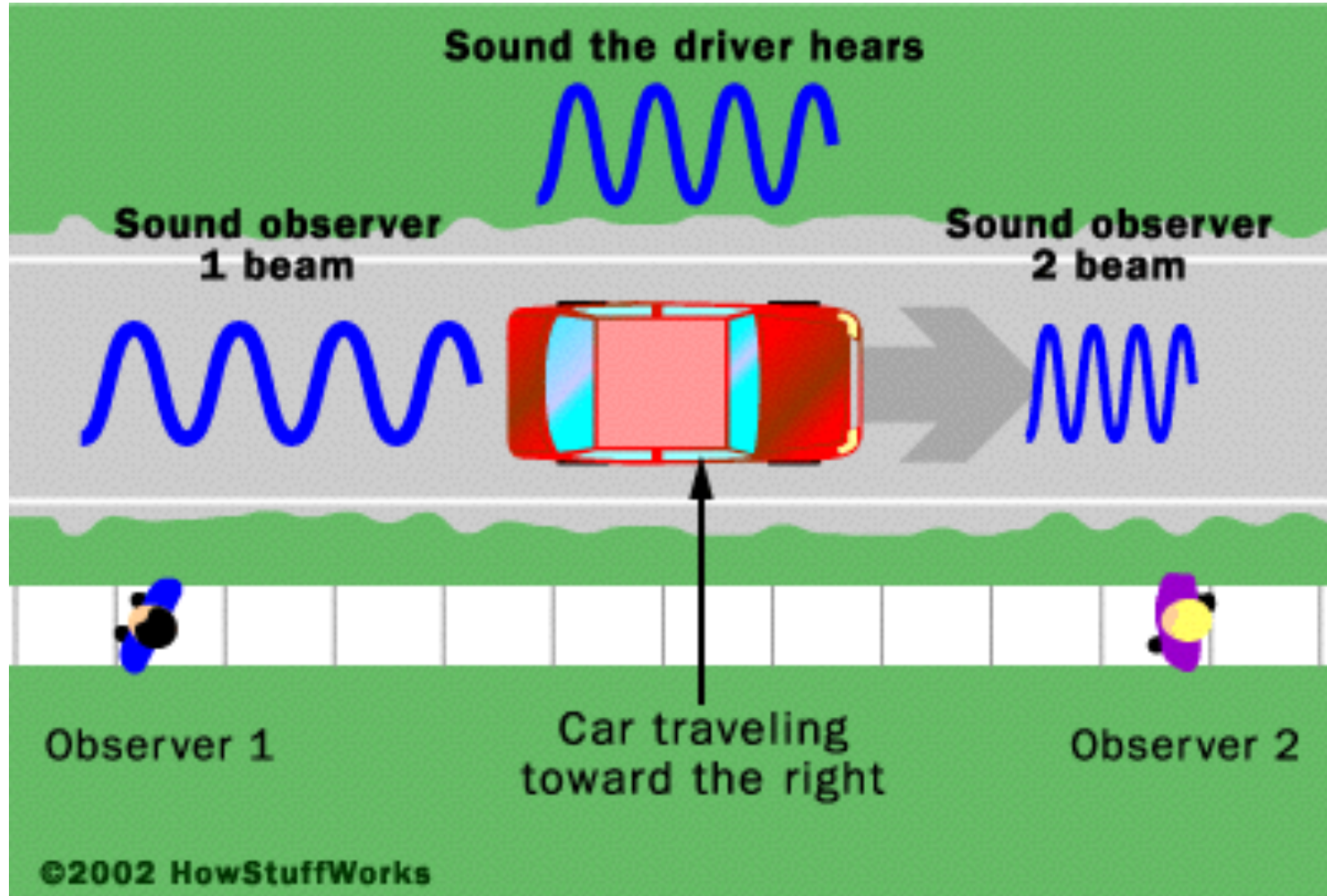
Vertical Polarization



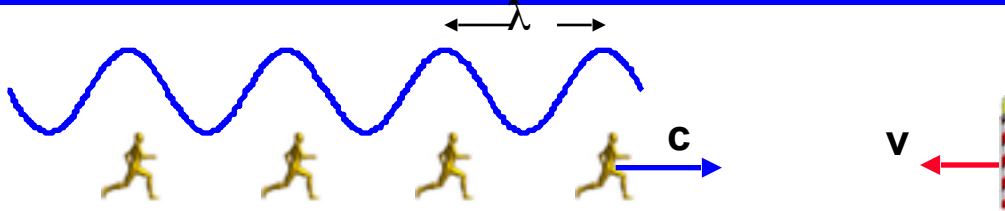
Horizontal Polarization



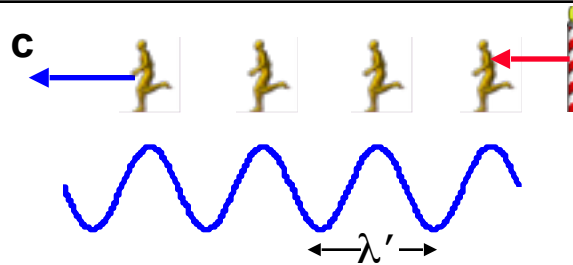
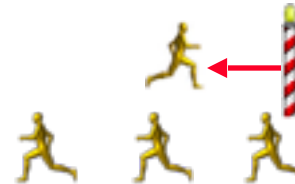
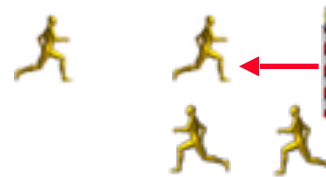
Doppler Effect



Doppler Shift Concept



$$f = \frac{c}{\lambda}$$



$$f' = f \pm (2v/\lambda)$$

Doppler shift





OUTLINE

RADAR –definition

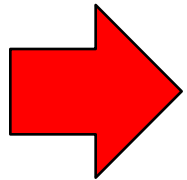
Basic principles of radio waves:

properties of waves

amplitude phase coherent/destructive interference

polarization

Doppler



Antennas

Radar Equation

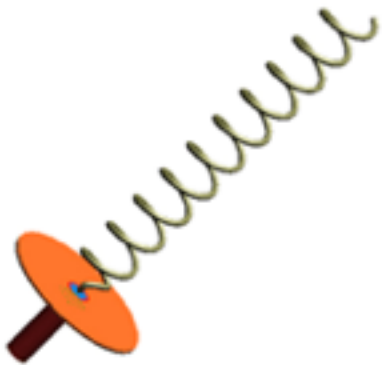
Hard Targets versus Soft Targets

Signal Processing

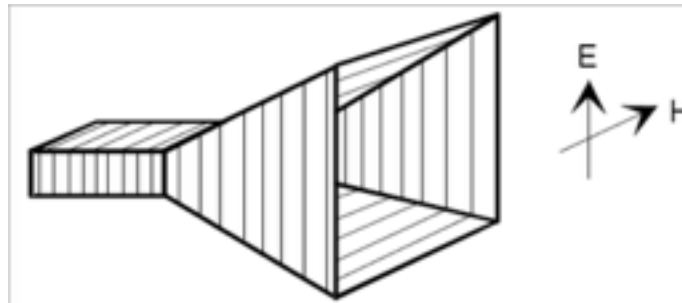
correlation versus convolution

Antennas

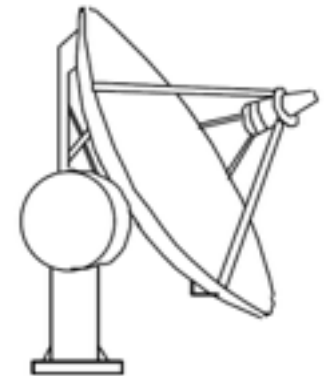
- **Four primary functions of an antenna for radar applications**
 - **Impedance transformation (free-space intrinsic impedance to transmission-line characteristic impedance)**
 - **Propagation-mode adapter (free-space fields to guided waves)**
 - **Spatial filter (radiation pattern – direction-dependent sensitivity)**
 - **Polarization filter (polarization-dependent sensitivity)**



