Advanced Modular Incoherent Scatter Radar

Roger H. Varney

¹Center for Geospace Studies SRI International

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- Hardware
- Electronic Beam Steering Capabilities
- Design Considerations for ISR Science

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- RISR-C First Results
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AMISR Modular Design



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Antenna Element Unit (AEU) Specifications

- Distributed Solid State Power Amplifiers (SSPAs)
- 430-450 MHz instantaneous bandwidth
- 10% Maximum duty cycle
- Minimum PRF interval 500 usec
- Maximum pulsewidth 2 msec
- Passive cooling (no moving parts
- 400 Hz prime power





- Crossed dipoles, circular polarization on axis
- Balun built into the antenna support shaft
- Constant impendence over bandwidth and scan angle
- Spacing is hexagonal for efficiency
- Tx/Rx polarizations are opposite and fixed (not measureable)

The AMISR UHF System



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Poker Flat Incoherent Scatter Radar (PFISR)



AMISR Technical Specifications

- Peak Power: 2 MW
- Max RF Duty: 10%
- Pulse Length: 1 µsec 2 msec
- TX Frequency: 430-450 MHz
 - Antenna Gain: ~43 dBi
- Antenna Aperture: ~715 m²
- Beam Width: ~1.1°
- System temperature: ~120 K
- Steering: Pulse to pulse over ~ +/-25°
- Max system power consumption: ~700 KW
- Max operations: continuous, depending on power availability
- Unattended operations
- Data volume ~6 TB/year at Poker Flat
- No moving parts on the antenna
- Environment: -40° C to +35° C

- Altitude coverage: ~60 km to ?? km (depending on Ne)
- Minimum measurable electron densities: ~1e9 m⁻³
- Typical time resolution:
 - E region <~3 min,
 - F region <~1 min,
- ~10 look directions and typical ionospheric conditions many caveats apply!
- Typical range resolution: 600, meters to 72 km (mode dependent, can be extended)
 - Plasma parameters: Ne, Te, Ti, Vi, v_{in} , composition
 - Derived parameters: E, J, J E, J E', Un, σ_P , σ_H

Electronic Beam Steering



- Time to steer beam is ${\sim}400~\mu{\rm s}$. Less than typical IPP (1-10 ms).
- Beam steering happens pulse-to-pulse.

Mechanical Steering vs Electronic Steering

Mechanical Steering Experiment

- Steer to position 1
- Send many pulses for 1 min
- Steer to position 2
- Send many pulses for 1 min
- Steer to position 3
- Send many pulses for 1 min
- Steer to back to position 1

Advantages of Electronic Steering:

- Each beam is revisited once every $N\tau_{IPP}$.
- Can average data at any multiple of $N\tau_{IPP}$. Incoherent integration time is adjustable after the fact.
- Data being combined is nearly simultaneous.
- No time lost steering between pulses.

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Electronic Steering Experiment

- Pulse in beam 1
- Pulse in beam 2
- Pulse in beam 3

- Pulse in beam N
- Pulse in beam 1 again

Statistical Considerations with Pulse Steering

$$\frac{\delta \hat{S}}{S} = \frac{1}{\sqrt{K}} \left(1 + \frac{1}{S/N} \right)$$

- Larger number of beams \Rightarrow fewer pulses per beam
- If I can confortably integrate for 1 min using 7 beam positions ⇒ I would need to integrate 6 min to get the same data quality using 42 beams.

Multiple frequency channels can help statistics. Example: RISR-N "ImagingLP" mode for imaging F-region polar cap patches.

- 51 beam positions
- Long pulses on 3-frequency channels
- In each IPP 2 frequencies Tx, 3rd collects noise/cal samples
- Same statistics as a single frequency experiment on 17 beams

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Limitations of Phased Array Beam Steering

- FOV limited by grating lobe limit $\sim 30^{\circ} 40^{\circ}$
- Antenna gain decreases with steering angle off of boresight
- Antenna works best within $\sim 25^{\circ}$ off of boresight



Sizing an AMISR for ISR

Statistical Accuracy of ISR Measurements:

$$rac{\delta \hat{S}}{S} = rac{1}{\sqrt{K}} \left(1 + rac{1}{S/N}
ight) pprox rac{1}{\sqrt{K}} rac{1}{S/N}$$

Soft Target Radar Equation:

