Matthew Thompson

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Cambridge, MA 02142	(561) 628-0338
Education	
Massachusetts Institute of Technology, Cambridge, MA	Candidate for June 2010
Sloan School of Management and School of Engineering	
Master of Science in Engineering and Management, System Design and M	lanagement Fellow
University of Washington, Seattle, WA	2001
Bachelor of Science in Mechanical Engineering, specialty in Thermodynam	mics and Energy
Experience	
Beckman Coulter, Inc., Miami, FL	
Senior Mechanical Engineer	2006 - 2008
• Worked as primary mechanical engineer on team to develop new flow cooling architecture for system, sized fans and ensured proper thermal	
• Led environmental testing, validated prototype temperature control for	optical assembly of analyzer.
• Redesigned plastic injection molded covers (skins) for final production analyzer; increased	
performance and reduced complexity.	•
• Started Engineering Forum, a company-wide discussion group for eng	ineers to share experiences.
Lockheed Martin MS2 (Maritime Sensors and Systems), Riviera Beach, FL	
Mechanical Engineer	2004 - 2006
• Led team that designed maintenance support equipment for DOD under	
Worked with customer to develop requirements, design concepts, and solutions.	
• Optimized propeller design for an autonomous underwater vehicle (AU	
 Performed system-level static and dynamic analyses for performance v 	
verification for large remotely operated vehicle (ROV).	undurion una requirements
 Used simulation tools (MatLab, Simulink, and C++) that identified per 	rformance deficiencies.
Lockheed Martin Space Systems Company, Sunnyvale, CA	
Mechanical Engineer	2001 - 2004
 Designed, built, and delivered precision optical servomechanisms as consupported designs through all phases of review (PDR, CDR, TRR). 	ontributing team member.
	of machanical machanisms
 Analyzed, designed, drafted, procured and tested various components of mechanical mechanisms. Designed mechanical components using solid modeling and CAD software. Analyzed kinematics and 	
• Designed mechanical components using solid modeling and CAD soft dynamics using MatLab and Simulink.	ware. Anaryzed kinematics and
• Worked with consultants and suppliers to design and procure electrom experiments to verify actuator performance after manufacture.	echanical actuators. Conducted
• Defined customer requirements and developed initial design of future mechanisms.	

- Defined customer requirements and developed initial design of future mechanisms.
- Used geometric dimensioning and tolerancing (GD&T) in complex engineering drawings.

Siemens Medical Solutions, Inc., Issaquah, WA

Mechanical Engineer Intern

1999 - 2001

U.S. Government Security Clearance: Inactive TS/SCI based on a SSBI