Helical antenna



Horn antenna



Parabolic reflector antenna



Impedance transformer

- **Intrinsic impedance of free-space, $\eta_0 \equiv E/H$ is**

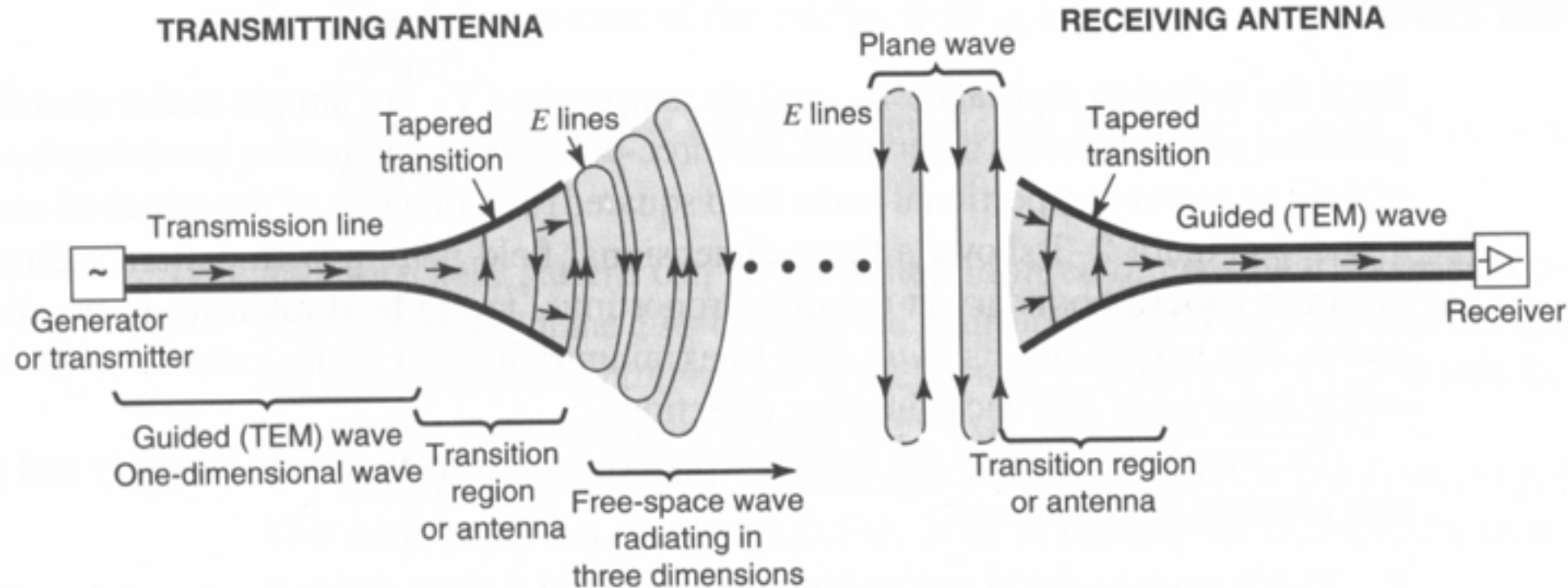
$$\eta_0 = \sqrt{\mu_0 / \epsilon_0} = 120 \pi \approx 376.7 \Omega$$

- **Characteristic impedance of transmission line, $Z_0 = V/I$**
- **A typical value for Z_0 is 50 Ω .**

- **Clearly there is an impedance mismatch that must be addressed by the antenna.**

Propagation-mode adapter

- During both transmission and receive operations the antenna must provide the transition between these two propagation modes.

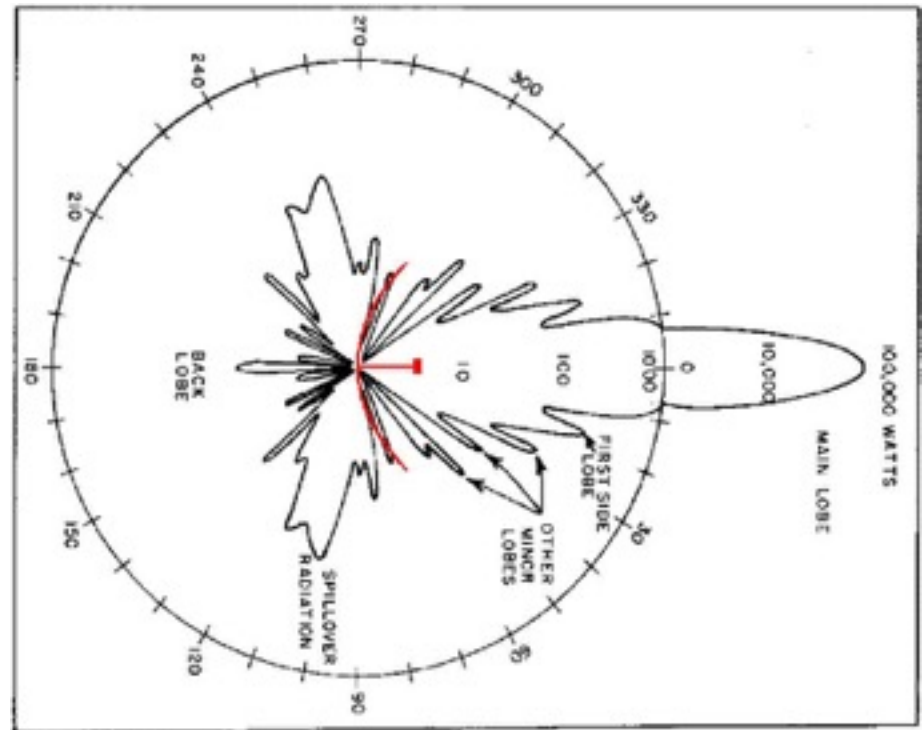


Spatial filter (also Polarization Filter)

- Antennas have the property of being more sensitive in one direction than in another which provides the ability to spatially filter signals from its environment.



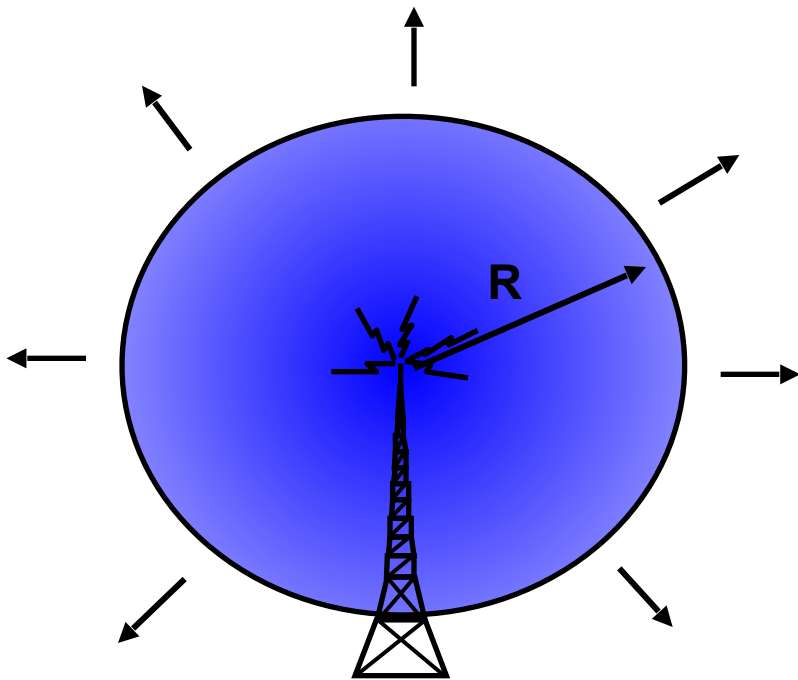
Directive antenna.



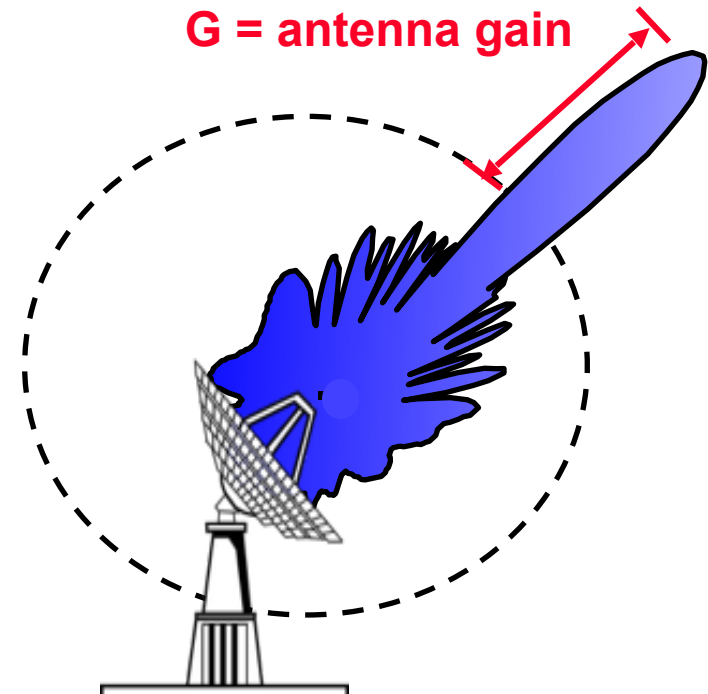
Radiation pattern of directive antenna.