For an active phased array

$$\begin{split} &\frac{S}{N} \propto P_{\mathrm{Tx}} \frac{G}{4\pi R^2} \eta V_s \frac{A_{\mathrm{eff}}}{4\pi R^2} \\ &G \sim \frac{4\pi}{\Omega} \quad V_s \sim R^2 \Omega \\ &\frac{S}{N} \propto P_{\mathrm{Tx}} \frac{1}{4\pi R^2} \frac{4\pi}{\Omega} \eta R^2 \Omega \frac{A_{\mathrm{eff}}}{4\pi R^2} \\ &\frac{S}{N} \propto \frac{1}{4\pi R^2} P_{\mathrm{Tx}} A_{\mathrm{eff}} \eta \end{split}$$

$$egin{aligned} P_{\mathrm{Tx}} &\propto \mathsf{Panels} \ A_{\mathrm{eff}} &\propto \mathsf{Panels} \ rac{S}{N} &\propto \left(\mathsf{Panels}
ight)^2 \ K &\propto \left(\mathsf{Panels}
ight)^4 \end{aligned}$$

1 min integration with 128 panels \Rightarrow 16 min integration with 64 panels

Existing AMSIR Fields of View



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PFISR Field of View at Multiple Altitudes



PFISR Overview

- 128 Panels
- Science operations began in 2007
- 65.13° geographic latitude (a few degrees south of Tromsø)
- 65.39° geomagnetic latitude (Auroral Region)
- Common Tx Frequencies 449.3, 449.6, 449.8 MHz
- Powered by/grid
- Funded by the US National Science Foundation (NSF)
- Operated by SRI International

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Imaging Auroral Structure [Semeter et al. (2009)]



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Vector Electric Fields [Heinselman and Nicolls (2008)]



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MICA Sounding Rocket Support



Lynch et al. (2015) JGR

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Imaging Electrodynamics: 2-D E-Estimation

Assumptions:

- E maps along equipotential field lines
- $\nabla \times \mathbf{E} = \mathbf{0} \Rightarrow \mathbf{E} = -\nabla \Phi$
- E is "smooth" in that it minimizes a curvature measure G



Constrained optimization problem using Lagrange multipliers:

$$\mathcal{L} = \left|\left|\Phi\right|\right|_{G}^{2} + \lambda^{\dagger} \left(\tilde{\mathbf{v}}_{los}^{\prime} - \mathbf{e} - M\Phi\right) + \Omega\left(\left|\left|\mathbf{e}\right|\right|_{C^{-1}}^{2} - N + 1\right)$$

Nicolls et al. (2014) Radio Sci.

Mesospheric Winds and Gravity Waves



Polar Mesospheric Summer Echoes





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Movie

Nicolls et al. (2007) GRL



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PFISR IPY Mode (Continuous Operations)

- 1% duty cycle
- 4 beams, including up-B
- Alternating code (E-region), Long Pulse (F-region)
- 5 min integration and fitting:
 - $N_e, T_e, T_i, V_{\rm LOS}$
 - Vector electric field
 - E-region neutral wind





RISR-N Overview

- 121 Panels
- Science operations began in 2009
- 74.73° geographic latitude (not as high as Svalbard)
- $\bullet~$ 82.77° geomagnetic latitude (deep in the polar cap; highest of any ISR)
- Most common Tx Frequency 442.9 MHz
- Frequency flexibility, 4 MHz frequency allocation
- Powered by diesel generator
- Funded by the US National Science Foundation 115
- Operated by SRI International

Unique Location of Resolute Bay



Figures courtesy Eric Donovan

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Polar Cap Patch Imaging



RISR-N Volumetric Images of Polar Cap Patches

Dahlgren et al., 2012, GRL.

Electrodynamics of Polar Cap Arcs



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e-POP, SuperDARN, and RISR-N Observations

e-POP Upflow



SuperDARN Convection



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Intense Frictional Heating and Ion Anisotropy



F-region anisotropy is common during intense frictional heating!

RISR-C Overview

121 panels (identical to RISR-N)
Science operations began in 2016
Pulses Stimulation PISR-N. Both radars can operate simulationary without interference
Funded by the Canadian Foundation for Innovation (CFI)
Operated by the University of Calgary

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RISR-C and RISR-N Coordinated Observations



RISR "Keograms" (from Rob Gillies)



UMET-14 Overview

o Deployed in August 2014

 Long skinny array ⇒ beam narrow to N-S direction, pare in the direction ± ice.

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 Operated by the Universidad Metropolitana in Puerto Rico (P: Juan Arratia)

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Beam Steering in Plane \perp to **B**



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Spread-F Scatter at 33 cm vs 3 m Scales



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Resolving Space-Time Ambiguity in Spread-F



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Location of Scatter within Airglow Depletions



Future of AMISR Science?



Future of AMISR Science?