Antenna Gain

Isotropic antenna



Directional antenna





Write equation for Gain on blackboard

$$G = \frac{4\pi A}{\lambda^2} \rho_e$$



OUTLINE

Basic principles of radio waves:

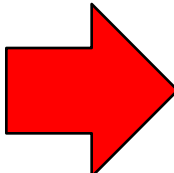
properties of waves

amplitude phase coherent/destructive interference

polarization

Doppler

Antennas

 RADAR –definition

Radar Equation

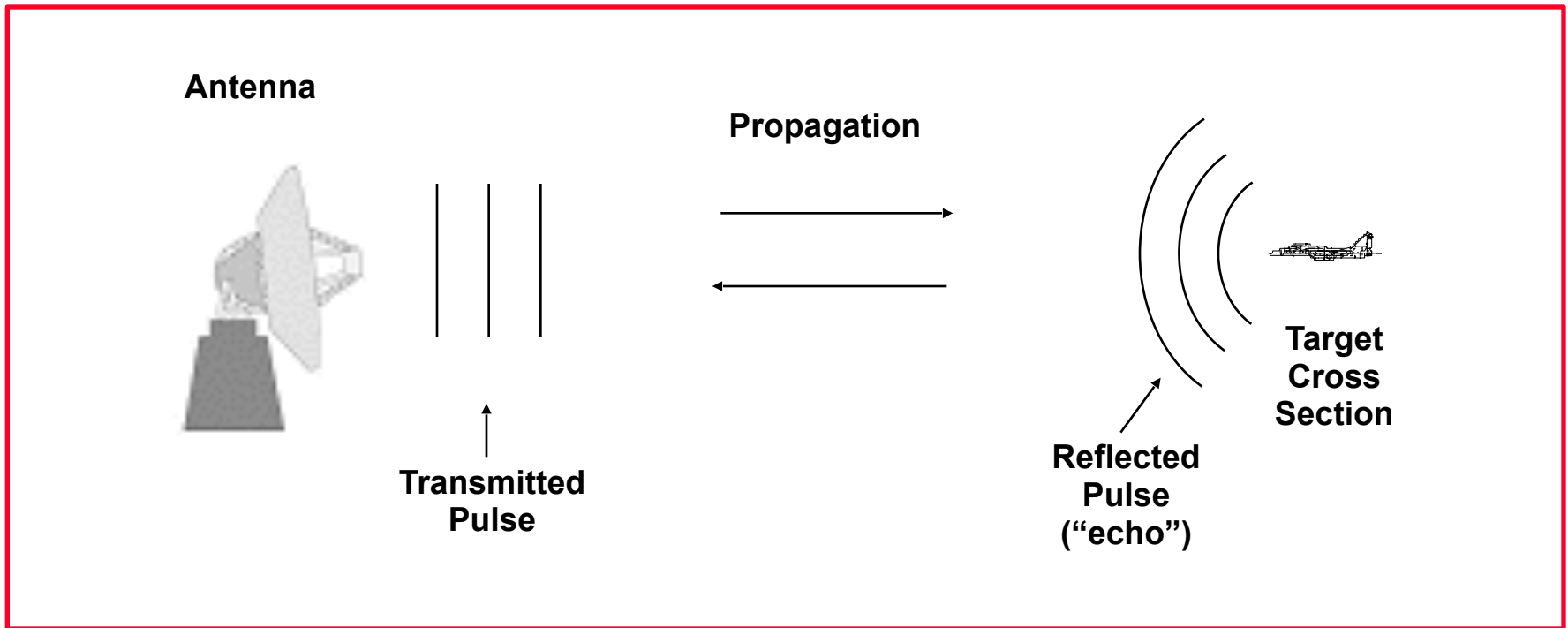
Hard Targets versus Soft Targets

Signal Processing

correlation versus convolution

RADAR

Radio Detection And Ranging

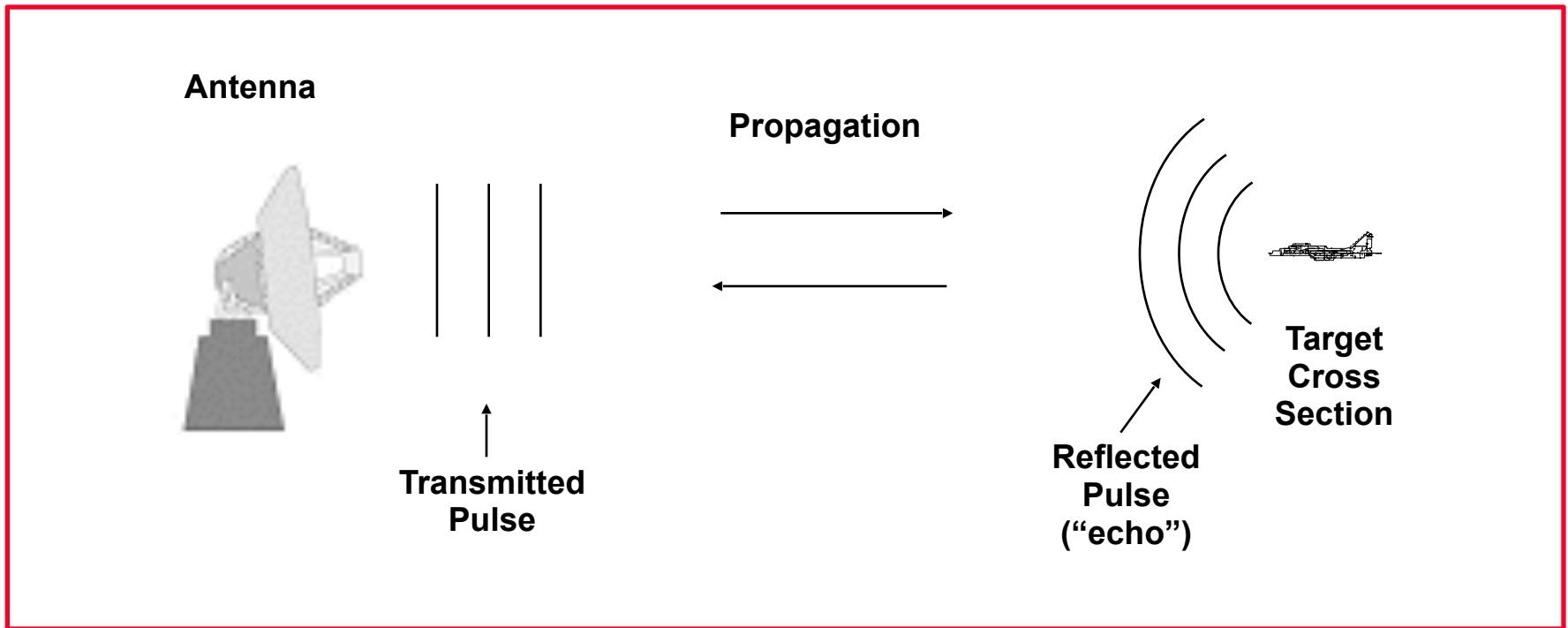


Radar observables:

- Target range
- Target angles (azimuth & elevation)
- Target size (radar cross section)
- Target speed (Doppler)
- Target features (imaging)

RADAR

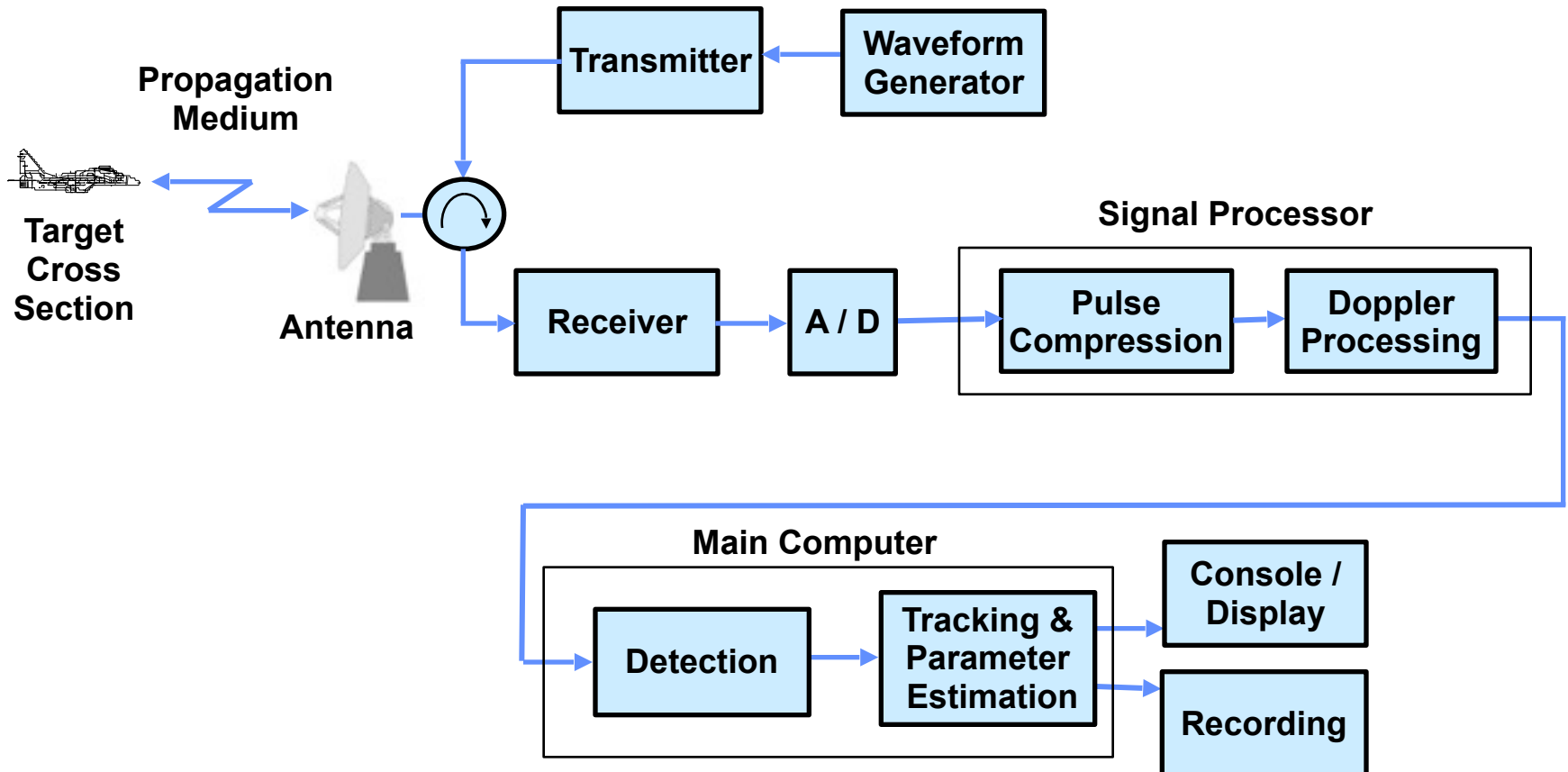
Radio Detection And Ranging



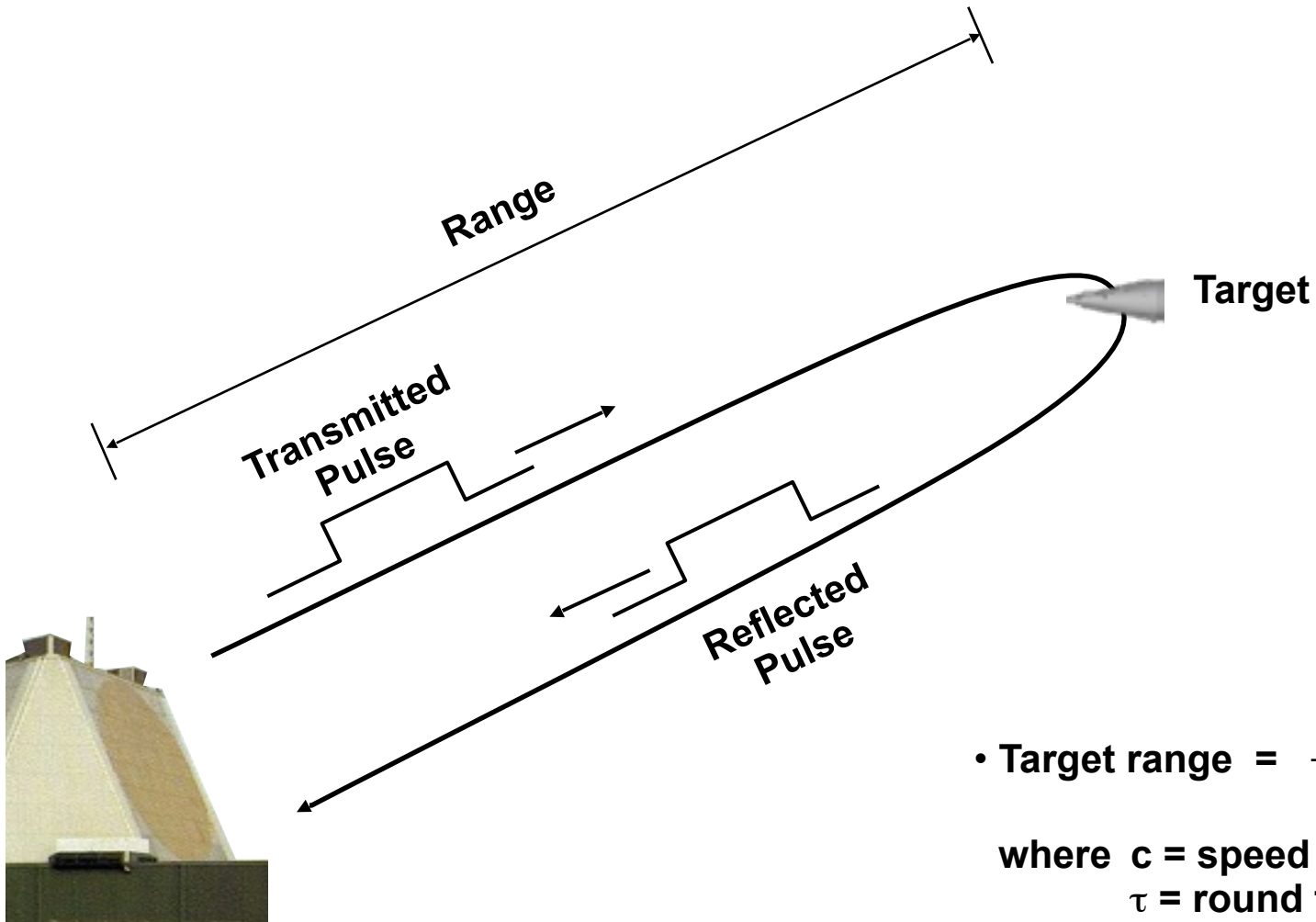
Radar observables:

- Target range
- Target angles (azimuth & elevation)
- Target size (radar cross section)
- Target speed (Doppler)
- Target features (imaging)

Radar Block Diagram



Radar Range Measurement



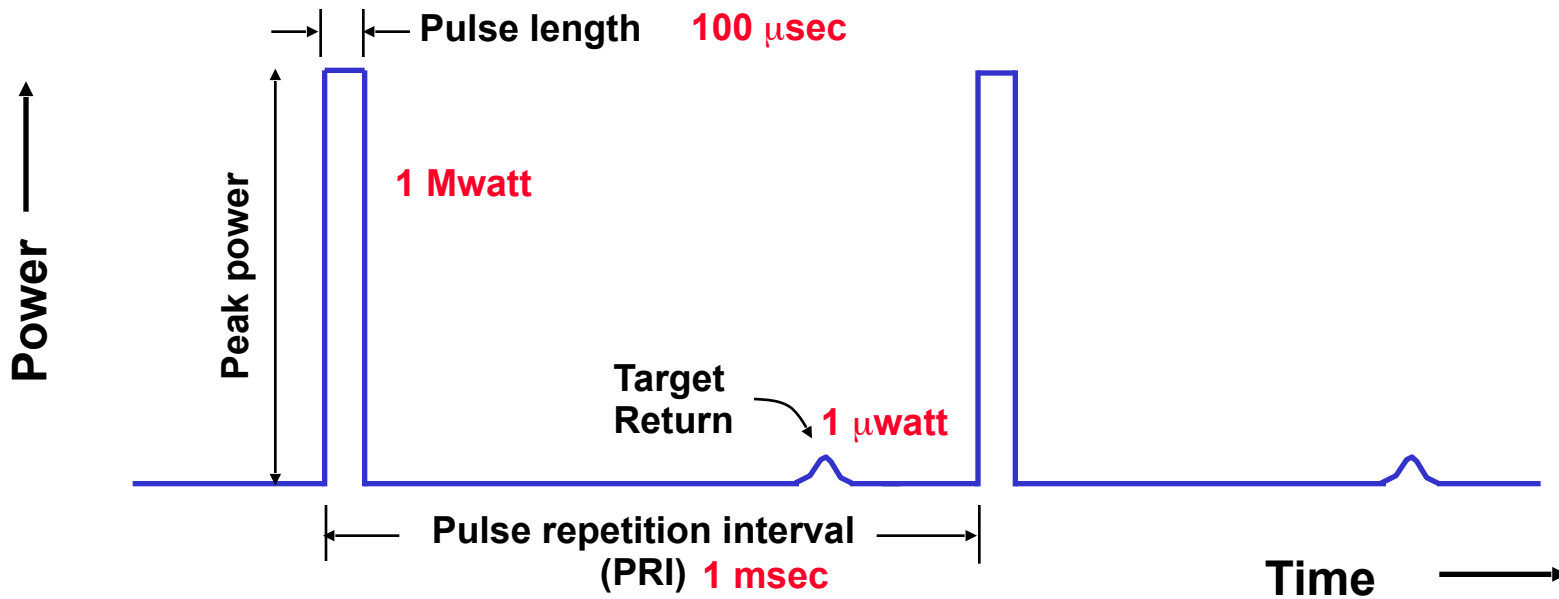
- Target range = $\frac{c\tau}{2}$

where c = speed of light
 τ = round trip time



Pulsed Radar

Terminology and Concepts



$$\text{Duty cycle} = \frac{\text{Pulse length}}{\text{Pulse repetition interval}} \quad 10\%$$

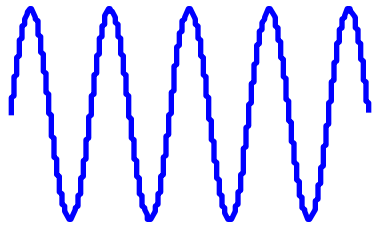
$$\text{Average power} = \text{Peak power} * \text{Duty cycle} \quad 100 \text{ kWatt}$$

$$\text{Pulse repetition frequency (PRF)} = 1/(\text{PRI}) \quad 1 \text{ kHz}$$

Continuous wave (CW) radar: Duty cycle = 100% (always on)

Radar Waveforms

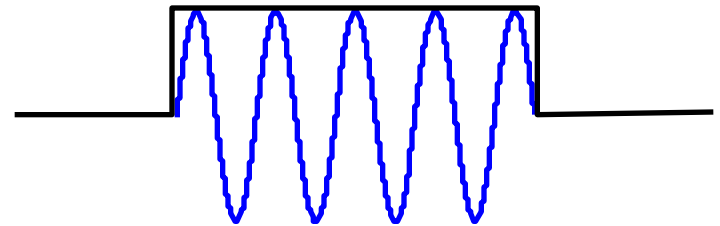
What do radars transmit?



Waves?



or Pulses?



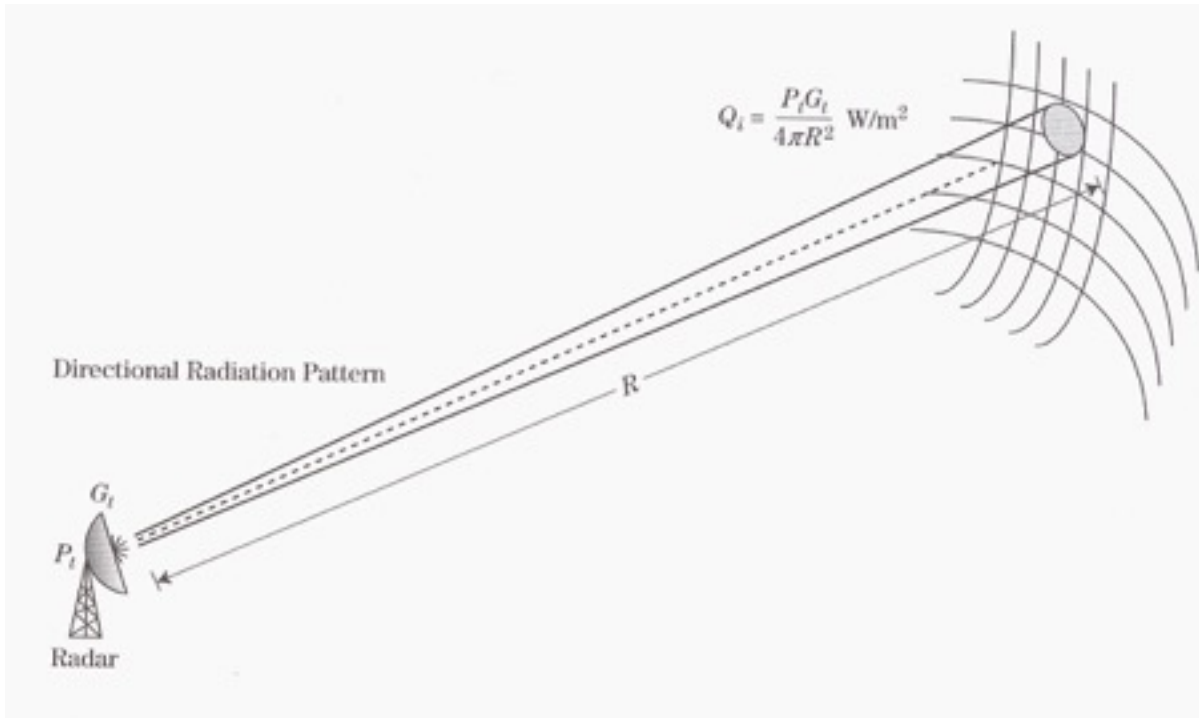
Waves, modulated
by “on-off” action of
pulse envelope

The Radar Equation: Monostatic Version

Power density at range R (directional):

$$\frac{P_t G}{4\pi R^2}$$

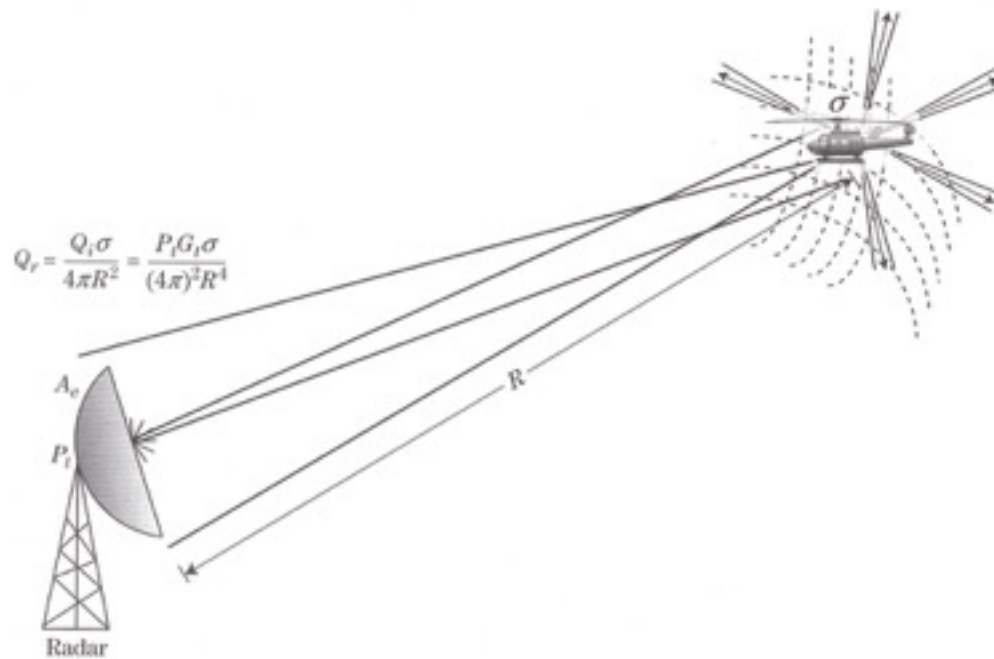
1. P_t = Transmit Power
2. G = Gain of Antenna
3. $\frac{1}{4\pi R^2}$ Spread Factor



The Radar Equation: Monostatic Version

Reradiated power density at Rx:

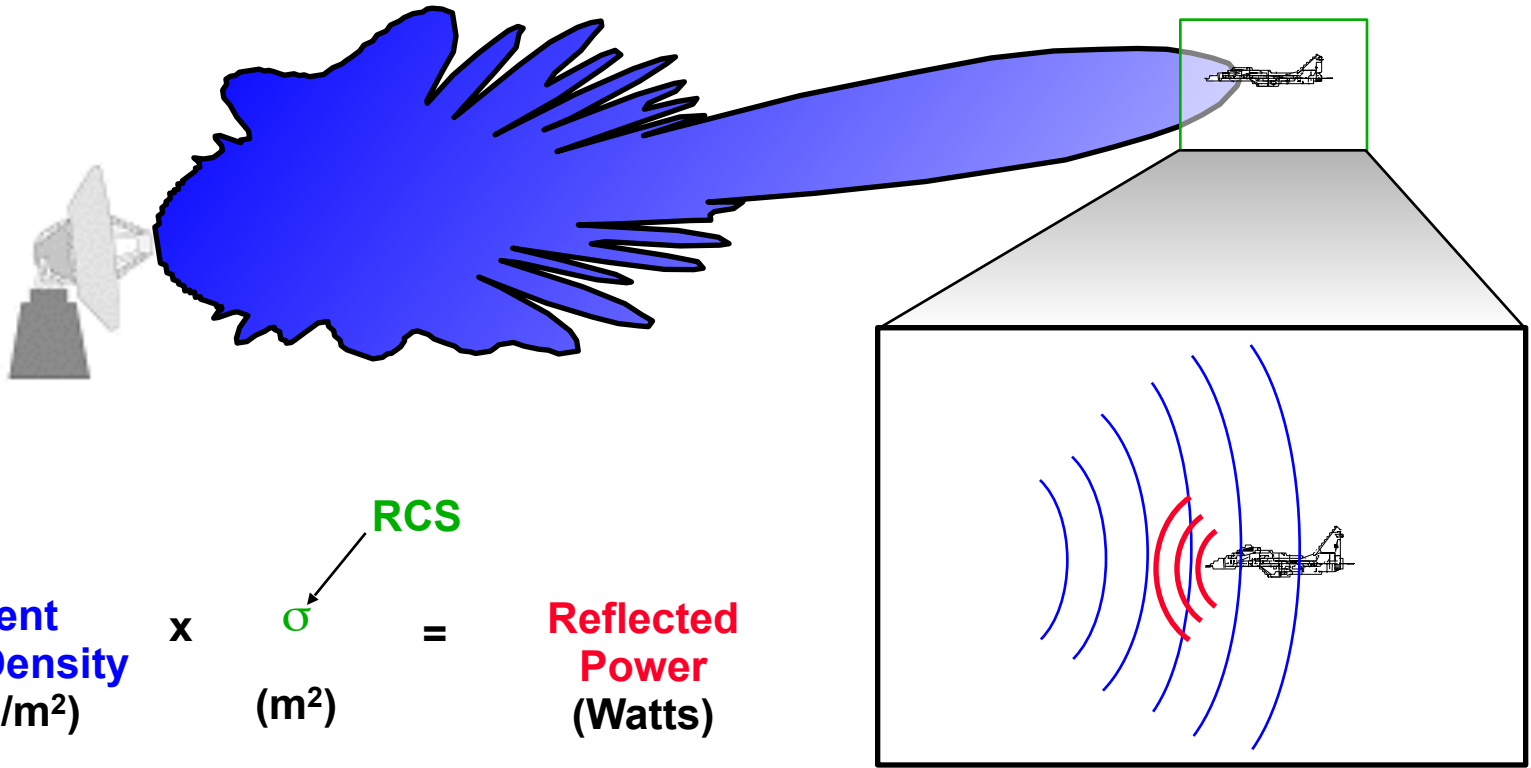
$$\frac{P_t G}{4\pi R^2} \cdot \frac{\sigma}{4\pi R^2}$$



$$Q_r = \frac{Q_t \sigma}{4\pi R^2} = \frac{P_t G_t \sigma}{(4\pi)^2 R^4}$$

1. P_t = Transmit Power
2. G = Gain of Antenna
3. $\frac{1}{4\pi R^2}$ = Spread Factor
4. σ = radar cross section (m^2)
5. $\frac{1}{4\pi R^2}$ = Spread Factor

Radar Cross Section (RCS)



$$\begin{array}{c}
 \text{Incident} \\
 \text{Power Density} \\
 \text{(Watts/m}^2\text{)}
 \end{array}
 \times
 \begin{array}{c}
 \text{RCS} \\
 \sigma \\
 \text{(m}^2\text{)}
 \end{array}
 =
 \begin{array}{c}
 \text{Reflected} \\
 \text{Power} \\
 \text{(Watts)}
 \end{array}$$

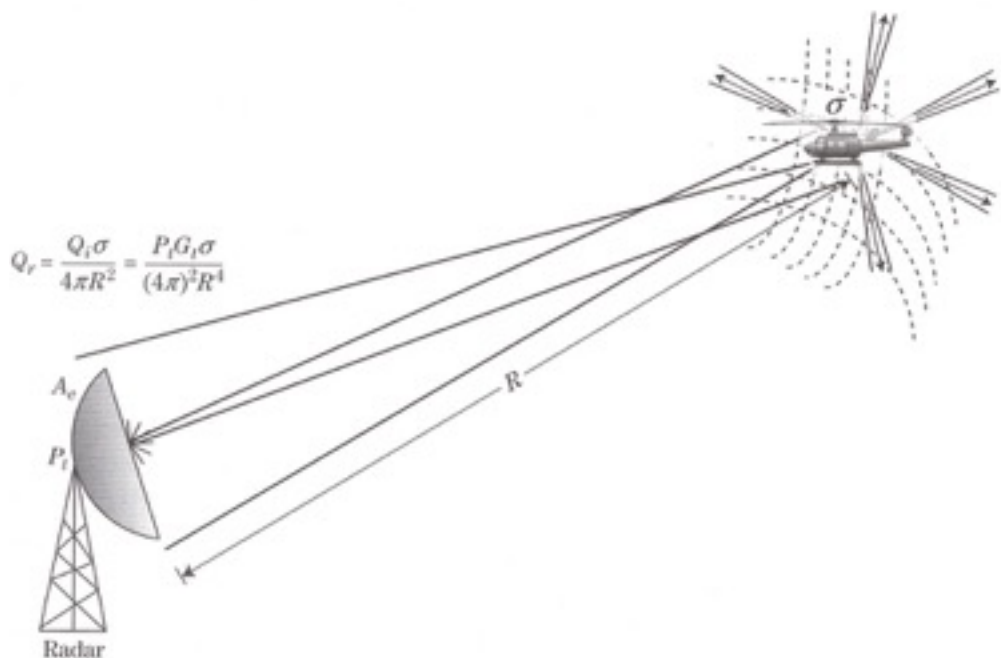
Radar Cross Section (RCS, or σ) is the effective cross-sectional area of the target as seen by the radar

measured in m^2 , or dBm^2

The Radar Equation: Monostatic Version

Total Received Power at Rx:

$$P_r = \frac{P_t G}{4\pi R^2} \cdot \frac{\sigma}{4\pi R^2} \cdot A_e = \frac{P_t G A_e \sigma}{(4\pi)^2 R^4}$$



1. P_t = Transmit Power
2. G = Gain of Antenna
3. $\frac{1}{4\pi R^2}$ = Spread Factor
4. σ = radar cross section (m^2)
5. $\frac{1}{4\pi R^2}$ = Spread Factor
6. A_e = effective collecting area



The Radar Equation: Monostatic Version

Total received power:
$$P_r = \frac{P_t G}{4\pi R^2} \cdot \frac{\sigma}{4\pi R^2} \cdot A_e = \frac{P_t G A_e \sigma}{(4\pi)^2 R^4}$$

Use gain/area relation -

The Radar Equation:
$$P_r = P_t \frac{\rho_a^2 A^2}{4\pi \lambda^2 R^4} \sigma$$



Hard vs Soft Radar Targets

Generalize radar equation for one or more scatterers, distributed over a volume:

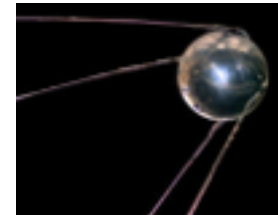
$$P_r = \int P_t \frac{\rho_a^2 A^2}{4\pi\lambda^2 R^4} \sigma(\vec{x}) dV_s$$

First case: single scatterer (“hard target”) at single point in space:

$$\int \sigma(\vec{x}) dV_s = \sigma_{target} \equiv \sigma$$

Hard target radar equation:

$$P_r = P_t \frac{\rho_a^2 A^2}{4\pi\lambda^2 R^4} \sigma$$

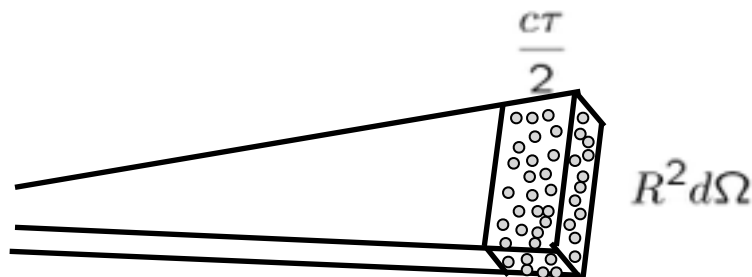


Sputnik 1
(1957-10-04)

Distributed Targets

$$\int \sigma(\vec{x}) dV_s = \int_0^{2\pi} \int_0^\pi \sigma(\vec{x}) \frac{c\tau}{2} R^2 d\Omega$$

$$\int \sigma(\vec{x}) dV_s = \frac{c\tau}{2} \int_0^{2\pi} \int_0^\pi \sigma(\vec{x}) R^2 \sin \theta d\theta d\phi$$



Assume volume is filled with identical, isotropic scatters

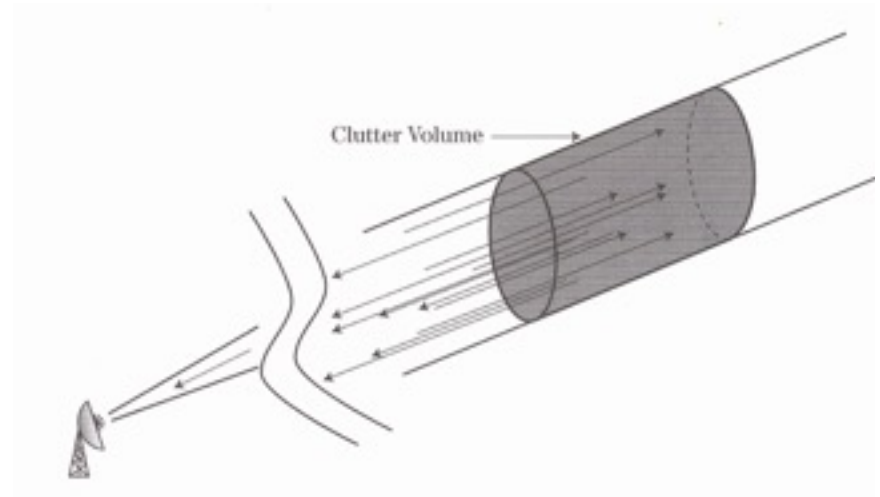
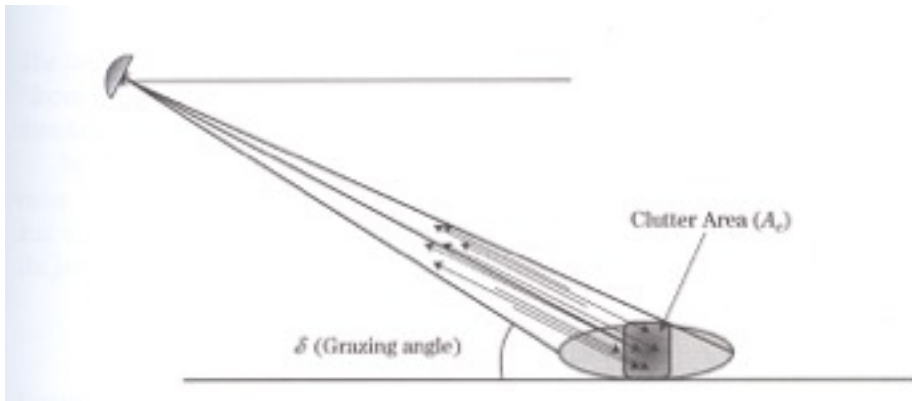
$$\int \sigma(\vec{x}) dV_s = \frac{c\tau}{2} R^2 \sigma$$

Distributed Scatterers

$$P_r = P_t \frac{\rho_a^2 A^2}{4\pi\lambda^2 R^4} \sigma \frac{c\tau}{2} R^2$$

The “soft target” Radar Equation

$$P_r = P_t \frac{c\rho_a^2 A^2 \tau}{8\pi\lambda^2 R^2} \sigma$$





OUTLINE

Basic principles of radio waves:

- properties of waves

- amplitude phase coherent/destructive interference

- polarization

- Doppler

Antennas

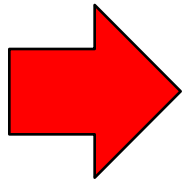
RADAR –definition

Radar Equation

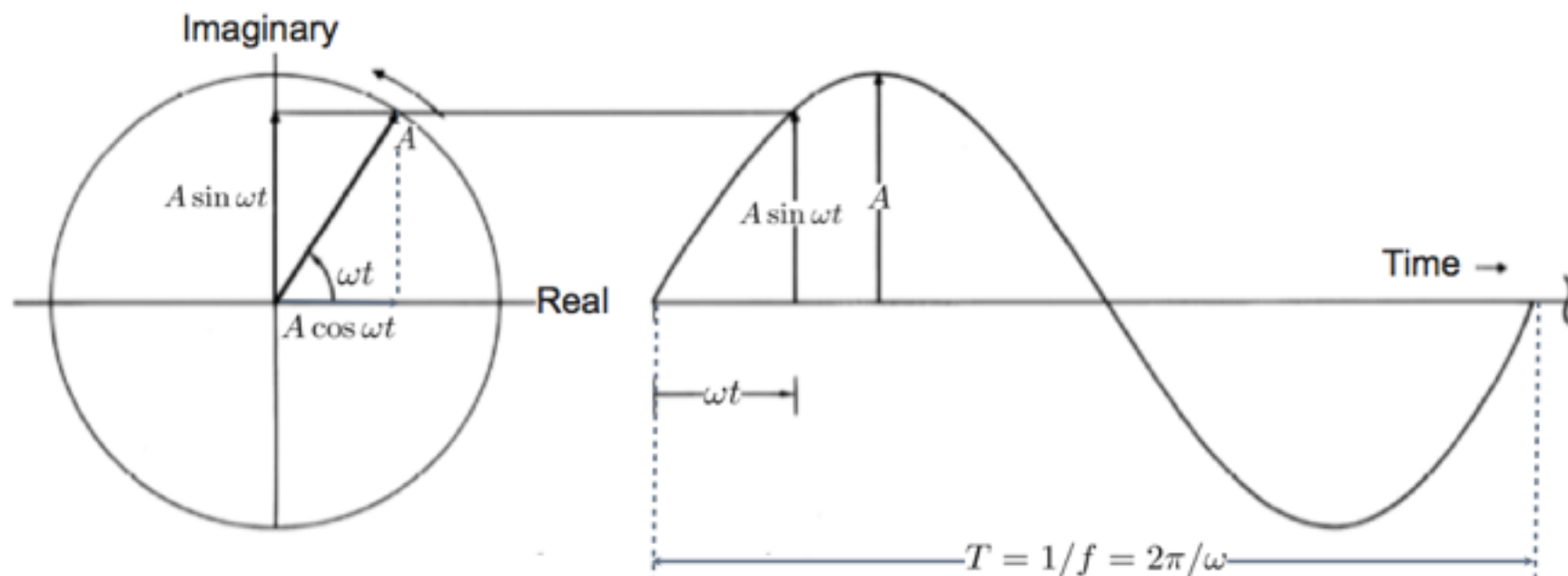
Hard Targets versus Soft Targets

Signal Processing

correlation versus convolution



Euler identity and the complex plane



ω is the "angular velocity" (radians/s) of the spinning arrow

f is the number of complete rotations (2π radians) in one second (1/s or Hz)

We need a signal that tells us **how fast** and in **which direction** the arrow is spinning. This signal is the complex exponential. Invoking the Euler identity,

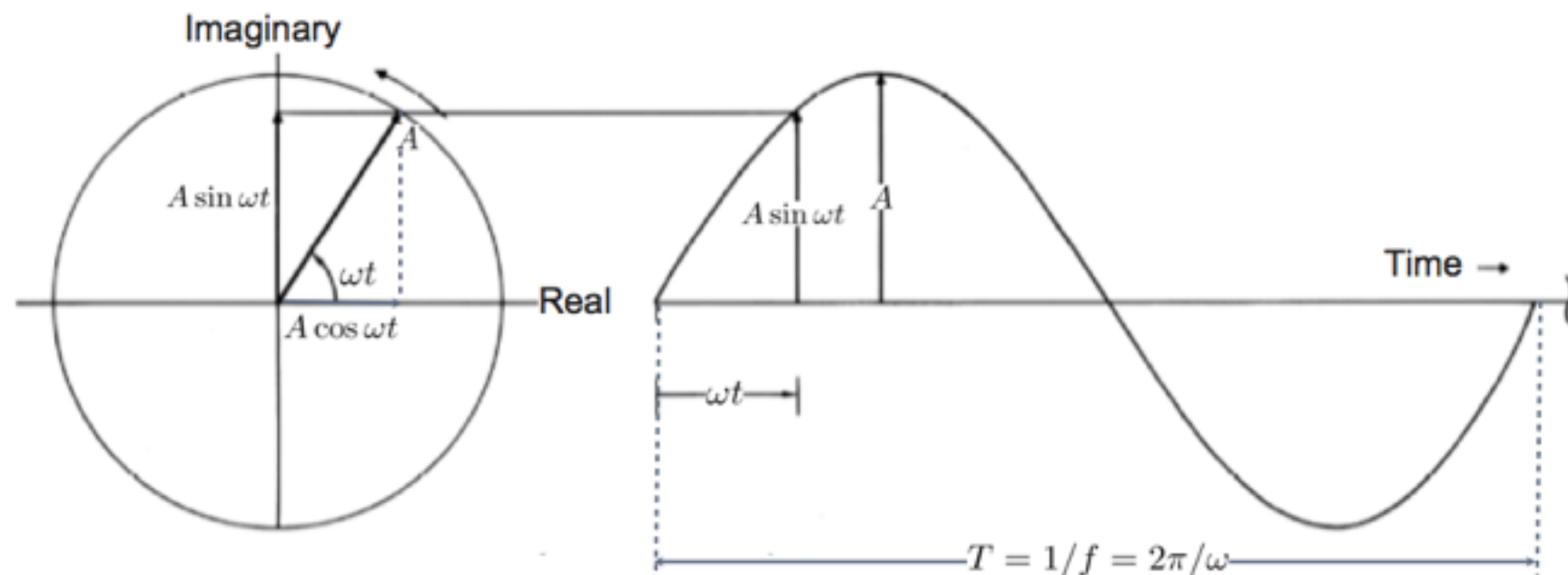
$$s(t) = Ae^{j\omega t} = A \cos \omega t + jA \sin \omega t = I + jQ$$

I = in-phase component

Q = in-quadrature component

Exponentials are eigenfunctions of linear, time-invariant systems!

Euler identity and the complex plane



ω is the "angular velocity" (radians/s) of the spinning arrow

f is the number of complete rotations (2π radians) in one second (1/s or Hz)

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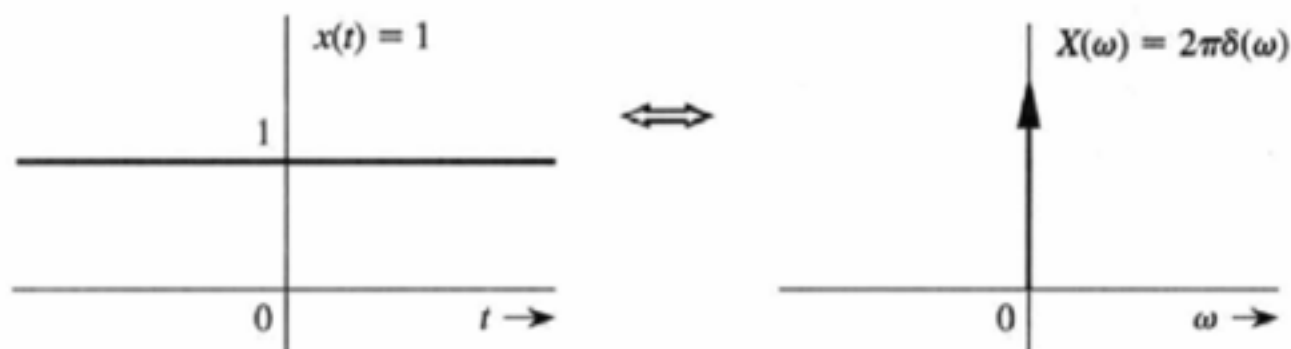
Exponentials are eigenfunctions of linear, time-invariant systems!

Essential mathematical operations

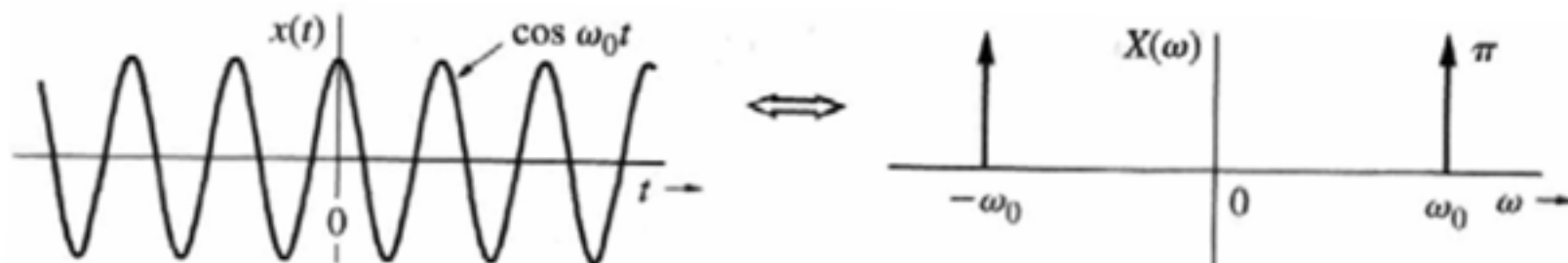
Fourier Transform: Expresses a function as a weighted sum of harmonic functions (i.e., complex exponentials)

$$f(t) = \int_{-\infty}^{+\infty} F(\omega) e^{j\omega t} d\omega \quad \Longleftrightarrow \quad F(\omega) = \int_{-\infty}^{+\infty} f(t) e^{-j\omega t} dt$$

Harmonic Functions



$$\cos \omega_0 t \iff \pi [\delta(\omega + \omega_0) + \delta(\omega - \omega_0)]$$



$$\sin \omega_0 t \iff j\pi [\delta(\omega + \omega_0) - \delta(\omega - \omega_0)]$$

$$e^{j\omega_0 t} \iff 2\pi \delta(\omega - \omega_0)$$

Another Example

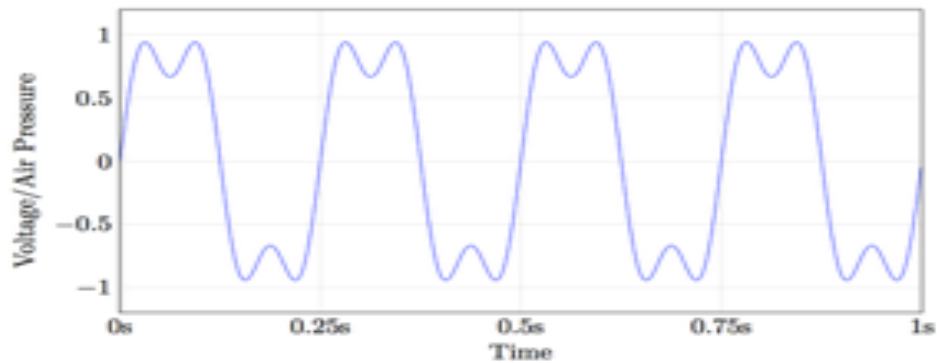


Figure 4: 4Hz + 12Hz Sin Wave.

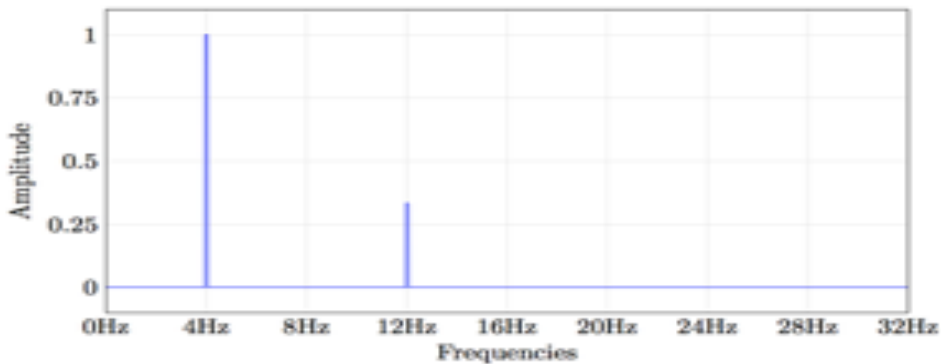


Figure 5: Frequency Domain of 4Hz + 12Hz Sin Waves.

Fourier Transform Properties

Operation	Time Function	Fourier Transform
Linearity	$af_1(t) + bf_2(t)$	$aF_1(\omega) + bF_2(\omega)$
Time shift	$f(t - t_0)$	$F(\omega)e^{-j\omega t_0}$
Time scaling	$f(at)$	$\frac{1}{ a } F\left(\frac{\omega}{a}\right)$
Time transformation	$f(at - t_0)$	$\frac{1}{ a } F\left(\frac{\omega}{a}\right)e^{-j\omega t_0/a}$
Duality	$F(t)$	$2\pi f(-\omega)$
Frequency shift	$f(t)e^{j\omega_0 t}$	$F(\omega - \omega_0)$
Convolution	$f_1(t)*f_2(t)$	$F_1(\omega)F_2(\omega)$
	$f_1(t)f_2(t)$	$\frac{1}{2\pi}F_1(\omega)*F_2(\omega)$
Differentiation	$\frac{d^n[f(t)]}{dt^n}$	$(j\omega)^n F(\omega)$
	$(-jt)^n f(t)$	$\frac{d^n[F(\omega)]}{d\omega^n}$
Integration	$\int_{-\infty}^t f(\tau)d\tau$	$\frac{1}{j\omega}F(\omega) + \pi F(0)\delta(\omega)$

Determining the Doppler Spectrum

1. Doppler spectrum is measured at a particular range gate (e.g. at $r = \frac{c\Delta t}{2}$)
2. Must process a time series of discrete samples of echo $E_r(t)$ at intervals of the pulse period T_r
3. Analyze the sampled signal using (fast) Fourier Transform methods:

$$E(mT_r) = \frac{1}{M} \sum_{m=0}^{M-1} F(kf_0) \cos[2\pi kf_0 mT_r]$$

M = # of samples
 f_0 = frequency resolution

$$F(kf_0) = \sum_{m=0}^{M-1} E_r(mT_r) \cos[2\pi kf_0 mT_r]$$

4. Frequency components (radial velocities) occur at discrete intervals, with **M** intervals separated by intervals of $1/MT_r = f_D$

Essential mathematical operations

Fourier Transform: Expresses a function as a weighted sum of harmonic functions (i.e., complex exponentials)

$$f(t) = \int_{-\infty}^{+\infty} F(\omega) e^{j\omega t} d\omega \quad \Longleftrightarrow \quad F(\omega) = \int_{-\infty}^{+\infty} f(t) e^{-j\omega t} dt$$

Convolution: Expresses the action of a linear, time-invariant system on a function.

$$f(t) * g(t) = \int_{-\infty}^{+\infty} f(\tau) g(t - \tau) d\tau \quad f(t) * g(t) \Longleftrightarrow F(f)G(f)$$

Correlation: A measure of the degree to which two functions look alike at a given offset.

$$f(t) \circ g(t) = \int_{-\infty}^{+\infty} f^*(\tau) g(t + \tau) d\tau \quad f(t) \circ g(t) \Longleftrightarrow F^*(f)G(f)$$



End of Day One - RADAR
